

Coalgebras in Kleisli Categories

Generic Theory for Traces and Simulations

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- Introduction

- Conventional view
- Coalgebras in Kleisli categories
- Toward a generic theory of traces and simulations
- References

- Coalgebras in Kleisli categories

- Trace semantics via coinduction

- Simulations as lax/oplax coalgebra morphisms

- Conclusions and future work

Theory of coalgebras
 ||
Mathematics for systems' behavior

| coalgebraic notion | interpretation |
|---|-------------------------|
| coalgebra $\begin{array}{c} FX \\ \uparrow \\ X \end{array}$ | system |
| morphism of coalgebras $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & & \uparrow \\ X & \longrightarrow & Y \end{array}$ | behavior preserving map |
| coinduction $\begin{array}{ccc} FX & \dashrightarrow & FZ \\ \uparrow & & \cong \uparrow \text{final} \\ X & \dashrightarrow & Z \\ & \text{beh} & \end{array}$ | beh gives behavior |

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Theory of coalgebras in Sets
 ||
Mathematics for systems' behavior modulo bisimulation

| coalgebraic notion | interpretation in Sets |
|--|---|
| coalgebra $\begin{matrix} FX \\ \uparrow \\ X \end{matrix}$ | system |
| morphism of coalgebras $\begin{matrix} FX & \longrightarrow & FY \\ \uparrow & & \uparrow \\ X & \longrightarrow & Y \end{matrix}$ | behavior preserving map i.e. functional bisimulation |
| coinduction $\begin{matrix} FX & \dashrightarrow & FZ \\ \uparrow & & \cong \uparrow \text{final} \\ X & \dashrightarrow & Z \\ & \text{beh} & \end{matrix}$ | beh gives behavior modulo bisimilarity |

Coalgebras in Kleisli categories

Can the “theory of coalgebra” be more generic?

- Interpretation of coalgebraic notions, in other categories?
- Can we handle semantics other than bisimilarity?

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- Interpretation of coalgebraic notions, in other categories?
- Can we handle semantics other than bisimilarity?

This talk : the theory of coalgebras

- In **Kleisli categories**
- For **trace semantics** and **simulations**

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| | in Sets | in Kleisli category |
|---|-------------------------|---------------------|
| semantics to be captured | bisimilarity | |
| coalgebra $\begin{array}{c} FX \\ \uparrow \\ X \end{array}$ | system | |
| morphism of coalgebras $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & & \uparrow \\ X & \longrightarrow & Y \end{array}$ | functional bisimulation | |
| coinduction $\begin{array}{ccc} FX & \dashrightarrow & FZ \\ \uparrow & & \cong \uparrow \text{final} \\ X & \dashrightarrow & Z \\ & \text{beh} & \end{array}$ | beh gives bisimilarity | |

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| | in Sets | in Kleisli category |
|---|-------------------------------|--|
| semantics to be captured | bisimilarity | trace equivalence |
| coalgebra $\begin{array}{c} FX \\ \uparrow \\ X \end{array}$ | system | system |
| morphism of coalgebras $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & & \uparrow \\ X & \longrightarrow & Y \end{array}$ | functional bisimulation | <p>lax</p> $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & \sqsupseteq & \uparrow \\ X & \longrightarrow & Y \end{array} :$ <p>forward simulation</p> <p>oplax</p> $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & \sqsubseteq & \uparrow \\ X & \longrightarrow & Y \end{array} :$ <p>backward simulation</p> |
| coinduction $\begin{array}{ccc} FX & \dashrightarrow & FZ \\ \uparrow & & \cong \uparrow \text{final} \\ X & \dashrightarrow & Z \\ & \text{beh} & \end{array}$ | beh gives bisimilarity | beh gives trace semantics |

Toward a generic theory of traces and simulations

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In other words: we present

generic theory of traces and simulations

employing theory of coalgebras.

- Generalizes existing work such as [Lynch-Vaandrager'95] on simulations and traces
- Genericity: both **non-determinism** and **probabilism** are handled in a uniform manner
- Results such as: soundness of forward simulation

$$\begin{pmatrix} FX \\ c \uparrow \\ X \end{pmatrix} \sqsubseteq_{\text{fwd}} \begin{pmatrix} FY \\ d \uparrow \\ Y \end{pmatrix} \implies \text{tr}_c \sqsubseteq \text{tr}_d \text{ (trace inclusion)}$$

is via coinduction!

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- Ichiro Hasuo, Bart Jacobs and Ana Sokolova.
Generic Trace Theory.
Proc. CMCS 2006.
- Ichiro Hasuo.
Generic Forward and Backward Simulations.
Proc. CONCUR 2006.

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Example 1

Example 2 (**skip!**)

Kleisli category
 $\mathcal{Kl}(T)$ for monad T

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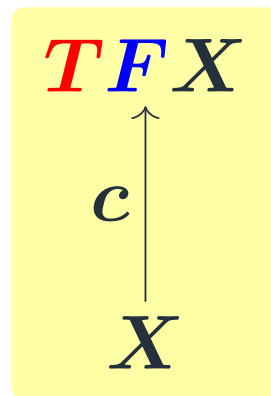
Trace semantics via coinduction

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For trace semantics and simulations, we separate **branching type** and **transition type**.

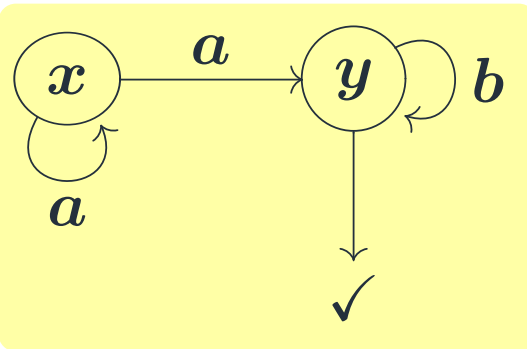
In Sets



- T : a **monad** with suitable order, specifying branching type.
- F : a functor, specifying transition type.
- $FT \Rightarrow TF$, distributive law.

Let's look at examples...

(Non-deterministic) LTS with explicit termination



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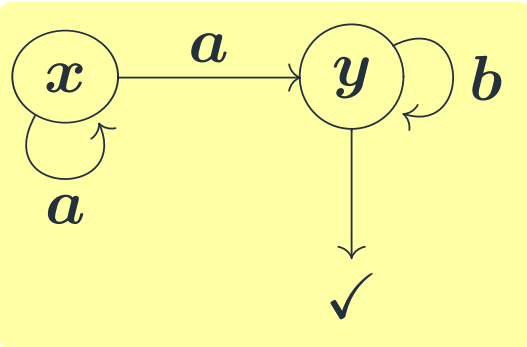
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as a coalgebra

$$\mathcal{P}(1 + \Sigma \times X) \quad \{ (a, x), (a, y) \} \quad \{ (b, y), \checkmark \}$$
$$\uparrow \quad \uparrow \quad \uparrow$$
$$X \quad x \quad y$$

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- Kleisli category $\mathcal{Kl}(T)$ for monad T

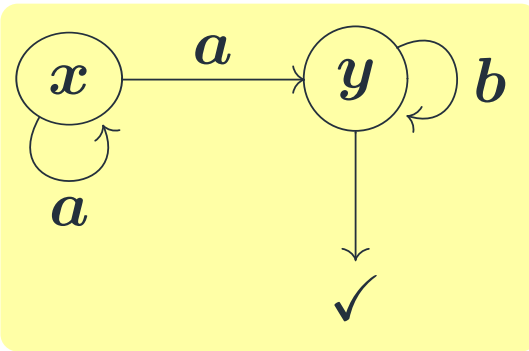
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as a coalgebra

$$\begin{array}{ccc}
 \mathcal{P}(1 + \Sigma \times X) & \{ (a, x), (a, y) \} & \{ (b, y), \checkmark \} \\
 \uparrow & \uparrow & \uparrow \\
 X & x & y
 \end{array}$$

- Branching: **non-deterministic**, modelled by the **powerset monad \mathcal{P}** .

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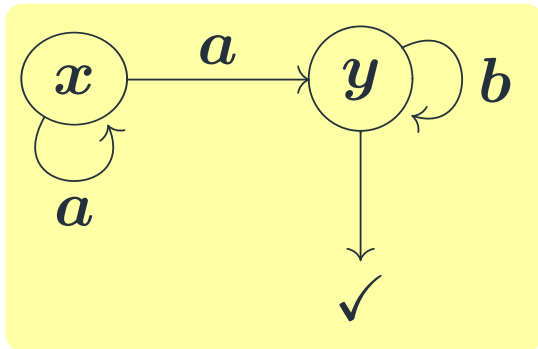
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as a coalgebra

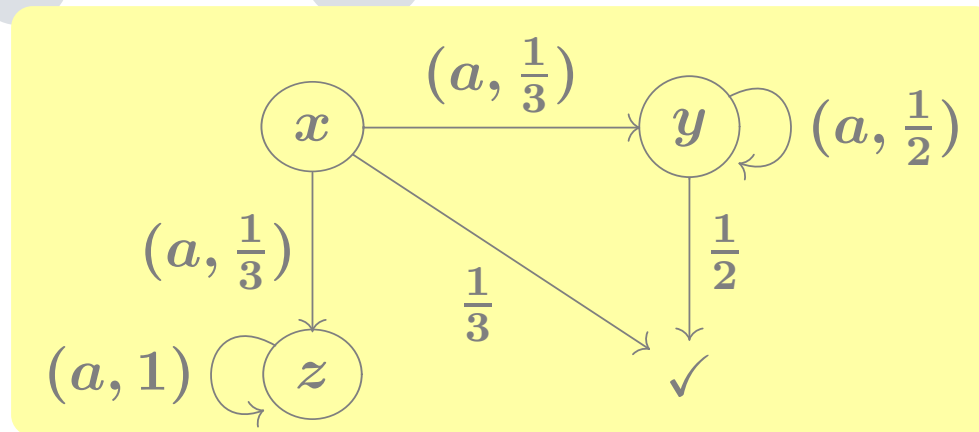
$$\begin{array}{ccc}
 \mathcal{P}(1 + \Sigma \times X) & \{ (a, x), (a, y) \} & \{ (b, y), \checkmark \} \\
 \uparrow & \uparrow & \uparrow \\
 X & x & y
 \end{array}$$

- Branching: **non-deterministic**, modelled by the **powerset monad** \mathcal{P} .
- Transition: either
 - output symbol + next state, or
 - termination \checkmark

modelled by the functor $1 + \Sigma \times _$.

Example 2 (skip!)

Probabilistic LTS with explicit termination



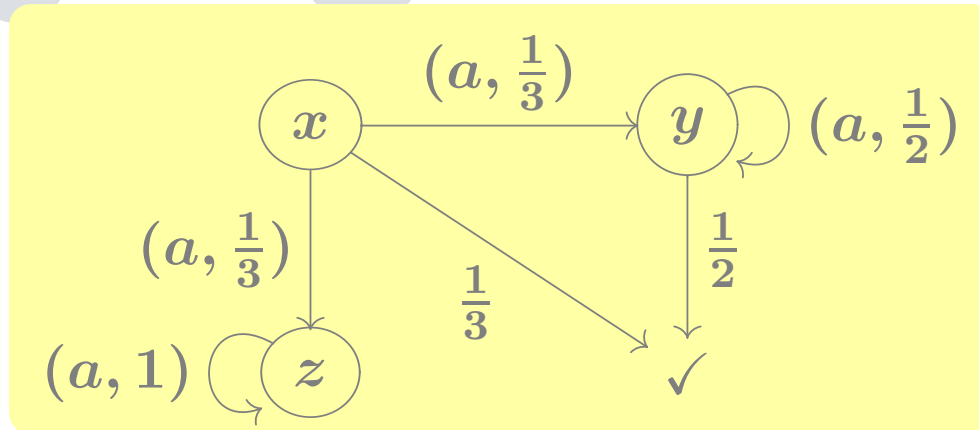
Compared to the previous one,

- The transition type is the same, $\mathbf{1} + \Sigma \times _$.
- Branching: **probabilistic**, modelled by the **subdistribution monad** \mathcal{D}

$$\begin{aligned}\mathcal{D}X &= \{\text{probability (sub)distributions over } X\} \\ &= \{d : X \rightarrow [0, 1] \mid \sum_{x \in X} d(x) \leq 1\}\end{aligned}$$

Example 2 (skip!)

Probabilistic LTS with explicit termination



$$\begin{array}{c}
 \mathcal{D}(\mathbf{1} + \Sigma \times \mathbf{X}) \\
 \uparrow c \\
 \mathbf{X}
 \end{array}
 \quad
 \begin{array}{c}
 \left[\begin{array}{l} (a, z) \mapsto 1/3 \\ (a, y) \mapsto 1/3 \\ \checkmark \mapsto 1/3 \end{array} \right] \\
 \uparrow x \\
 \mathbf{x}
 \end{array}
 \quad
 \begin{array}{c}
 \left[\begin{array}{l} (a, y) \mapsto 1/2 \\ \checkmark \mapsto 1/2 \end{array} \right] \\
 \uparrow y \\
 \mathbf{y}
 \end{array}$$

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Kleisli category $\mathcal{Kl}(T)$ for monad T

- Objects are sets (same as Sets)

$$X \longrightarrow Y \text{ in } \mathcal{Kl}(T)$$

- Arrows: $\underline{\underline{\hspace{1.5cm}}}$

$$X \longrightarrow TY \text{ in Sets}$$

- Arrows in $\mathcal{Kl}(T)$ are functions with **structured output**. [Moggi]
- T 's effect is hidden in $\mathcal{Kl}(T)$.

Kleisli category $\mathcal{Kl}(T)$ for monad T

- Objects are sets (same as **Sets**)

$$X \longrightarrow Y \text{ in } \mathcal{Kl}(T)$$

- Arrows: $\underline{\underline{\hspace{1.5cm}}}$

$$X \longrightarrow TY \text{ in Sets}$$

- Arrows in $\mathcal{Kl}(T)$ are functions with **structured output**. [Moggi]
- T 's effect is hidden in $\mathcal{Kl}(T)$.

Examples

- $X \rightarrow Y$ in $\mathcal{Kl}(\mathcal{P})$

\iff function $X \rightarrow \mathcal{P}Y$ “non-deterministic function”

\iff relation between X and Y

- $X \rightarrow Y$ in $\mathcal{Kl}(\mathcal{D})$

\iff function $X \rightarrow \mathcal{D}Y$ “probabilistic function”

mapping $x \mapsto$ (prob. distribution over Y)

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$$X \longrightarrow Y \text{ in } \mathcal{Kl}(T)$$

hence

$$X \longrightarrow TY \text{ in Sets}$$

$$TFX$$
$$c \uparrow$$
$$X$$

in Sets

=

$$FX$$
$$c \uparrow$$
$$X$$

in $\mathcal{Kl}(T)$

- Branching is “absorbed in the base category $\mathcal{Kl}(T)$ ”
- [Power-Turi, CTCS’99]
- Now a system is an F -coalgebra!
- We can apply theory of coalgebras in $\mathcal{Kl}(T)$:
what is
 - coinduction?
 - morphism of coalgebras?

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Trace semantics via coinduction [CMCS'06]

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Coinduction in $\mathcal{Kl}(T)$:

system

$$\begin{array}{ccc} FX & \dashrightarrow & FZ \\ \uparrow c & & \uparrow \cong \\ X & \dashrightarrow & Z \end{array}$$

final coalg.

Questions

- What is the final coalgebra in $\mathcal{Kl}(T)$?
- What is the unique map via coinduction?

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Coinduction in $\mathcal{Kl}(T)$:



Questions

- What is the final coalgebra in $\mathcal{Kl}(T)$?

Answer [CMCS'06] Initial F -algebra in Sets!

- What is the unique map via coinduction?

Answer [CMCS'06] Trace semantics!

This holds for

- a wide variety of functors F and
- monads T with a suitable order structure, such as \mathcal{P} and \mathcal{D} .

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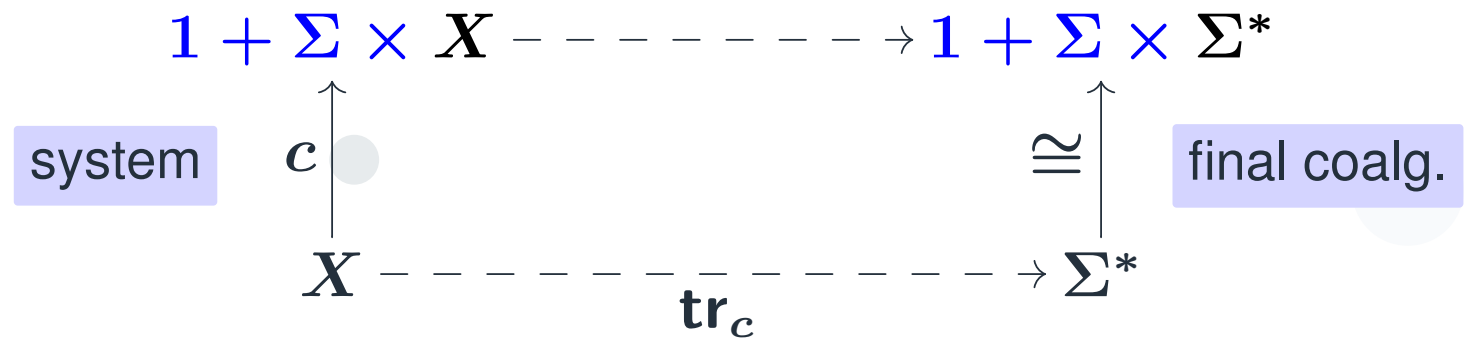
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Coinduction in $\mathcal{Kl}(\mathcal{P})$:



The commutation amounts to the standard (co)inductive definition of traces:

- $\langle \rangle \in \text{tr}_c(x)$ iff $\checkmark \in c(x)$
- $a \cdot s \in \text{tr}_c(x)$ iff $\exists x' \in X. (a, x') \in c(x) \wedge s \in \text{tr}_c(x')$

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Simulations as lax/oplax coalgebra morphisms [CONCUR'06]

Explicit start states

It is convenient to have start states explicit.

Now a **system** is:

$$\text{in } \mathcal{Kl}(T) \quad \begin{array}{c} FX \\ \uparrow c \\ X \\ \uparrow s \\ 1 \end{array}$$

, that is,

$$\text{in Sets} \quad \left(\begin{array}{c} TX \\ \uparrow s \\ 1 \end{array}, \begin{array}{c} TFX \\ \uparrow c \\ X \end{array} \right)$$

Examples

■ $\begin{array}{c} \mathcal{P}X \\ \uparrow s \\ 1 \end{array}$: set of possible start states

■ $\begin{array}{c} \mathcal{D}X \\ \uparrow s \\ 1 \end{array}$: probability distribution over possible start states

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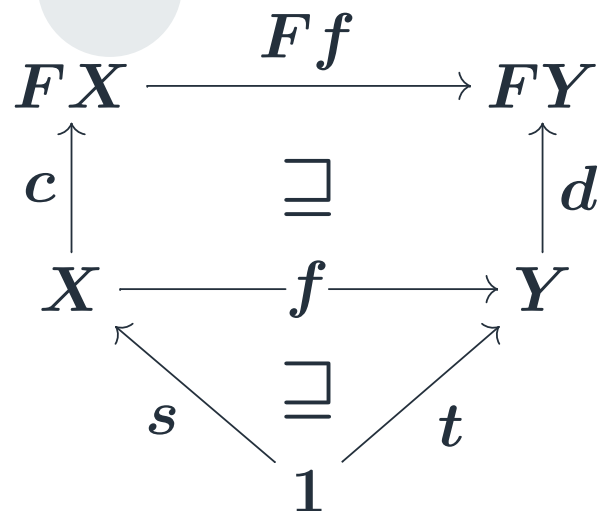
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Forward simulations

are identified as **lax morphisms of coalgebras!**

In $\mathcal{Kl}(T)$



- $d \circ f \sqsubseteq Ff \circ c$,
as functions $X \Rightarrow TFY$
- (s, c) simulates (t, d)
- Yields trace inclusion:
 $\mathbf{tr}_{(t,d)} \sqsubseteq \mathbf{tr}_{(s,c)}$

Let's take a closer look...

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Forward simulations

In $\mathcal{Kl}(\mathcal{P})$:

Note an arrow is a relation

$$\begin{array}{ccc} 1 + \Sigma \times X & \longrightarrow & 1 + \Sigma \times Y \\ \uparrow c & \cong & \uparrow d \\ X & \longrightarrow & Y \end{array}$$



Forward simulations

In $\mathcal{Kl}(\mathcal{P})$:

Note an arrow is a relation

$$x \xrightarrow{a} x'$$

$$x \xrightarrow{a} x' \\ \vdots \\ y'$$

$$\begin{array}{ccc} 1 + \Sigma \times X & \longrightarrow & 1 + \Sigma \times Y \\ \uparrow c & \cong & \uparrow d \\ X & \longrightarrow & Y \end{array}$$

$$x$$

Forward simulations

In $\mathcal{Kl}(\mathcal{P})$:

Note an arrow is a relation

$$\begin{array}{ccc} 1 + \Sigma \times X & \longrightarrow & 1 + \Sigma \times Y \\ \uparrow c & \cong & \uparrow d \\ X & \longrightarrow & Y \end{array}$$

$$\begin{array}{c} x \\ \vdots \\ y \end{array} \xrightarrow{a} y'$$

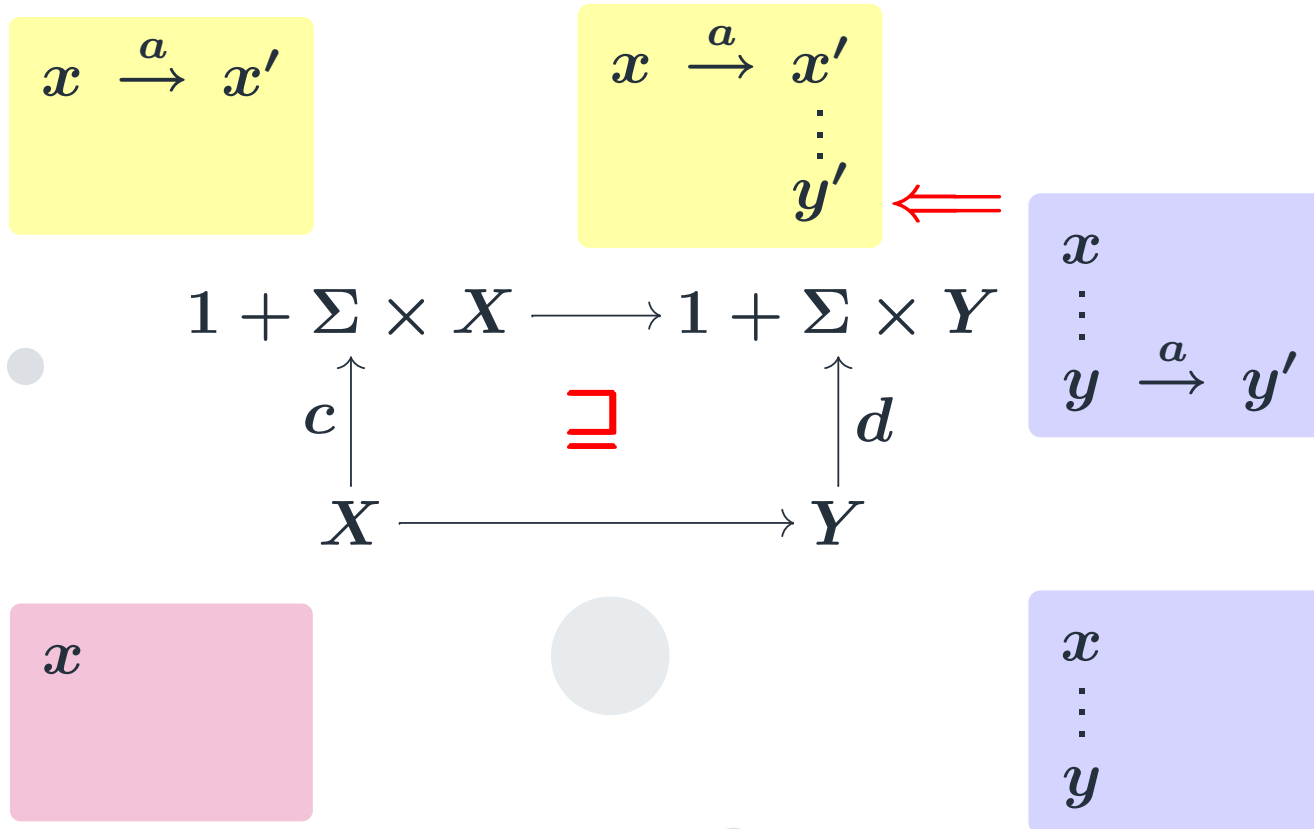
$$x$$

$$\begin{array}{c} x \\ \vdots \\ y \end{array}$$

Forward simulations

In $\mathcal{Kl}(\mathcal{P})$:

Note an arrow is a relation



Hence

$$\begin{array}{c} x \\ \vdots \\ y \end{array} \xrightarrow{a} y'$$

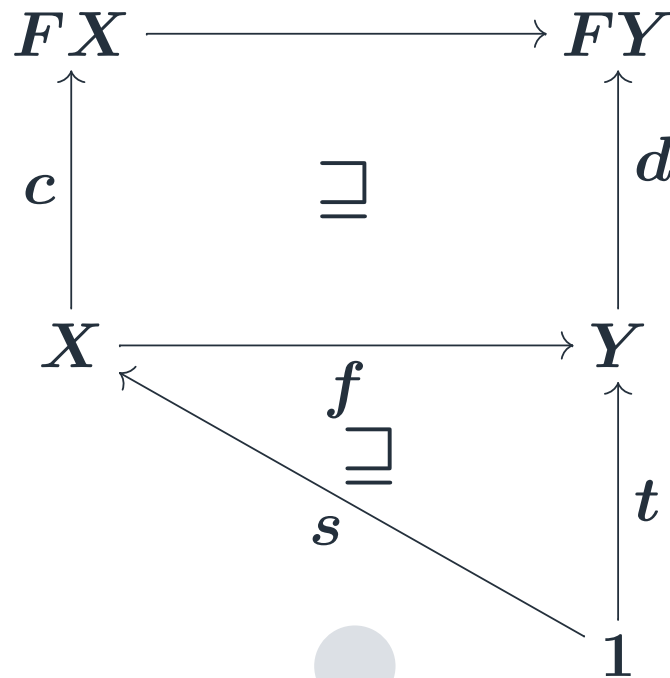
implies

$$\begin{array}{c} x \xrightarrow{a} \exists x' \\ \vdots \\ y \xrightarrow{a} y' \end{array}$$

Simulations yield trace inclusion (soundness)

Theorem

$$(t, d) \sqsubseteq_{\text{fwd}} (s, c) \implies \text{tr}_{(t,d)} \sqsubseteq \text{tr}_{(s,c)} .$$



Simulations yield trace inclusion (soundness)

Theorem

$$(t, d) \sqsubseteq_{\text{fwd}} (s, c) \implies \text{tr}_{(t,d)} \sqsubseteq \text{tr}_{(s,c)} .$$

FY



d

Y



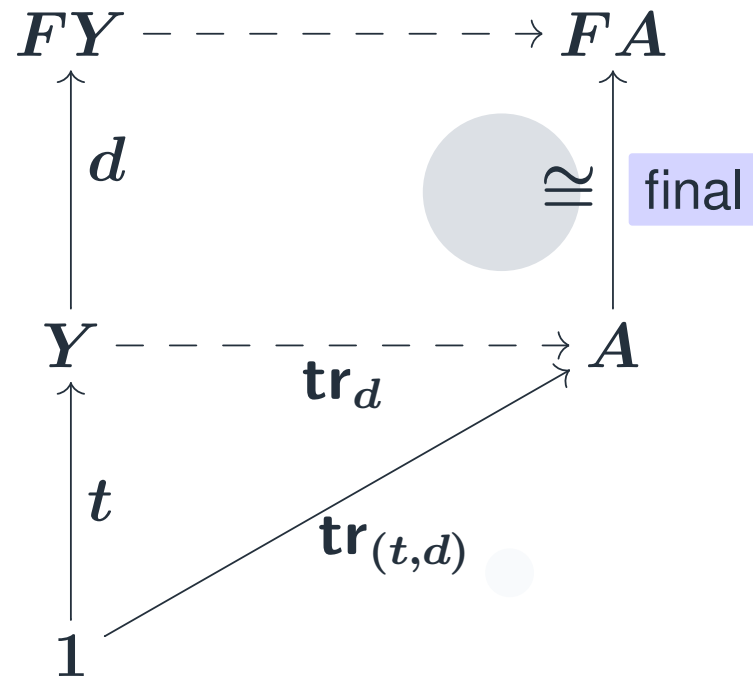
t

1

Simulations yield trace inclusion (soundness)

Theorem

$$(t, d) \sqsubseteq_{\text{fwd}} (s, c) \implies \text{tr}_{(t,d)} \sqsubseteq \text{tr}_{(s,c)} .$$

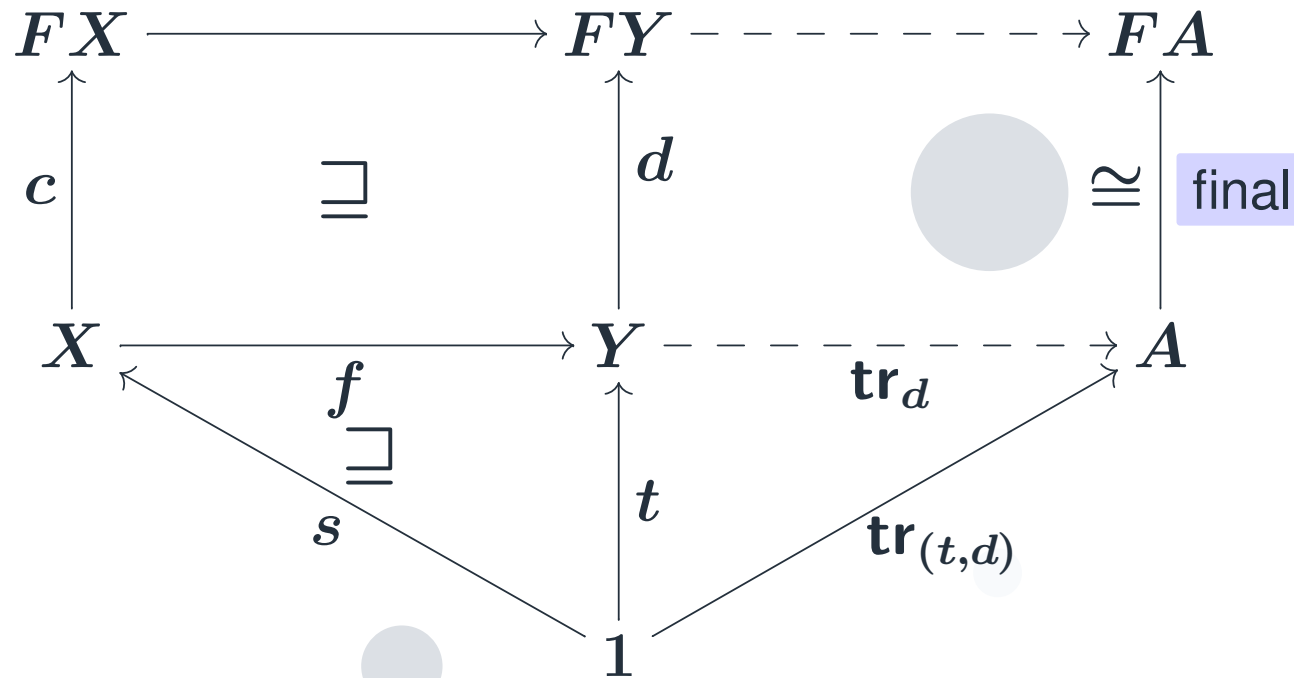


$$\text{tr}_{(t,d)} = \text{tr}_d \circ t$$

Simulations yield trace inclusion (soundness)

Theorem

$$(t, d) \sqsubseteq_{\text{fwd}} (s, c) \implies \text{tr}_{(t,d)} \sqsubseteq \text{tr}_{(s,c)} .$$

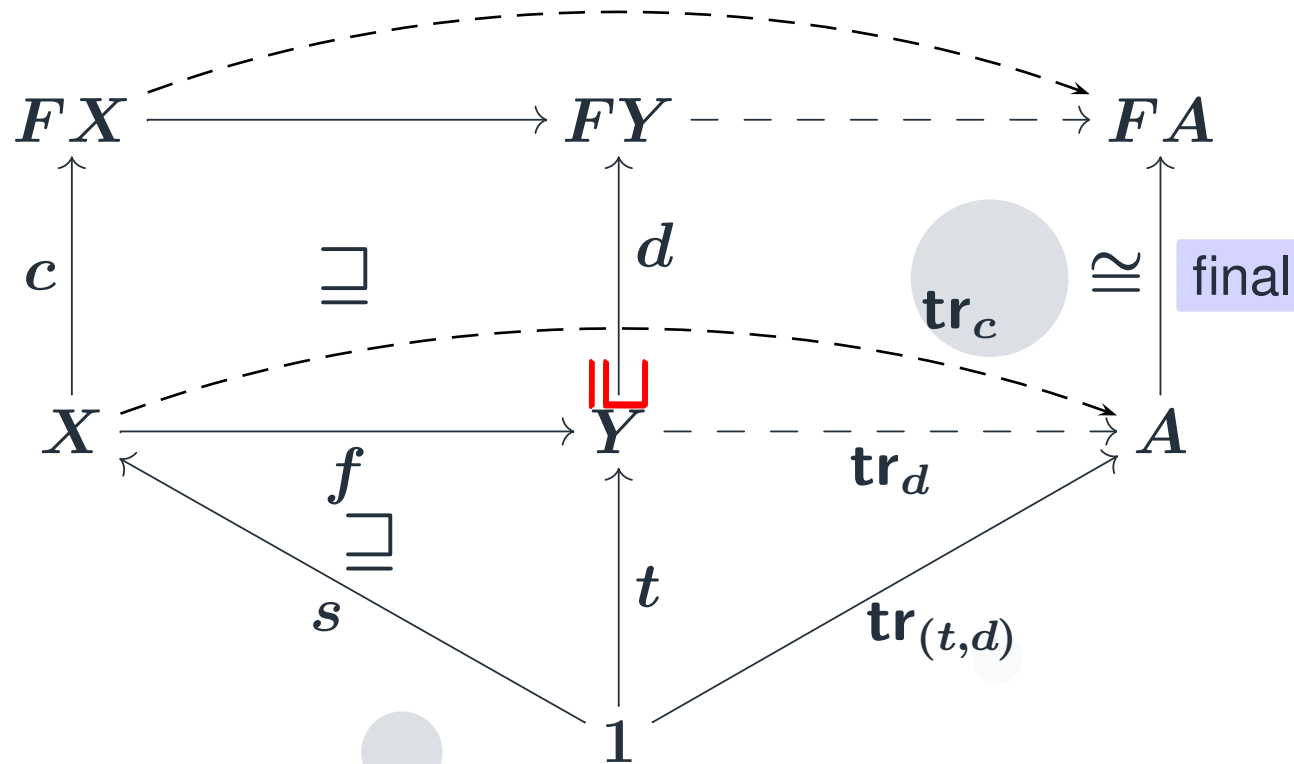


$$\text{tr}_{(t,d)} = \text{tr}_d \circ t \sqsubseteq \text{tr}_d \circ f \circ s$$

Simulations yield trace inclusion (soundness)

Theorem

$$(t, d) \sqsubseteq_{\text{fwd}} (s, c) \implies \text{tr}_{(t,d)} \sqsubseteq \text{tr}_{(s,c)} .$$



$$\text{tr}_{(t,d)} = \text{tr}_d \circ t \sqsubseteq \text{tr}_d \circ f \circ s \sqsubseteq \text{tr}_c \circ s = \text{tr}_{(s,c)} .$$

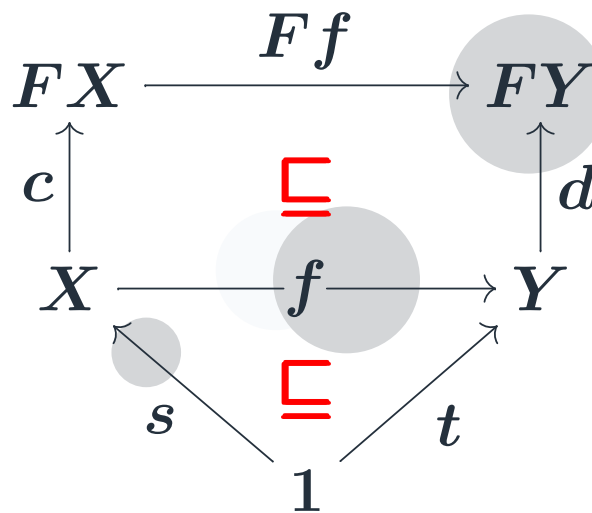
■ **Proposition** [Fiore'96/Plotkin]

Trace map is the biggest lax coalgebra morphism.

Backward simulations

Similarly, backward simulations
as **oplax morphisms of coalgebras**:

In $\mathcal{Kl}(T)$



- \sqsubseteq instead of \sqsupseteq

- (t, d) simulates (s, c)

- For example:

$$x \xrightarrow{a} x'$$

$$\vdots$$

$$y'$$

implies

$$x \xrightarrow{a} x'$$

$$\vdots$$

$$\exists y \xrightarrow{a} y'$$

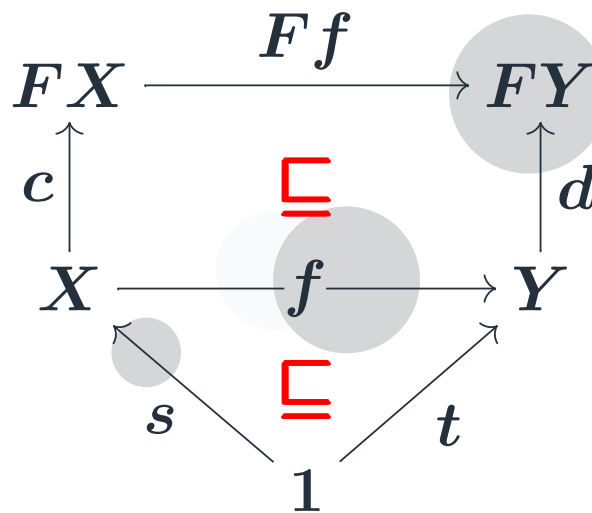
- Again yields trace inclusion:

$$\mathbf{tr}_{(s,c)} \sqsubseteq \mathbf{tr}_{(t,d)}$$

Backward simulations

Similarly, backward simulations
as **oplax morphisms of coalgebras**:

In $\mathcal{Kl}(T)$



- \sqsubseteq instead of \sqsupseteq

- (t, d) simulates (s, c)

- For example:

$$\begin{array}{c} x \xrightarrow{a} x' \\ \vdots \\ y' \end{array}$$

implies

$$\begin{array}{c} x \xrightarrow{a} x' \\ \vdots \\ \exists y \xrightarrow{a} y' \end{array}$$

- Again yields trace inclusion:

$$\mathbf{tr}_{(s,c)} \sqsubseteq \mathbf{tr}_{(t,d)}$$

Also: **completeness result** for hybrid “backward-forward” simulations.

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- **In summary** : in Kleisli categories,
 - trace semantics via coinduction
 - forward/backward simulations as lax/oplax coalgebra morphisms
 - soundness/completeness of simulations
- **Genericity** : valid for
 - monad T , type of branching : \mathcal{P} (non-determinism) or \mathcal{D} (probabilism)
 - functor F , type of transition : shapely (i.e. almost polynomial)

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- **Practical implication** : for a given type of systems,
 - definition of forward/backward simulations by instantiating coalgebraic definition,

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- **Practical implication** : for a given type of systems,
 - definition of forward/backward simulations by instantiating coalgebraic definition,
 - for which soundness/completeness comes **for free**.
 - Cf. In formal verification, finding a simulation is a common technique to establish trace inclusion.

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- **Practical implication** : for a given type of systems,
 - definition of forward/backward simulations by instantiating coalgebraic definition,
 - for which soundness/completeness comes **for free**.
 - Cf. In formal verification, finding a simulation is a common technique to establish trace inclusion.
 - Especially, a gap from non-deterministic systems to its probabilistic version is trivial.
 - E.g. Probabilistic version of “anonymity simulation” [Kawabe et al '06] (ongoing work)

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| | in Sets | in Kleisli category |
|---|-------------------------------|--|
| semantics to be captured | bisimilarity | trace equivalence |
| coalgebra $\begin{array}{c} FX \\ \uparrow \\ X \end{array}$ | system | system |
| morphism of coalgebras $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & & \uparrow \\ X & \longrightarrow & Y \end{array}$ | functional bisimulation | <p>lax</p> $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & \sqsupseteq & \uparrow \\ X & \longrightarrow & Y \end{array} :$ <p>forward simulation</p> <p>oplax</p> $\begin{array}{ccc} FX & \longrightarrow & FY \\ \uparrow & \sqsubseteq & \uparrow \\ X & \longrightarrow & Y \end{array} :$ <p>backward simulation</p> |
| coinduction $\begin{array}{ccc} FX & \dashrightarrow & FZ \\ \uparrow & & \cong \uparrow \text{final} \\ X & \dashrightarrow & Z \\ \text{beh} & & \end{array}$ | beh gives bisimilarity | beh gives trace semantics |

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- Generic theory of traces and simulations
- Soundness/completeness for free

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Future work

- Infinite traces [Jacobs, CMCS'04]
- Internal actions
- Linear-time logic using $\mathcal{X} \leftrightarrow \mathcal{A}^{\text{op}}$
(Ongoing work with A. Kurz)
- Process calculi and compositionality (bialgebraic view?)
- Semantics between trace sem. and bisimilarity, in the van Glabbeek spectrum (Cf. B. Klin)
- As an instance of the bigger “systems and tests” view, via

$$\mathcal{X} \leftrightarrow \mathcal{A}^{\text{op}}$$