

Climbing up a ladder:
an *evitcudnioc* approach to
contextual refinement

Koko Muroya
(RIMS, Kyoto University)

Climbing up a ladder:
an *evitcudnioc* (reverse coinductive)
approach to
contextual refinement

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Contextual refinement

- “Can the (observable) result of t be reproduced by u ?”

- variations:

- $t \leq_{\downarrow} u \stackrel{\Delta}{\iff} \forall C. C[t] \downarrow \implies C[u] \downarrow$

- $t \leq_V u \stackrel{\Delta}{\iff} \forall C, v. C[t] \rightarrow^* v \implies C[u] \rightarrow^* v$

- $t \leq_{\nabla}^{\geq} u \stackrel{\Delta}{\iff} \forall C, v. C[t] \rightarrow^k v \implies C[u] \rightarrow^m v \wedge k \geq m$

- Sands' *improvement*

- $t \leq_V^Q u \stackrel{\Delta}{\iff} \forall C, v. C[t] \rightarrow^k v \implies C[u] \rightarrow^m v \wedge k Q m$

- for a preorder $Q \subseteq \mathbb{N} \times \mathbb{N}$, e.g. $\mathbb{N} \times \mathbb{N}, \geq, \dots$

Abransky's applicative bisimilarity

- *the* coinductive proof methodology for contextual equivalence
 - (1) characterise observational equivalence as “bisimilarity”
 - (2) take a candidate \bowtie of contextual equivalence
 - (3) prove that \bowtie is a “bisimulation”
 - (4) prove that \bowtie is a congruence, typically by Howe's method

- (1) for all \bowtie , (2-4) for each \bowtie

Abramsky's applicative bisimilarity

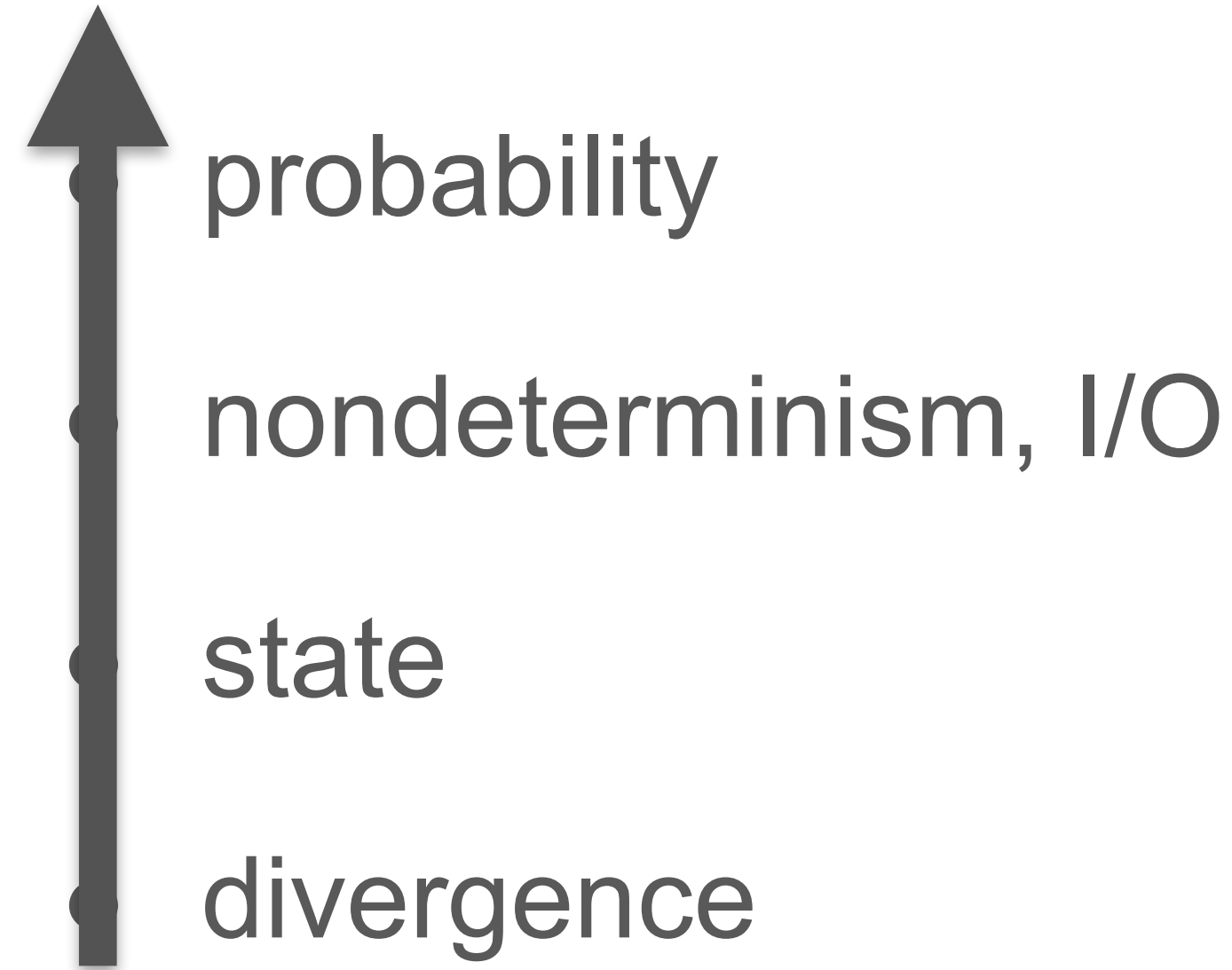
- climbing up a rope of advanced features
 - from applicative to environmental bisimilarity [Koutavas+ '11]
 - Howe's method, once for all effects [Dal Lago+ '17]

A new *evitcudnioc* approach

- yet another coinductive proof methodology for contextual refinement
 - (1) characterise observational refinement as “trace inclusion” of automata
 - (2) design a sound “simulation” notion
 - (3) take a candidate \triangleleft of contextual refinement
 - (4) take the contextual closure $\overline{\triangleleft}$ (i.e. $\forall C . C[\vec{t}] \overline{\triangleleft} C[\vec{u}] \iff \forall i . t_i \triangleleft u_i$)
 - (5) prove that $\overline{\triangleleft}$ is a “simulation”
- (1-2) for all \triangleleft , (3-5) for each \triangleleft

A new *evitcudnioc* approach

- climbing up a ladder



The left bar:
(2) “simulation” notions

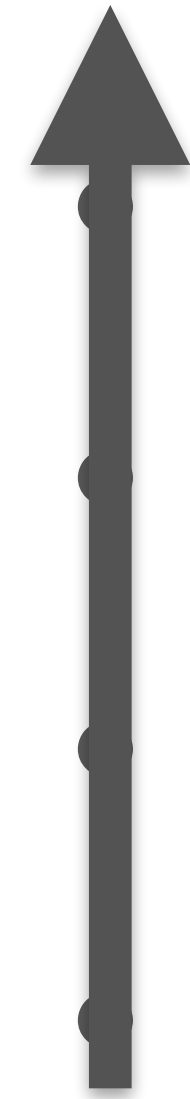
forgetting how each \rightarrow is
defined

The right bar:
(5) “simulation” proofs

examining how each \rightarrow is
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A new *evitcudnioc* approach

- climbing up a ladder



probability

nondeterminism, I/O

state

divergence



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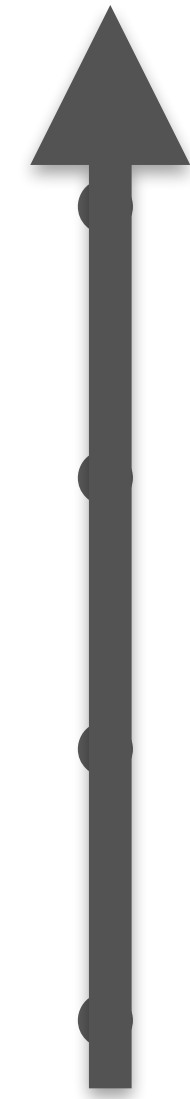


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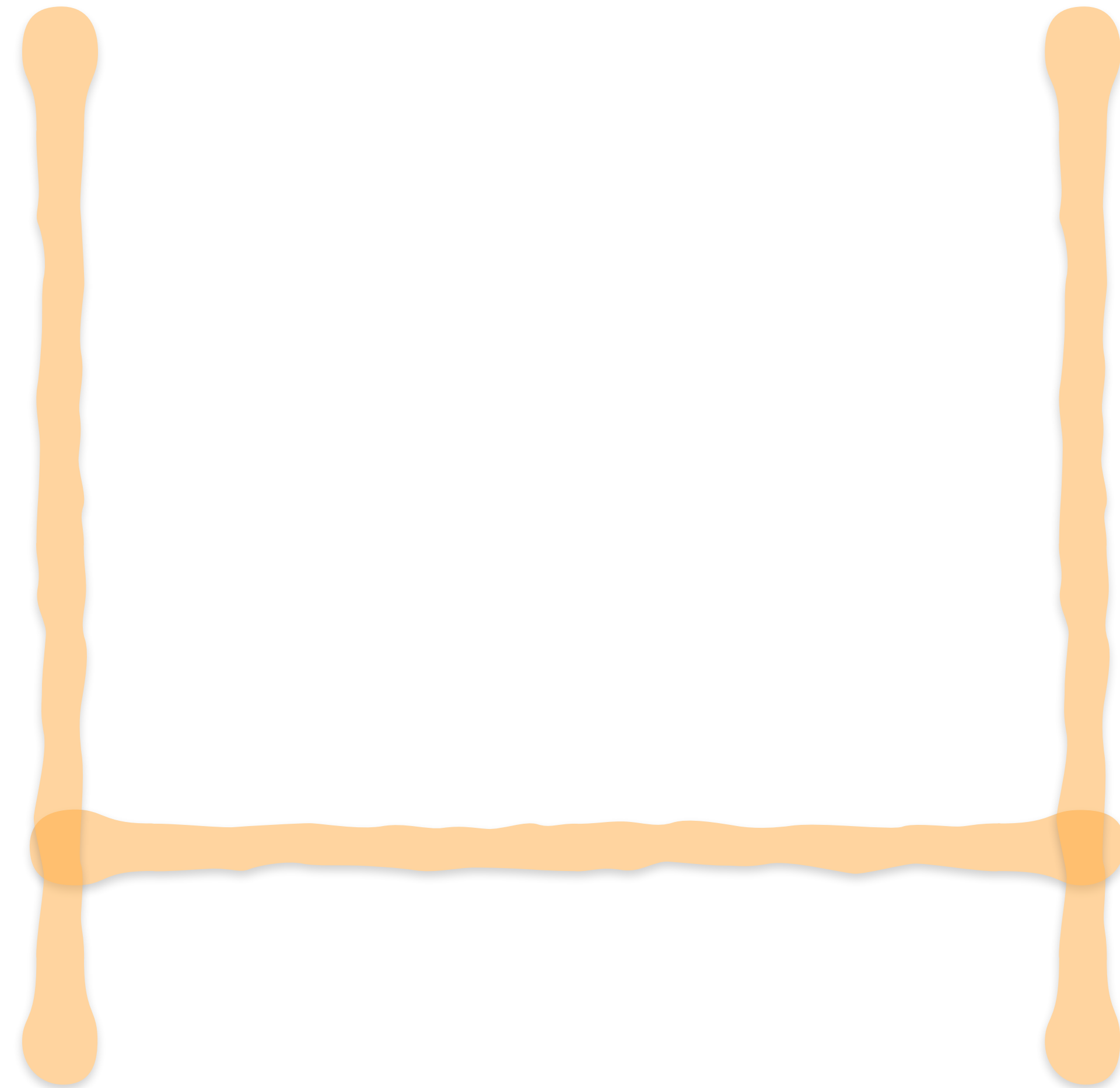


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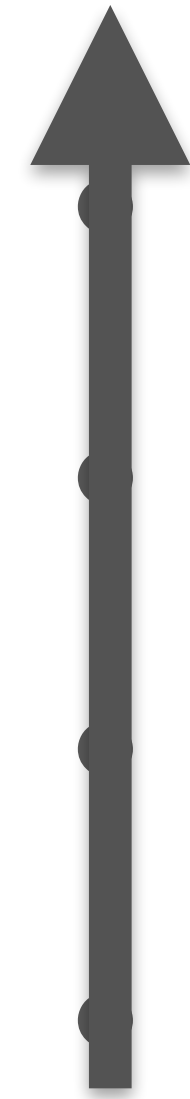
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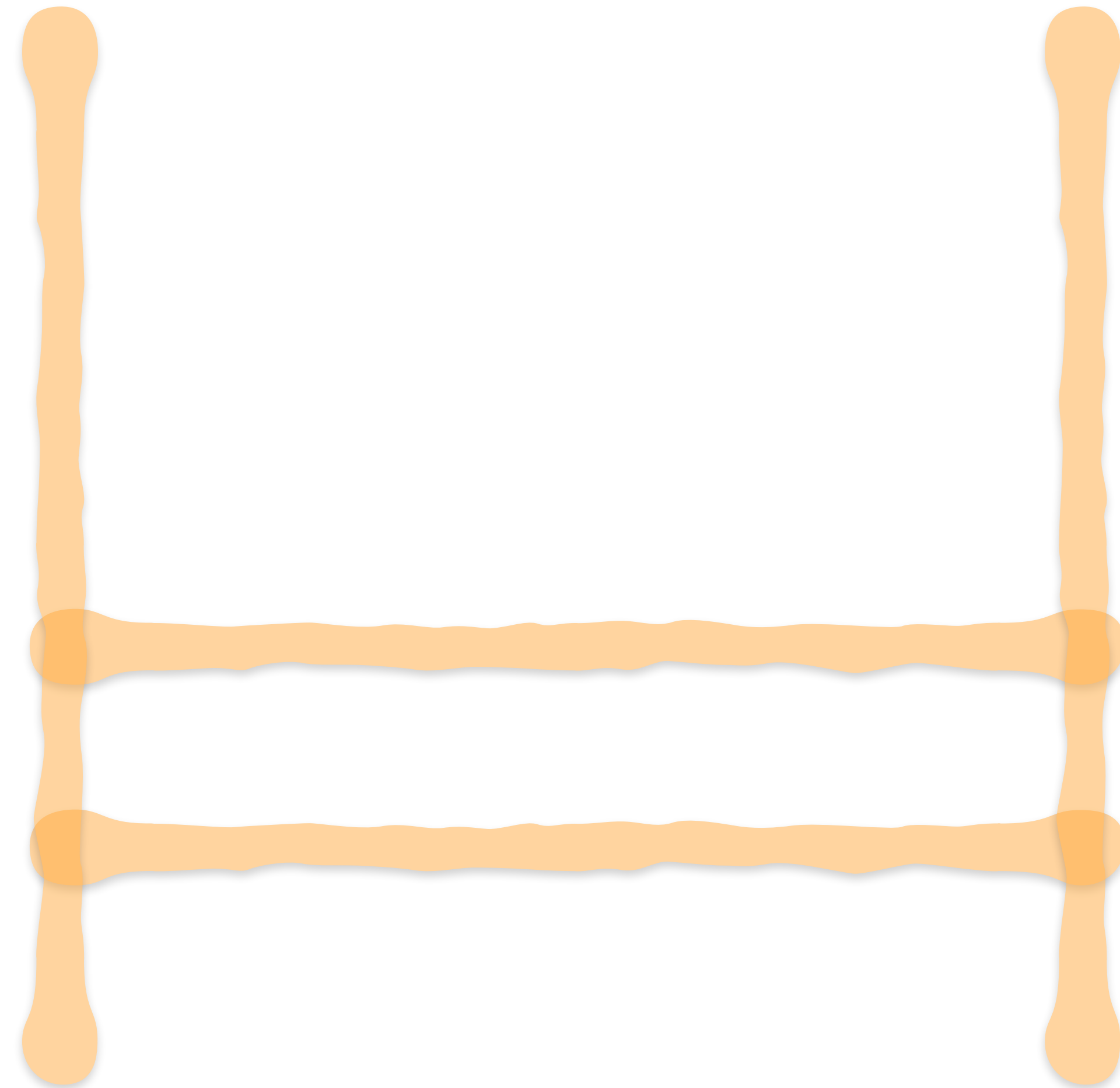


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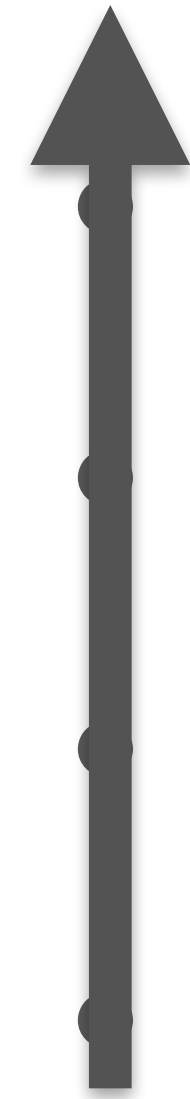
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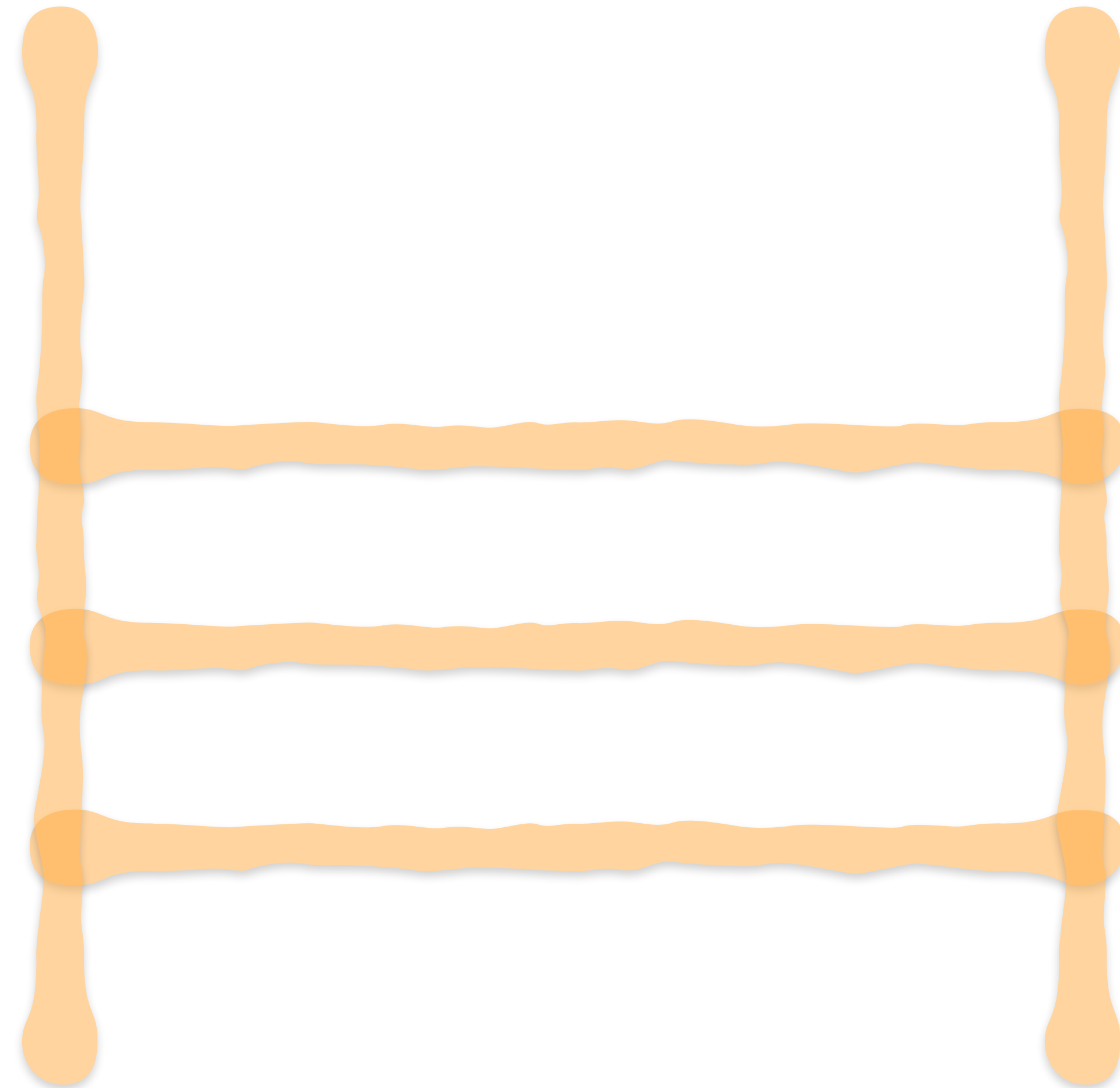


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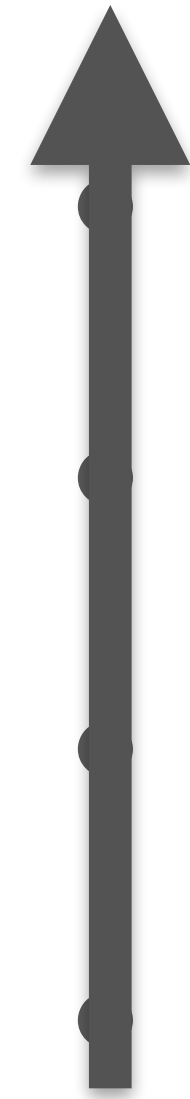


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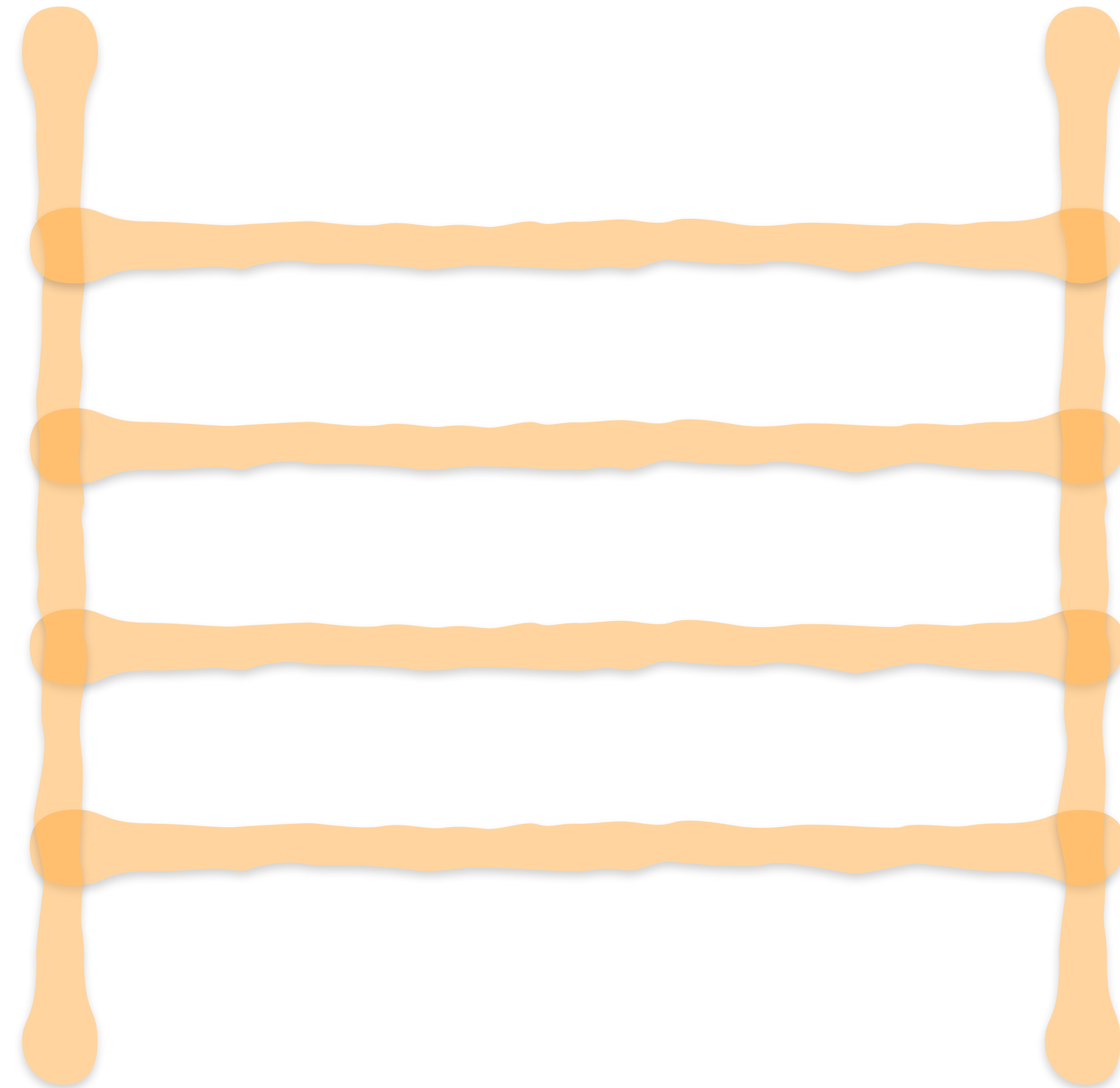


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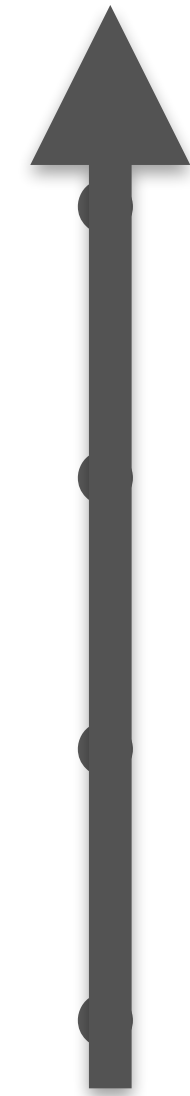


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counting simulation & graphical local reasoning (2020)

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Counting simulation

- (2) design a sound “simulation” notion (for observational refinement)

- target: \leq_{\downarrow}^Q for a preorder $Q \subseteq \mathbb{N} \times \mathbb{N}$

- $t \leq_{\downarrow}^Q u \stackrel{\Delta}{\iff} \forall C. C[t] \downarrow^k \implies C[u] \downarrow^m \wedge k Q m$

- Q introduced for a technical reason

- (will come back to this point)

Counting simulation

- (2) design a sound “simulation” notion (for observational refinement)

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- $t \leq_{\downarrow}^Q u \stackrel{\Delta}{\iff} \forall C. C[t] \downarrow^k \implies C[u] \downarrow^m \wedge k Q m$

- **Def.** (counting simulation)

$$R \text{ is a } Q\text{-counting simulation} \stackrel{\Delta}{\iff} \begin{array}{ccc} s \rightarrow s' \xrightarrow{k} s'' & & s \in F \\ R: & \vdots R & R: \\ t \xrightarrow{m} t' & & t \in F \end{array}$$

- **Prop.** (soundness) If $\overline{\triangleleft}$ is a Q -counting simulation, then $\triangleleft \subseteq \leq_{\downarrow}^Q$.

- only for deterministic \rightarrow , to prove by induction

Detour: counting simulation up-to

- namely, for *dependency* of contextual refinements
- Case 1. up to structural congruences
 - e.g. $(\text{let } x = t \text{ in } u) \simeq u$ if $x \notin \text{FV}(u)$
 - instead of working with equivalence classes of terms wrt. structural congruences

Detour: counting simulation up-to

- namely, for *dependency* of contextual refinements
- Case 2. up to auxiliary contextual equivalences
 - e.g. $n \simeq m$ for $n, m \in \mathbb{N}$, in the absence of `if`
 - **Q.** Is the call-by-value beta-law $(\lambda x . t) v \triangleleft_{\beta} t[v/x]$ preserved by `stat`?
 - `stat` inspects memory usage
 - **A1.** No, in the presence of `if`.
 - Try It Online: <https://bit.ly/3TqnGOW>

Detour: counting simulation up-to

- namely, for *dependency* of contextual refinements
- Case 2. up to auxiliary contextual equivalences
 - e.g. $n \simeq m$ for $n, m \in \mathbb{N}$, in the absence of `if`
 - **Q.** Is the call-by-value beta-law $(\lambda x . t) v \triangleleft_{\beta} t[v/x]$ preserved by `stat`?
 - `stat` inspects memory usage
 - **A2.** Yes, in the absence of `if`.
 - The beta-law would depend on the auxiliary law $n \simeq m$.

Detour: counting simulation up-to

- (2) design a sound “simulation” notion (for observational refinement)

- target: \leq_{\downarrow}^Q for a preorder $Q \subseteq \mathbb{N} \times \mathbb{N}$

- $t \leq_{\downarrow}^Q u \stackrel{\Delta}{\iff} \forall C. C[t] \downarrow^k \implies C[u] \downarrow^m \wedge k Q m$

- **Def.** (counting simulation up-to)

$$R \text{ is a } Q\text{-counting simulation up to } (Q_1, Q_2) \stackrel{\Delta}{\iff} R : \begin{array}{c} s \rightarrow s' \xrightarrow{k} s'' \\ \vdots \quad \quad \quad \cdot \quad \cdot \quad \cdot \\ t \xrightarrow{m} t' \end{array} \begin{array}{c} \cdot \quad \cdot \quad \cdot \\ \cdot \quad \cdot \quad \cdot \\ \cdot \quad \cdot \quad \cdot \end{array} \begin{array}{c} \cdot \quad \cdot \quad \cdot \\ \cdot \quad \cdot \quad \cdot \\ \cdot \quad \cdot \quad \cdot \end{array} \begin{array}{c} \cdot \quad \cdot \quad \cdot \\ \cdot \quad \cdot \quad \cdot \\ \cdot \quad \cdot \quad \cdot \end{array} \begin{array}{c} s \in F \\ \\ t \in F \end{array}$$

- **Prop.** (soundness) If $\overline{\triangleleft}$ is a Q -counting simulation up to $(\overset{\sim}{\downarrow}^{Q_1}, \overset{\sim}{\downarrow}^{Q_2})$, then $\triangleleft \subseteq \leq_{\downarrow}^Q$.

- only for deterministic \rightarrow and *reasonable* (Q, Q_1, Q_2) , in particular $Q_1 \subseteq \geq$

Counting simulation

- (2) design a sound “simulation” notion (for observational refinement)

- target: \leq_{\downarrow}^Q for a preorder $Q \subseteq \mathbb{N} \times \mathbb{N}$

- $t \leq_{\downarrow}^Q u \stackrel{\Delta}{\iff} \forall C. C[t] \downarrow^k \implies C[u] \downarrow^m \wedge k Q m$

- **Def.** (counting simulation)

$$R \text{ is a } Q\text{-counting simulation} \stackrel{\Delta}{\iff} R \vdash \begin{array}{l} s \rightarrow s' \xrightarrow{k} s'' \quad s \in F \\ \vdots R \\ t \xrightarrow{m} t' \quad t \in F \end{array}$$

- **Prop.** (soundness) If $\overline{\triangleleft}$ is a Q -counting simulation, then $\triangleleft \subseteq \leq_{\downarrow}^Q$.

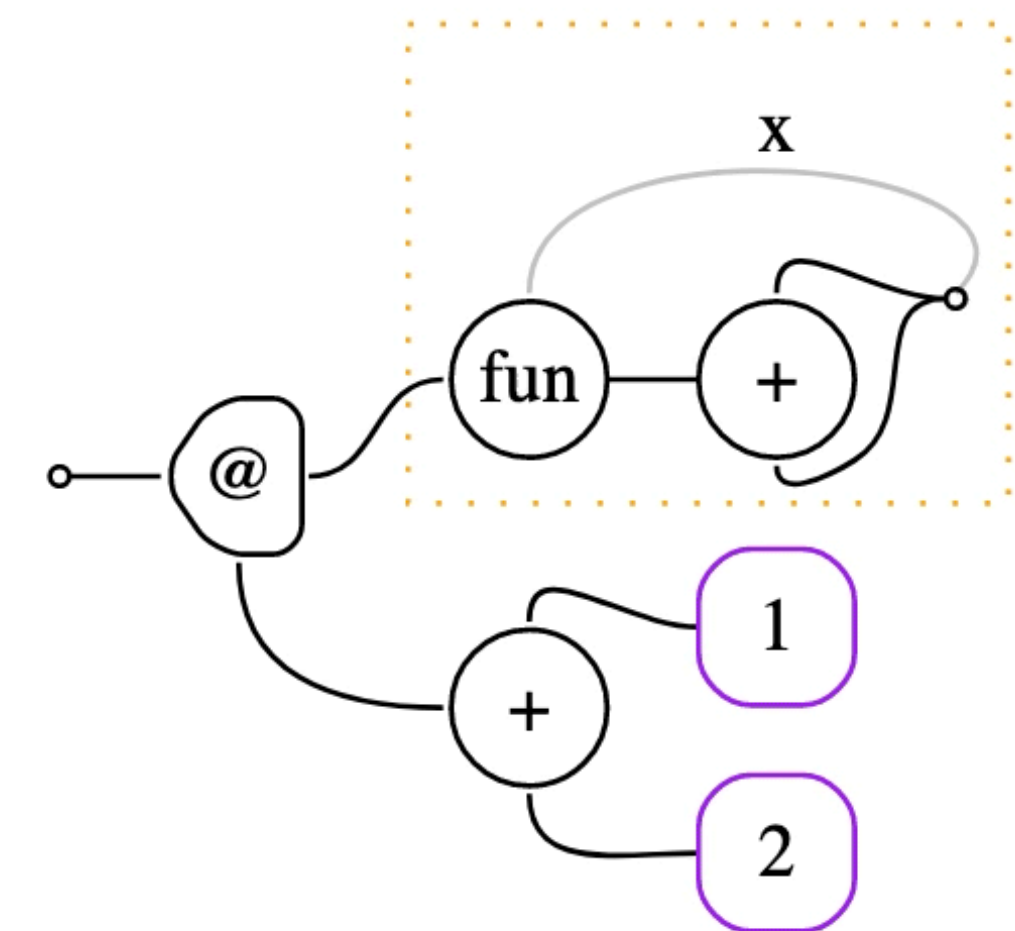
- only for deterministic \rightarrow , to prove by induction
- **Q.** Can we extend this result to nondeterministic \rightarrow ?

Graphical local reasoning for counting simulation

- (5) prove that $\overleftarrow{\Delta}$ is a Q -simulation

$$\begin{array}{l} C[\vec{t}] \rightarrow s \xrightarrow{k} C'[\vec{t}'] \\ \overleftarrow{\Delta}: \quad \quad \quad \vdots \overleftarrow{\Delta} \\ C[\vec{u}] \xrightarrow{m} C'[\vec{u}'] \end{array}$$

- now examining how each \rightarrow is defined
 - namely: *token-guided graph rewriting*
 - A token, moving around a graph, substitutes evaluation contexts.

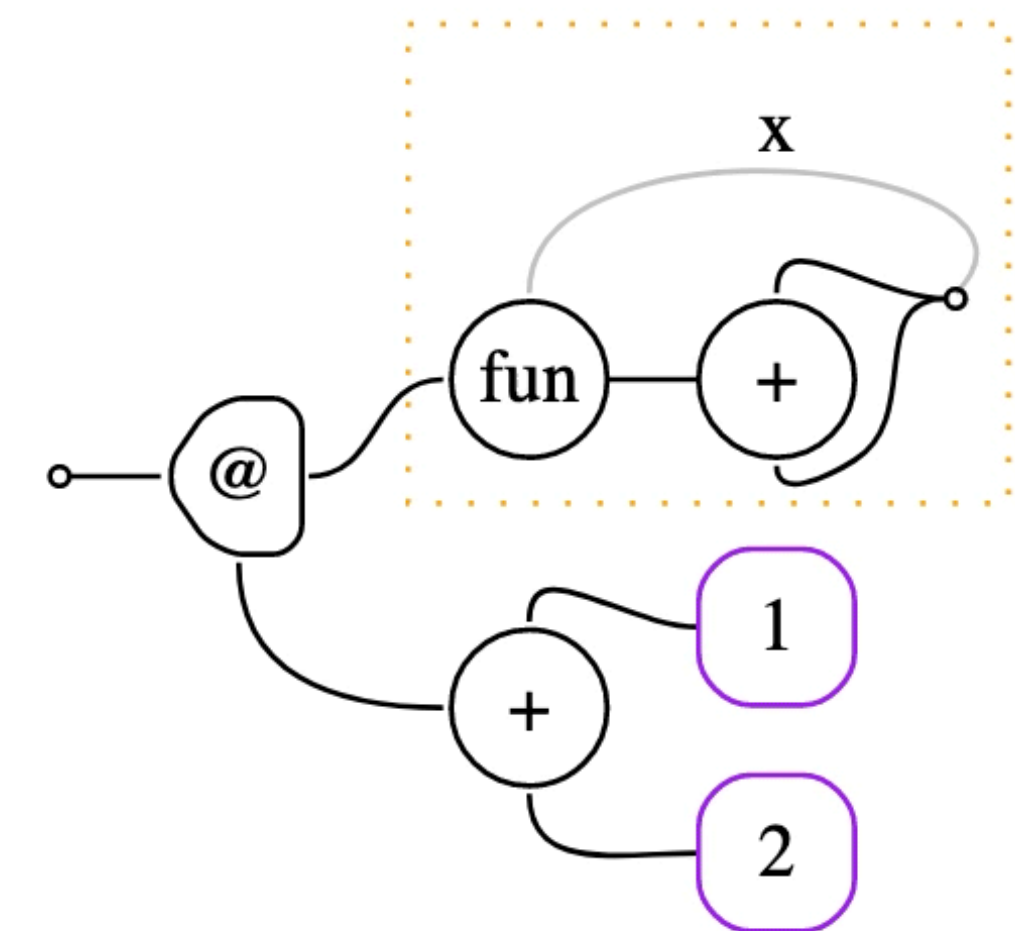


Graphical local reasoning for counting simulation

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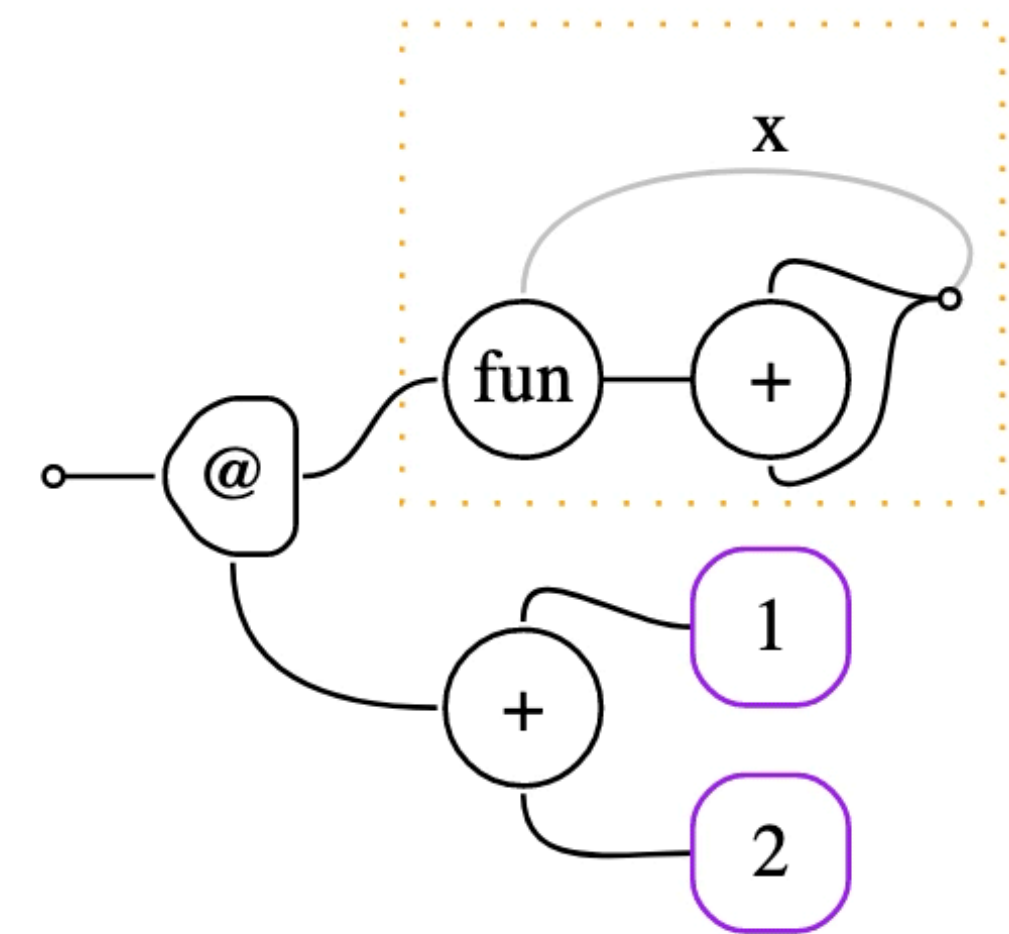
$$\begin{array}{l} C[\vec{t}] \rightarrow s \xrightarrow{k} C'[\vec{t}'] \\ \overleftarrow{\Delta}: \quad \quad \quad \vdots \overleftarrow{\Delta} \\ C[\vec{u}] \xrightarrow{m} C'[\vec{u}'] \end{array}$$

- now examining how each \rightarrow is defined
 - namely: *token-guided graph rewriting*
 - A token, moving around a graph, substitutes evaluation contexts.



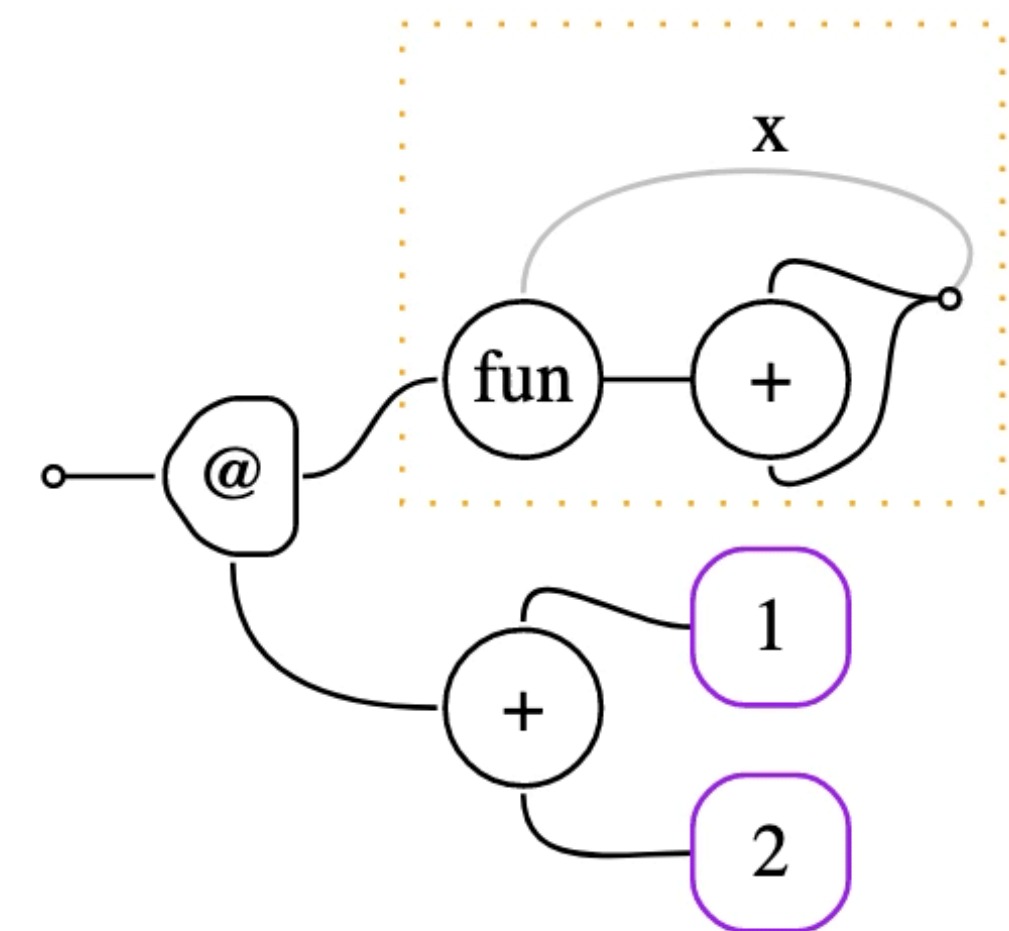
Token-guided graph rewriting

1. A token does depth-first traversal, searching for a redex.
2. The token triggers rewrite of the found redex.
3. Go back to 1.



Token-guided graph rewriting

1. A token does depth-first traversal, searching for a redex.
2. The token triggers rewrite of the found redex.
3. Go back to 1.



Graphical local reasoning for counting simulation

- (5) prove that $\overleftarrow{\triangleleft}$ is a Q -simulation

$$\begin{array}{ccc} \dot{\mathcal{C}}[\vec{N}] & \rightarrow \dot{P} & \xrightarrow{k} \dot{\mathcal{C}}'[\vec{N}'] \\ \overleftarrow{\triangleleft} \vdots & & \vdots \overleftarrow{\triangleleft} \\ \dot{\mathcal{C}}[\vec{H}] & \xrightarrow{m} & \dot{\mathcal{C}}'[\vec{H}'] \end{array}$$

- case analysis on $\dot{\mathcal{C}}[\vec{N}] \rightarrow \dot{P}$ in terms of the token behaviour
 - The token moves inside the context $\dot{\mathcal{C}}$. \implies Always OK.
 - The token visits N_i . \implies OK if \triangleleft is Q -safe.
 - The token triggers rewrite. \implies OK if \triangleleft is Q -robust.
- **Prop.** If \triangleleft is Q -safe and Q -robust, then $\overleftarrow{\triangleleft}$ is a Q -simulation.

Graphical local reasoning for counting simulation

- (5) prove that $\bar{\triangleleft}$ is a Q -simulation

$$\begin{array}{ccc} \dot{\mathcal{C}}[\vec{N}] & \rightarrow \dot{P} & \xrightarrow{k} \dot{\mathcal{C}}'[\vec{N}'] \\ \bar{\triangleleft} \vdots & & \vdots \bar{\triangleleft} \\ \dot{\mathcal{C}}[\vec{H}] & \xrightarrow{m} & \dot{\mathcal{C}}'[\vec{H}'] \end{array}$$

- **Prop.** If \triangleleft is Q -safe and Q -robust, then $\bar{\triangleleft}$ is a Q -simulation.
- **Q.** How to prove safety and robustness?
- **A.** By hand.
 - Safety: by feasible pen-and-paper proof.
 - Robustness: by tedious, involved, error-prone, case analysis.
 - **Q'.** Can somebody help the case analysis?

Graphical local reasoning for counting simulation

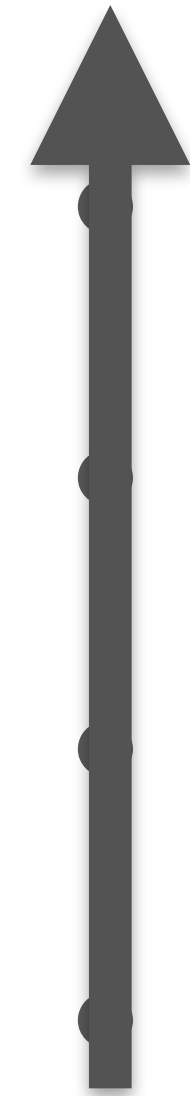
- (5) prove that $\overline{\triangleleft}$ is a Q -simulation

$$\begin{array}{ccc} \dot{\mathcal{C}}[\overrightarrow{N}] & \rightarrow \dot{P} & \xrightarrow{k} \dot{\mathcal{C}}'[\overrightarrow{N}'] \\ \overline{\triangleleft} \vdots & & \vdots \overline{\triangleleft} \\ \dot{\mathcal{C}}[\overrightarrow{H}] & \xrightarrow{m} & \dot{\mathcal{C}}'[\overrightarrow{H}'] \end{array}$$

- **Prop.** If \triangleleft is Q -safe and Q -robust, then $\overline{\triangleleft}$ is a Q -simulation.
- **Q.** How to prove safety and robustness?
- **Q''.** Can we do everything with terms and conventional reduction semantics?

A new *evitcudnioc* approach

- climbing up a ladder



probability

nondeterminism, I/O

state

divergence

counting simulation & graphical local reasoning (2020)

The left bar:
(2) “simulation” notions

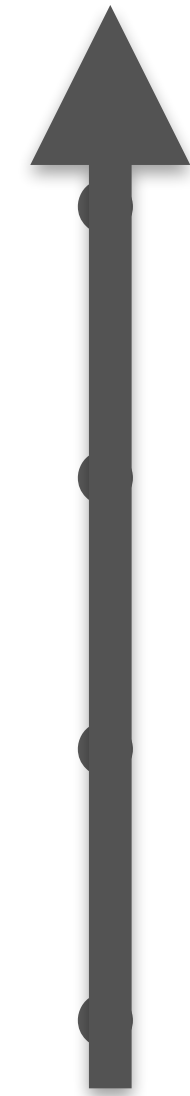
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preorder-constrained
simulation (2024)

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Preorder-constrained simulation

- (1) characterise observational refinement as “trace inclusion” of automata
- **Def.** (reduction semantics as NA)

$$\frac{}{E[(\lambda x . t) v] \xrightarrow{\tau} E[t\{v/x\}]} \quad \frac{\overline{\text{or}(t_1, t_2) \xrightarrow{\text{or}_i} t_i} \quad \overline{n \xrightarrow{n} \checkmark}}{\text{in}(t_1, t_2) \xrightarrow{\text{in}_i} t_i}$$

- **Def.** (\mathcal{Q} -trace inclusion) $x \sqsubseteq^{\mathcal{Q}} y \iff \forall w \in L_{\mathcal{A}_1}(x) . \exists w' \in L_{\mathcal{A}_2}(y) . w \mathcal{Q} w'$.

- for a preorder $\mathcal{Q} \subseteq \Sigma^* \times \Sigma^*$ on words

- *lifted* preorder $w | \mathcal{Q} | w' \iff |w| \mathcal{Q} |w'|$ for $\mathcal{Q} \subseteq \mathbb{N} \times \mathbb{N}$
- *filtered equality* $a\tau\tau b\tau c\tau =_{\text{rem}(\tau)} abc$

Preorder-constrained simulation

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 \frac{}{\text{in}(t_1, t_2) \xrightarrow{\text{in}_i} t_i} \\
 \frac{}{n \xrightarrow{n} \checkmark}
 \end{array}$$

- **Def.** (\mathcal{Q} -trace inclusion) $x \sqsubseteq^{\mathcal{Q}} y \iff \forall w \in L_{\mathcal{A}_1}(x) . \exists w' \in L_{\mathcal{A}_2}(y) . w \mathcal{Q} w'$.

- **Lem.** $\sqsubseteq^{|Q| \cup \text{rem}(\tau, \text{or})} = \dot{\sqsubseteq}_V^Q$ for nondeterminism $\leftarrow \text{or}(1,2) \dot{\sqsubseteq}_V^= \text{or}(2,1) \dots \text{YES.}$

- **Lem.** $\sqsubseteq^{|Q| \cup \text{rem}(\tau)} = \dot{\sqsubseteq}_V^Q$ for I/O $\leftarrow \text{in}(1,2) \dot{\sqsubseteq}_V^= \text{in}(2,1) \dots \text{NO.}$

Preorder-constrained simulation

- (2) design a sound “simulation” notion (for observational refinement)

- **Def.** (counting simulation)

$$R \text{ is a } Q\text{-counting simulation} \stackrel{\Delta}{\iff} R : \begin{array}{l} s \rightarrow s' \xrightarrow{k} s'' \\ t \xrightarrow{m} t' \end{array} \quad \begin{array}{l} s \in F \\ t \in F \end{array}$$

- **Def.** (preorder-constrained simulation)

$$R \text{ is an } M\text{-lookahead } \mathcal{Q}\text{-constrained simulation} \stackrel{\Delta}{\iff} R : \begin{array}{l} s \xrightarrow{w_1} s_k \xrightarrow{w_2} s_M \\ t \xrightarrow{w'} t' \end{array} \quad \begin{array}{l} s \xrightarrow{w} s_k \in F \\ t \xrightarrow{w'} t' \in F \end{array}$$

- idea: swap \forall and \exists to fully inspect branches

Preorder-constrained simulation, as a reachability game

- two-player reachability game between Challenger & Simulator

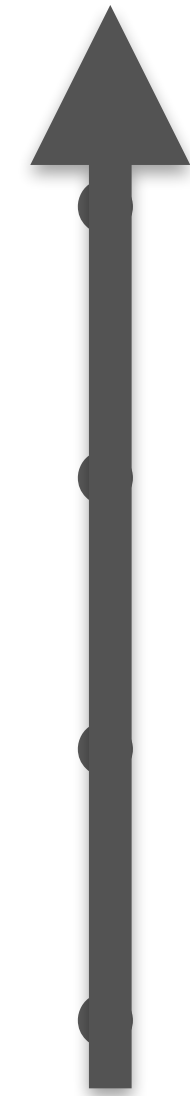
Position	Player	Move	Guard	
(w, x, y) $\in \Sigma^* \times X_1 \times X_2$	Challenger	(wa, x', y)	$x \xrightarrow{a}_1 x'$	①
		(\checkmark, w, x, y)	$x \in F_1$	②
(w, x', y) $\in \Sigma^* \times X_1 \times X_2$	Simulator	(w, x', y)	$ w < M$	③
		(ε, x', y')	$\exists w' \in \Sigma^*.$ $ w' < N \wedge y \xrightarrow{w'}_2 y' \wedge w \mathbf{Q} w'$	④
(\checkmark, w, x, y) $\in \{\checkmark\} \times \Sigma^* \times X_1 \times X_2$	Simulator	sim-win	$\exists w' \in \Sigma^*.\exists y' \in F_2.$ $ w' < N \wedge y \xrightarrow{w'}_2 y' \wedge w \mathbf{Q} w'$	⑤

- ① Challenger chooses $x \xrightarrow{a}_1 x'$ from the current state x and enqueues the label a .
- ② Challenger is at an accepting state $x \in F_1$. Challenger forces Simulator to check whether an accepting state is reachable from $y \in X_2$.
- ③ Simulator skips the turn. This move is always possible when $M = \infty$.
- ④ Simulator simulates Challenger's moves in the queue w , in less than N transitions.
- ⑤ Simulator simulates Challenger's moves in the queue w and reaches an accepting state, in less than N transitions.

■ **Figure 9** Two-player game $\mathcal{G}_{\mathcal{A}_1, \mathcal{A}_2}^{M, N, \mathbf{Q}}$ characterising $(M$ -bounded) \mathbf{Q} -constrained simulation.

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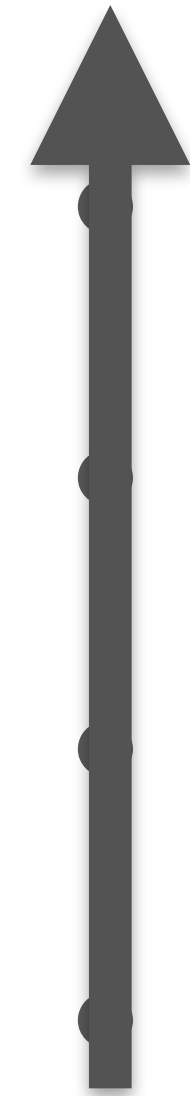
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“trace inclusion” with modalities (ongoing)

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“Trace inclusion” with modalities

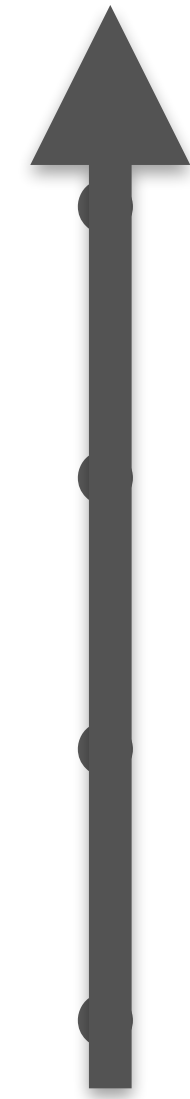
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 \end{array}$$

- **Def.** (\mathcal{O} -trace inclusion) $x \sqsubseteq^{\mathcal{O}} y \iff \dots$
- **Goal** $\sqsubseteq^{\mathcal{O}} = \dot{\sqsubseteq}_V^{\mathcal{O}}$ for various algebraic effects
 - $\dot{\sqsubseteq}_V^{\mathcal{O}}$: observational refinement with *modalities* [Simpson+ '18]
 - altering modalities \longrightarrow adjusting observation to various effects

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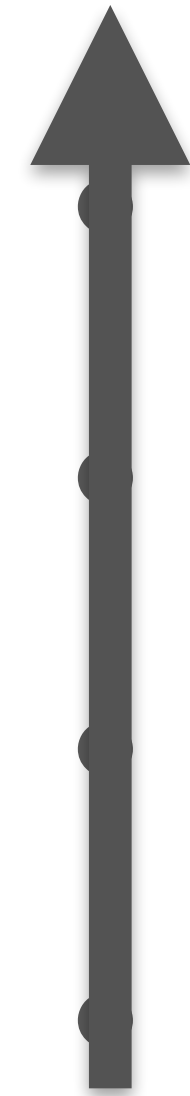
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nondeterminism, I/O

state

divergence

preorder-constrained
simulation (2024)

counting simulation & graphical local
reasoning (2020)

The left bar:
(2) “simulation” notions

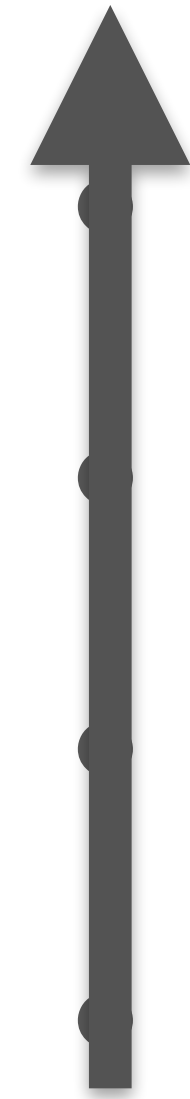
forgetting how each \rightarrow is
defined

The right bar:
(5) “simulation” proofs

examining how each \rightarrow is
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A new *evitcudnioc* approach

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A new *evitcudnioc* approach from rewriting perspective

- yet another coinductive proof methodology for contextual refinement
 - (1) characterise observational refinement as “trace inclusion” of automata
 - (2) design a sound “simulation” notion (for observational refinement)
 - (3) take a candidate \triangleleft of contextual refinement
 - (4) take the contextual closure $\overline{\triangleleft}$ (i.e. $\forall C . C[\vec{t}] \overline{\triangleleft} C[\vec{u}] \iff \forall i . t_i \triangleleft u_i$)
 - (5) prove that $\overline{\triangleleft}$ is a “simulation”
- (1-2) for all \triangleleft , (3-5) for each \triangleleft

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- only for deterministic \rightarrow

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standard
term
rewriting

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new kind of
term
rewriting

Local coherence

- (2) design a sound “simulation” notion (for observational refinement)

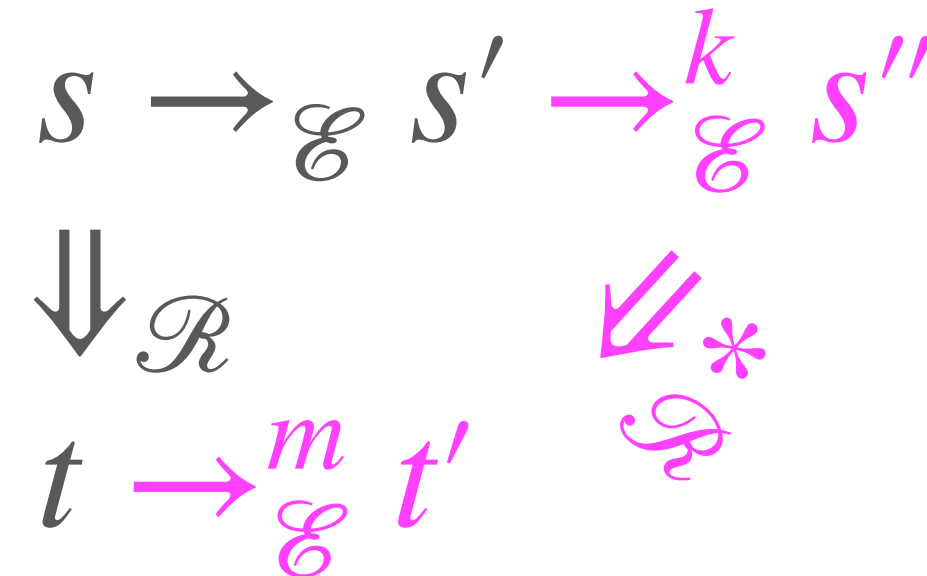
- target: \leq_V^{\geq} (Sands’ *improvement*)

- $t \leq_V^{\geq} u \stackrel{\Delta}{\iff} \forall C. C[t] \rightarrow^k v \implies C[u] \rightarrow^m v \wedge k \geq m$

- \geq chosen for a technical reason

- **Def.** (local coherence)

$\Rightarrow_{\mathcal{R}}$ is locally coherent $\stackrel{\Delta}{\iff}$



a notion taken from equational rewriting

- **Prop.** (soundness) If $\Rightarrow_{\mathcal{R}}$ is locally coherent, then $\Rightarrow_{\mathcal{R}} \subseteq \leq_V^{\geq}$.

- only for deterministic $\rightarrow_{\mathcal{E}}$ and *value-invariant* $\Rightarrow_{\mathcal{R}}$

Critical pair analysis for local coherence

- (5) prove that $\Rightarrow_{\mathcal{R}}$ is locally coherent
- **Thm.** (critical pair theorem) $\Rightarrow_{\mathcal{R}}$ is locally coherent iff every critical pair is joinable.

- joinability:

$$\begin{array}{ccc} s & \xrightarrow{\mathcal{E}} & s' \xrightarrow[k_{\mathcal{E}}]{} s'' \\ \Downarrow_{\mathcal{R}} & & \Downarrow_{\mathcal{R}^*} \\ t & \xrightarrow[m_{\mathcal{E}}]{} & t' \end{array}$$

Critical pairs can be automatically enumerated & checked for joinability!

- only for evaluation-context-preserving $\Rightarrow_{\mathcal{R}}$, linear refinement rules, left-linear evaluation rules, ...
- **Ex.** the call-by-value λ -calculus,
the computational λ -calculus with (shallow) effect handlers

2 critical pairs

10 critical pairs

Critical pair analysis for local coherence

- Ex. the call-by-value λ -calculus

Signature Σ

Syntax class $Sclass$

Evaluation contexts $Ectx$

Evaluation rules \mathcal{E}

$(\lambda x.M[x]) V \rightarrow M[V]$

$\lambda: \langle 1 \rangle, @: \langle 0, 0 \rangle$

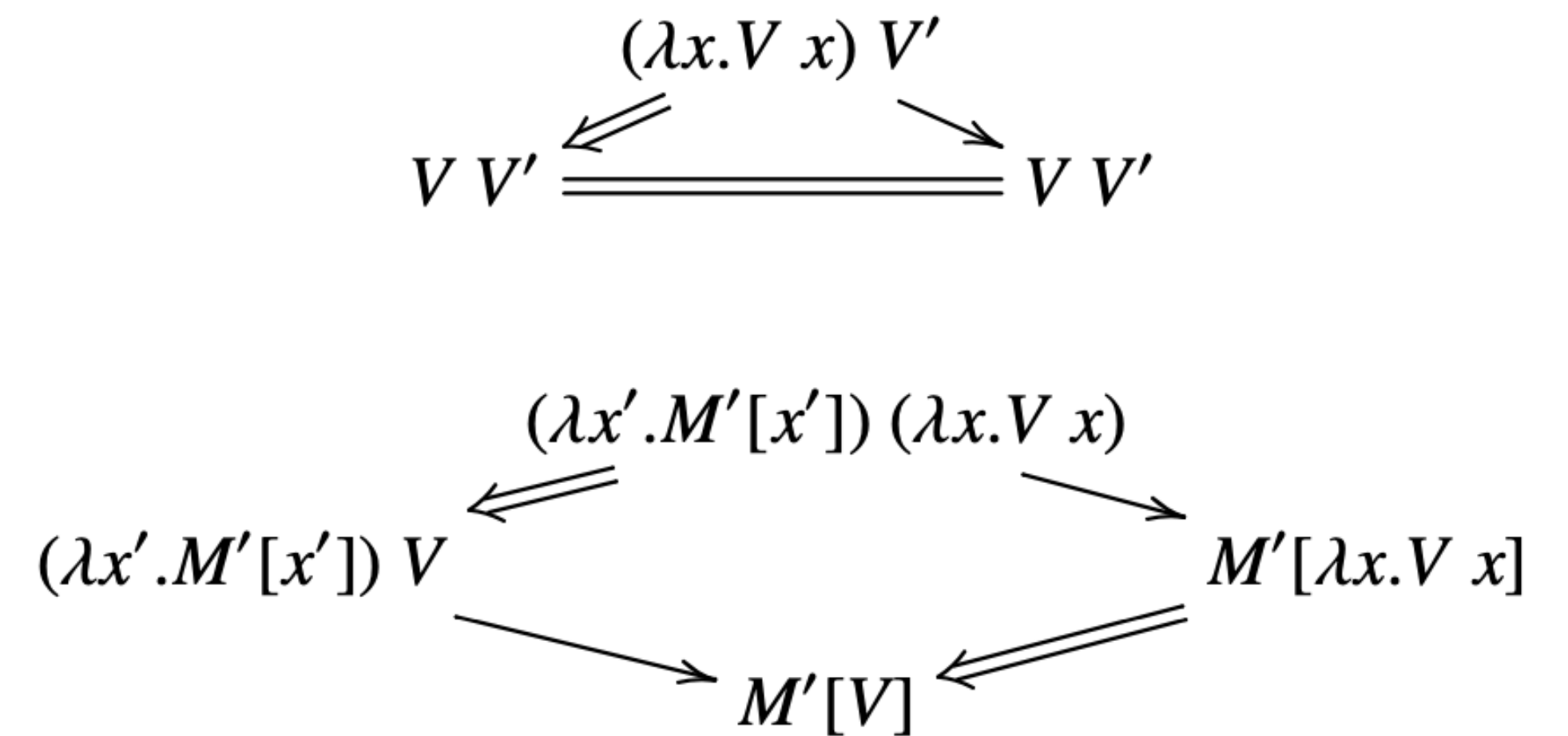
values $V ::= \lambda x.t$

$E ::= \square \mid E t \mid v E$

Refinement rules \mathcal{R}

$(\lambda x.M[x]) V \Rightarrow M[V]$

$\lambda x.V x \Rightarrow V$



Critical pair analysis for local coherence

- Ex. the computational λ -calculus with (shallow) effect handlers

Signature Σ

true: $\langle 0 \rangle$, false: $\langle 0 \rangle$, fun: $\langle 1 \rangle$, @: $\langle 0, 0 \rangle$, return: $\langle 0 \rangle$, op₁: $\langle 0, 1 \rangle$, op₂: $\langle 0, 1 \rangle$,
handler₁: $\langle 1, 2 \rangle$, handler₀: $\langle 1 \rangle$, do: $\langle 0, 1 \rangle$, if: $\langle 0, 0, 0 \rangle$, with_handle: $\langle 0, 0 \rangle$

Syntax class *Sclass*

functions $F ::= x \mid \text{fun}(x.P)$

values $V ::= \text{true} \mid \text{false} \mid F \mid H$

handlers $H ::= \text{handler}_1(x.P, x.k.P_1) \mid \text{handler}_0(x.P)$

computations $P, P_1, P_2 ::= \text{return}(V) \mid \text{op}(V, y.P) \mid \text{do}(P_1, x.P_2)$
 $\mid \text{if}(V, P_1, P_2) \mid F V \mid \text{with_handle}(H, P)$

Evaluation contexts *Ectx* $E ::= \square \mid \text{do}(E, x.P) \mid \text{with_handle}(H, E)$

Evaluation rules \mathcal{E} where $i \in [2]$

$\text{do}(\text{return}(V), x.P[x]) \rightarrow P[V]$ (1)

$\text{do}(\text{op}_i(V, y.P_1[y]), x.P_2[x]) \rightarrow \text{op}_i(V, y.\text{do}(P_1[y], x.P_2[x]))$ (2)

$\text{if}(\text{true}, P_1, P_2) \rightarrow P_1$ (3)

$\text{if}(\text{false}, P_1, P_2) \rightarrow P_2$ (4)

$\text{fun}(x.P[x]) V \rightarrow P[V]$ (5)

In the following three rules, $h_1 \equiv \text{handler}_1(x.P[x], x.k.P_1[x, k])$.

$\text{with_handle}(h_1, \text{return}(V)) \rightarrow P[V]$ (6)

$\text{with_handle}(h_1, \text{op}_1(V, y.P'[y])) \rightarrow P_1[V, \text{fun}(y.P'[y])]$ (7)

$\text{with_handle}(h_1, \text{op}_2(V, y.P'[y])) \rightarrow \text{op}_2(V, y.\text{with_handle}(h_1, P'[y]))$ (8)

In the following two rules, $h_0 \equiv \text{handler}_0(x.P[x])$.

$\text{with_handle}(h_0, \text{return}(V)) \rightarrow P[V]$ (9)

$\text{with_handle}(h_0, \text{op}_i(V, y.P'[y])) \rightarrow \text{op}_i(V, y.\text{with_handle}(h_0, P'[y]))$ (10)

Refinement rules \mathcal{R}

$\text{do}(P, x.\text{return}(x)) \Rightarrow P$ (r3)

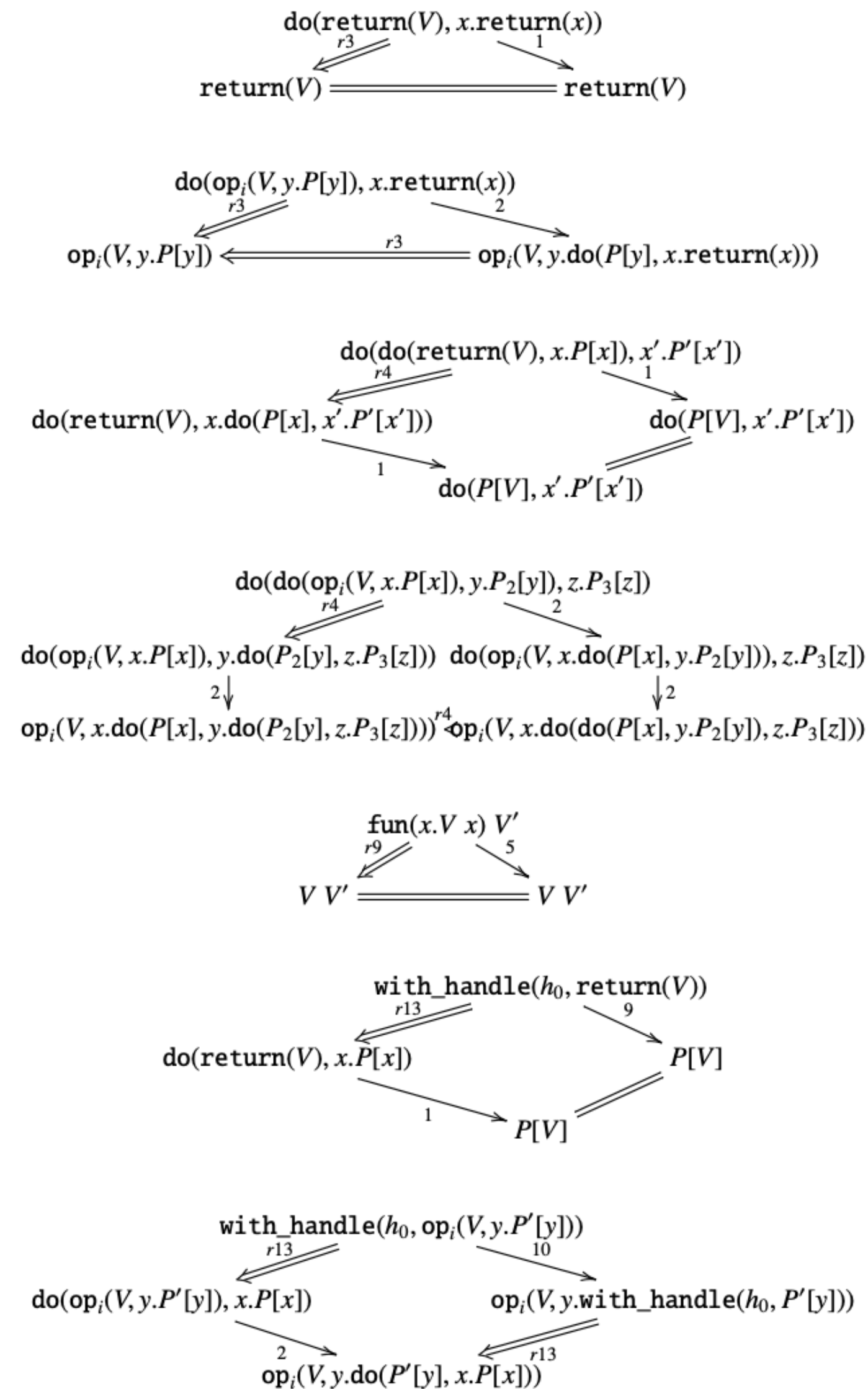
$\text{do}(\text{do}(P_1, x_1.P_2[x_1]), x_2.P_3[x_2]) \Rightarrow \text{do}(P_1, x_1.\text{do}(P_2[x_1], x_2.P_3[x_2]))$ (r4)

$\text{fun}(x.F x) \Rightarrow F$ (r9)

$\text{with_handle}(\text{handler}_0(x.P[x]), P') \Rightarrow \text{do}(P', x.P[x])$ (r13)

Critical pair analysis for local coherence

- Ex. the computational λ -calculus with (shallow) effect handlers

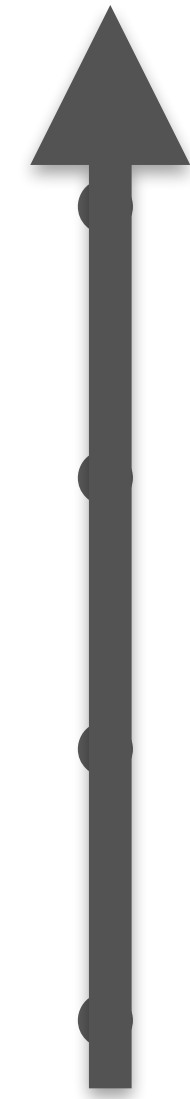


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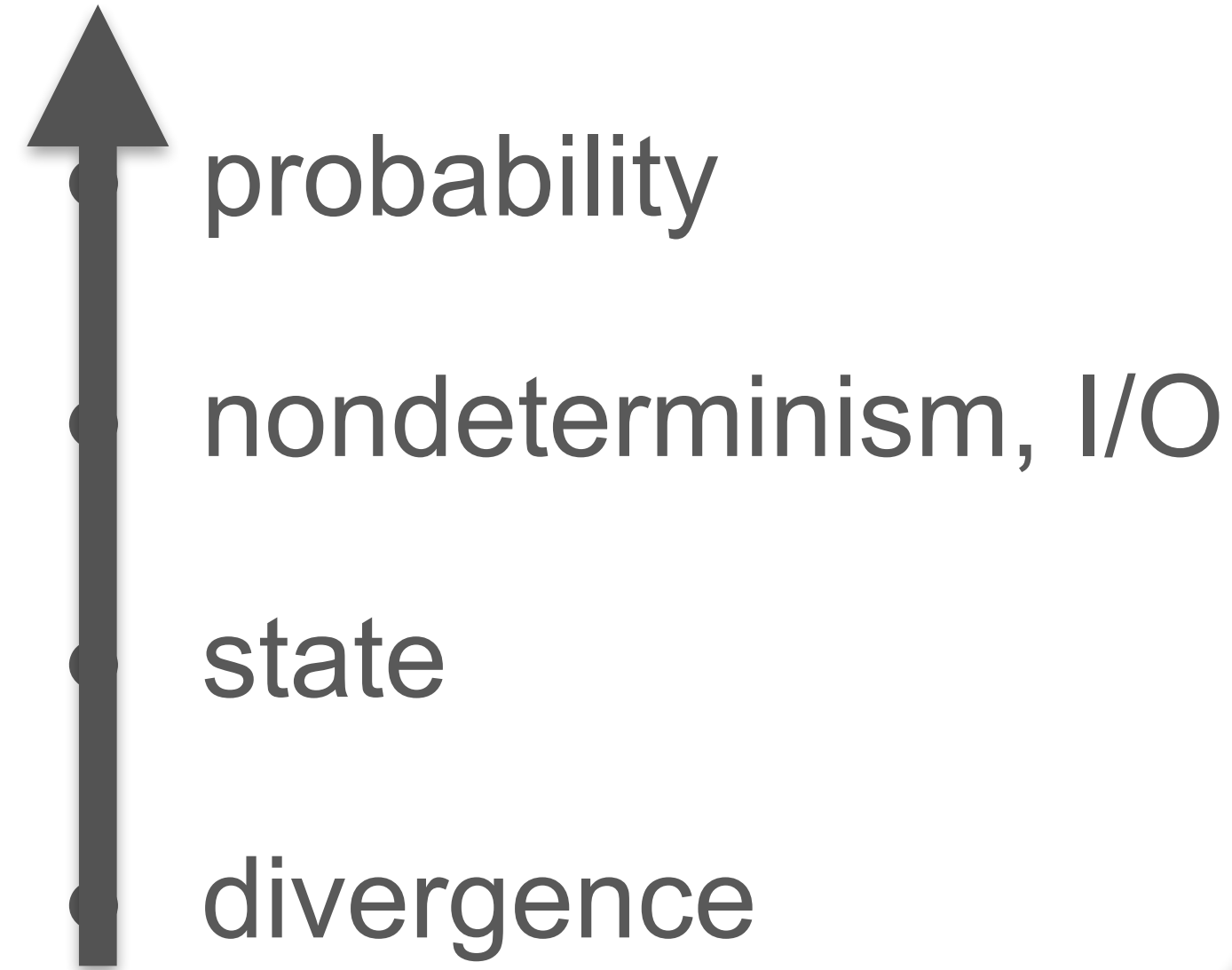
M. PhD thesis 2020

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preorder-constrained simulation (2024)

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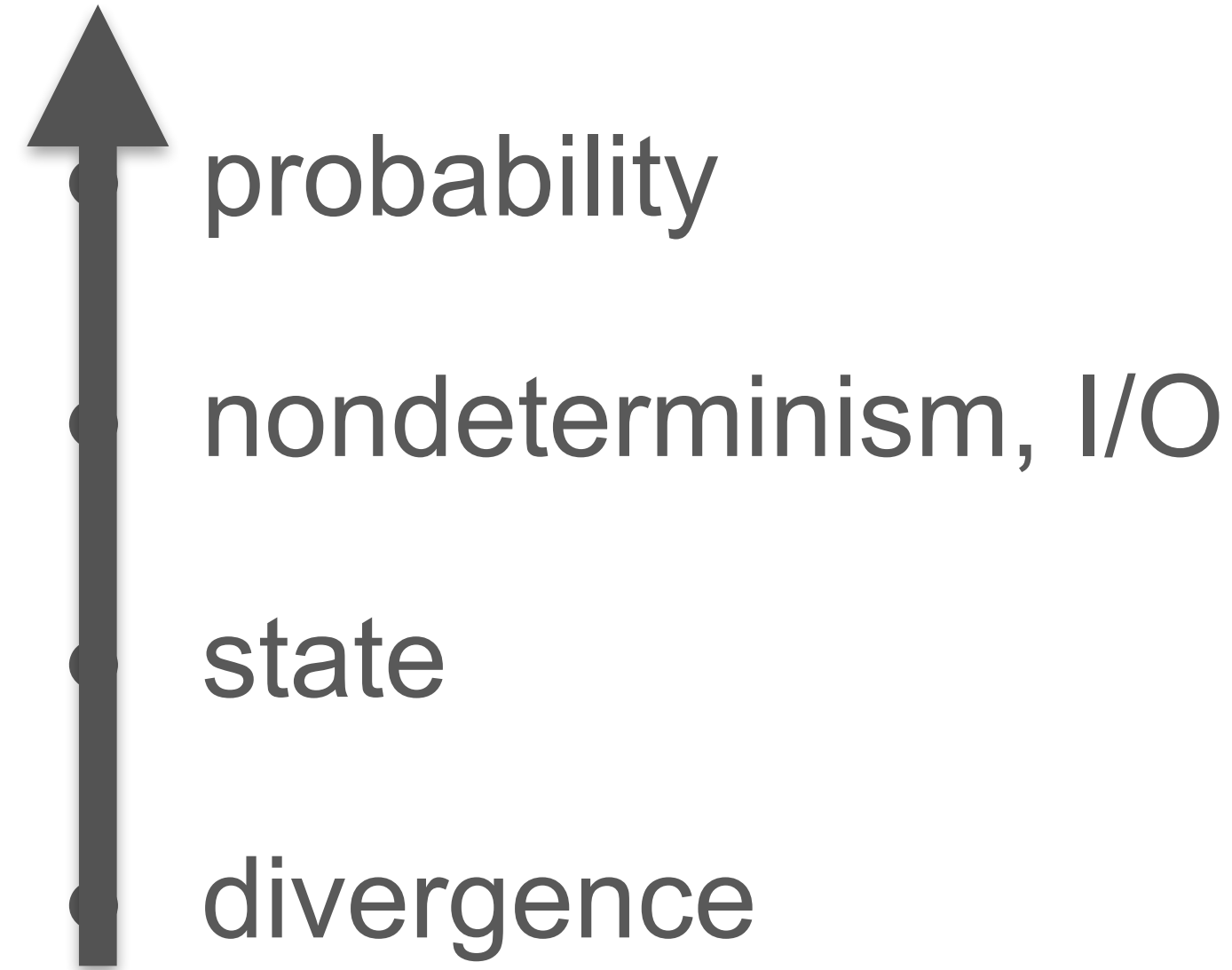
M., Sanada & Urabe
CMCS 2024

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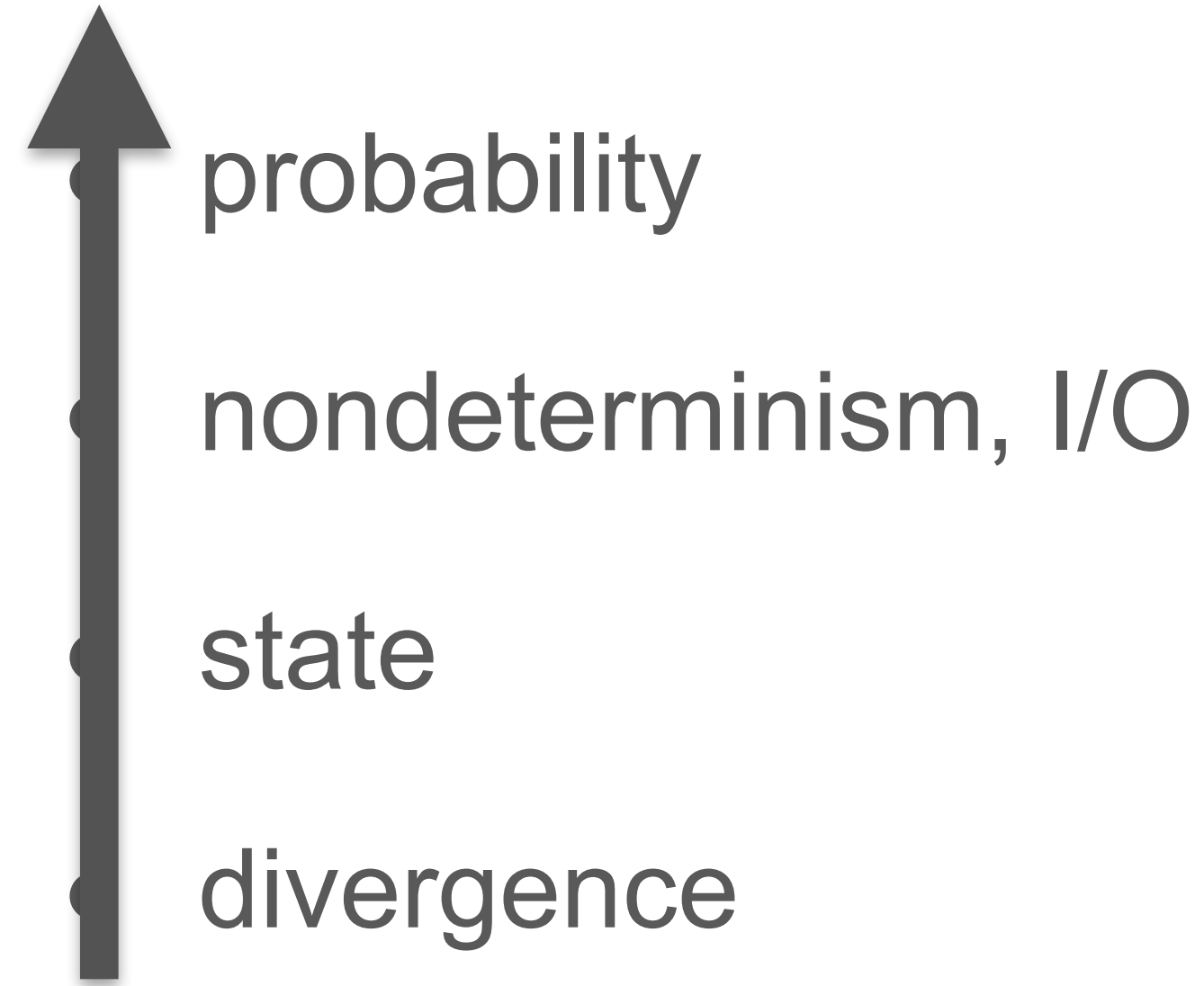
M. & Hamana
FLOPS 2024

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- potential side-steps

- call-by-need
- continuation

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