

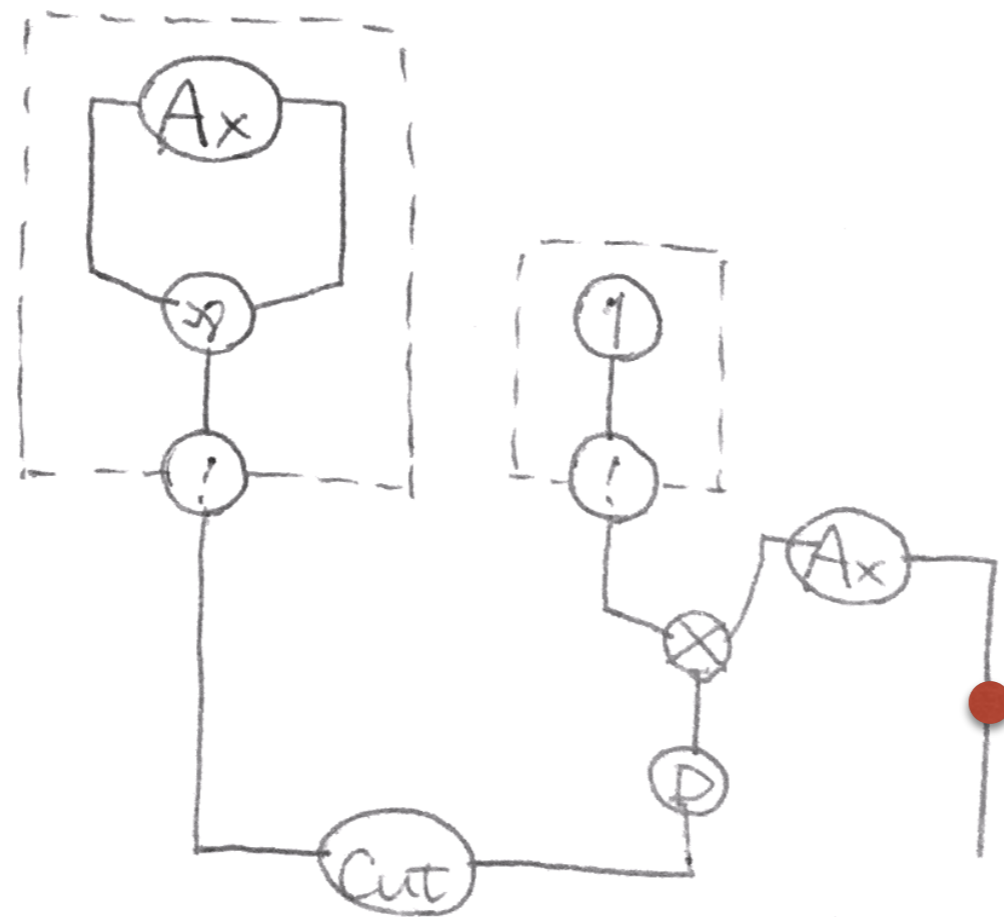
Dynamic Gol machine

Call-by-need and call-by-value graph rewriter

Koko Muroya & Dan Ghica
(Univ. Birmingham)

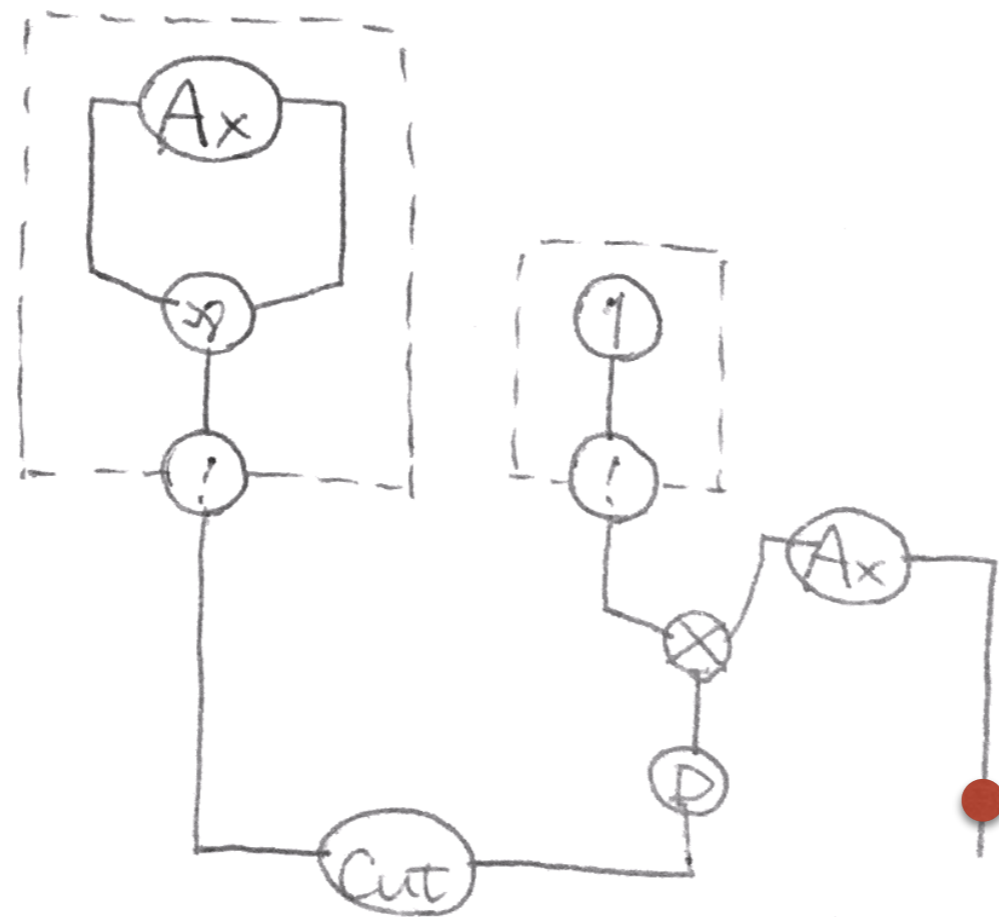
Gol machine [Danos & Regnier '99] [Mackie '95]

$(\lambda x. x) 1$



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$(\lambda x. x) 1$



Gol machine [Danos & Regnier '99] [Mackie '95]

call-by-name

call-by-value

effects

Gol machine [Danos & Regnier '99] [Mackie '95]

call-by-name

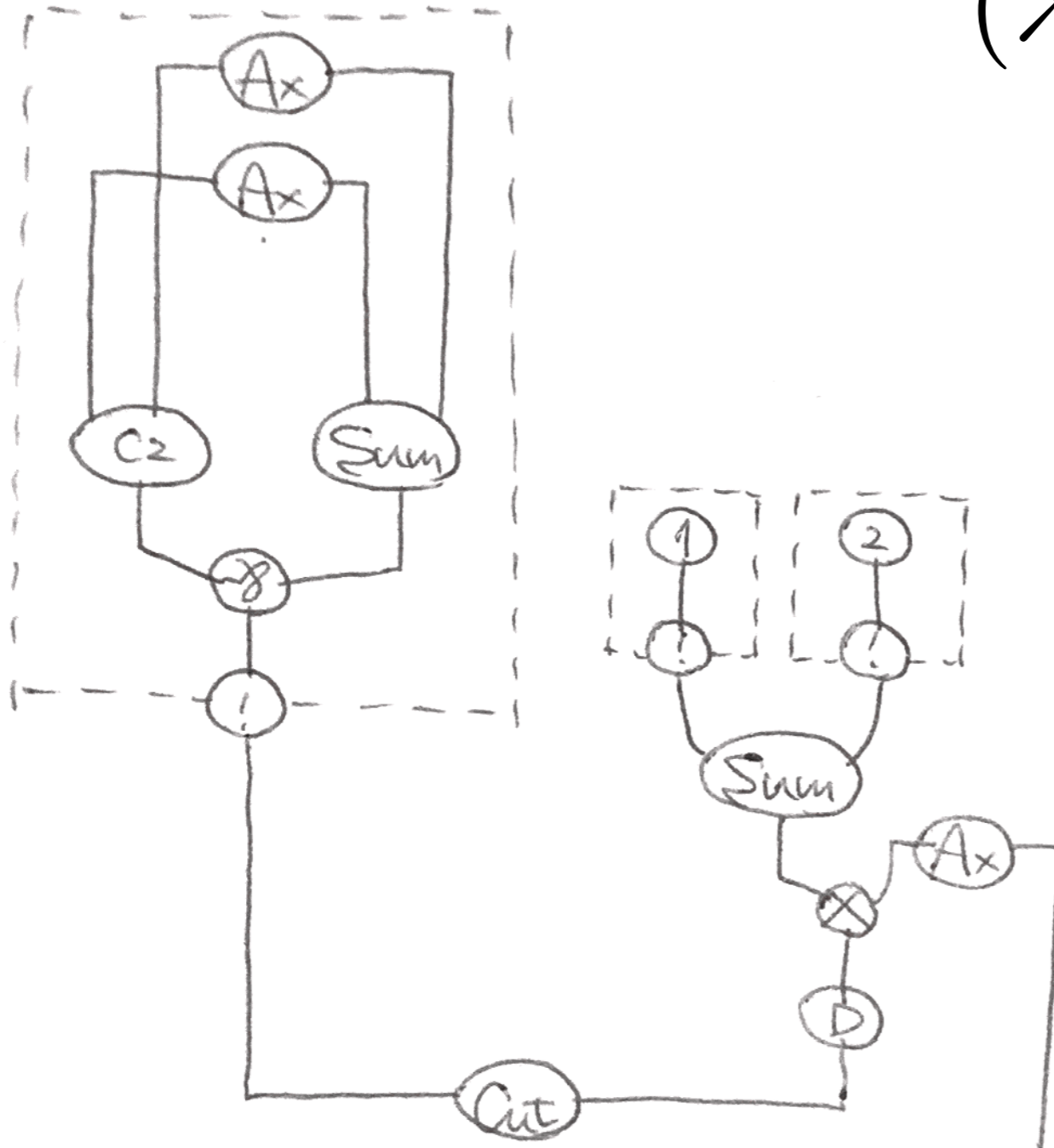
call-by-value

effects

	avoid re-evaluation	force evaluation of arguments	track each copy of terms
CPS transform.	?	✓	? Schöpp
memory	△		✓ Hoshino+
parallelism & sync.	△	✓	Dal Lago+
dynamic jump	✓	✓	Fernández+
dynamic rewrite	✓		☺
checkpoint		✓	

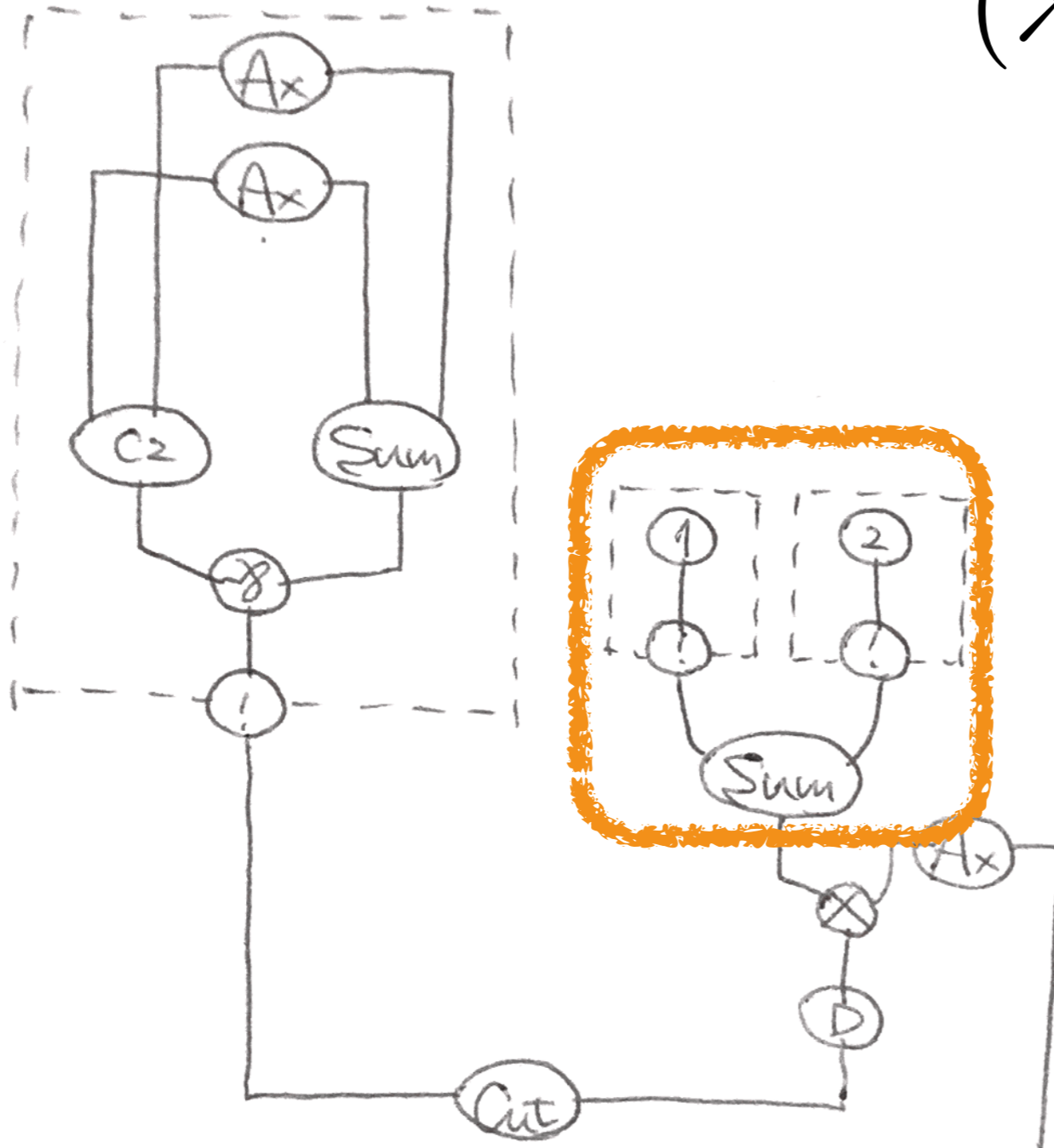
Avoid re-evaluation

$$(\lambda x. x + x) (1 + 2)$$



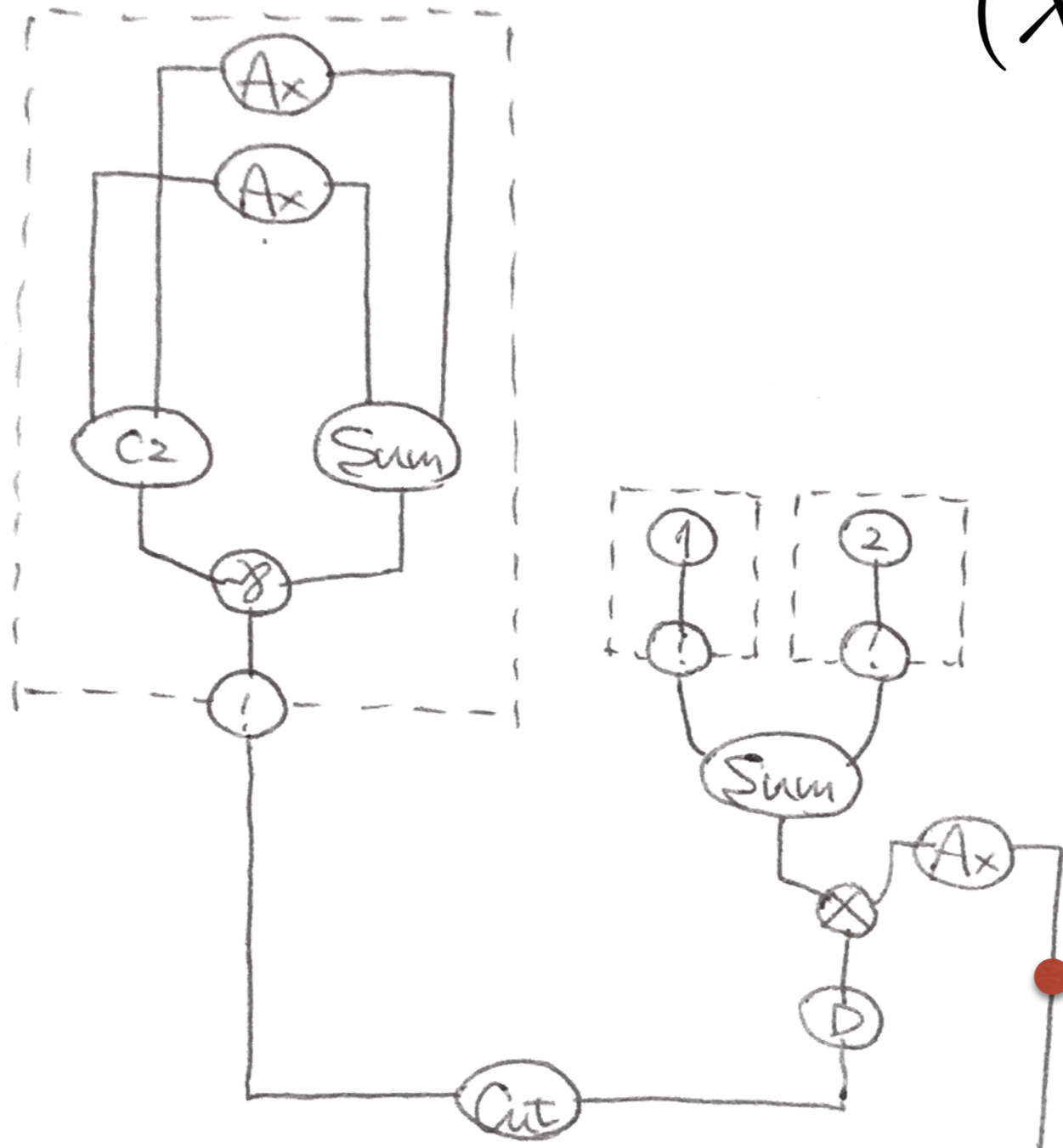
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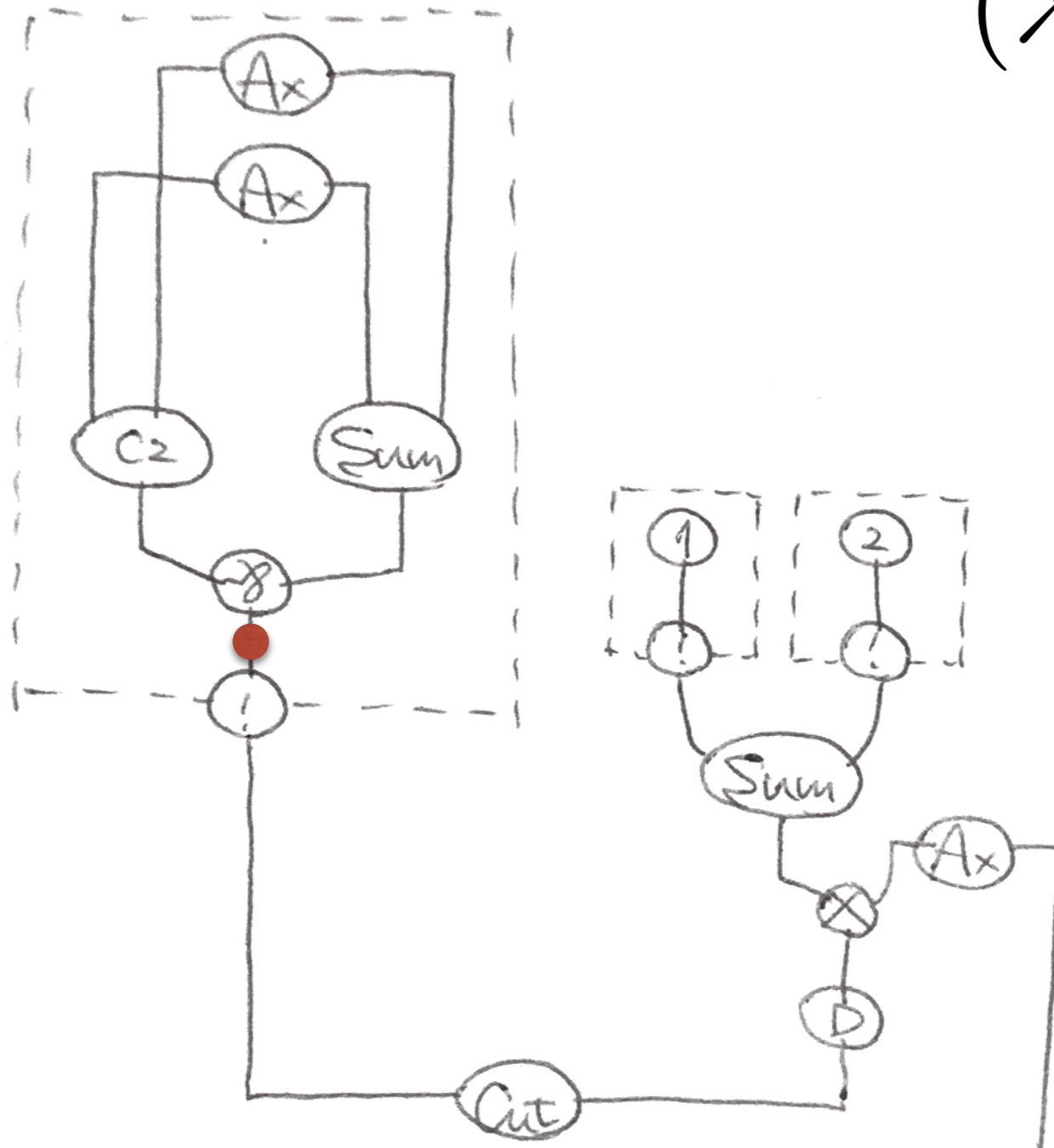
Avoid re-evaluation: dynamic rewrite

$$(\lambda x. x + x) (1 + 2)$$



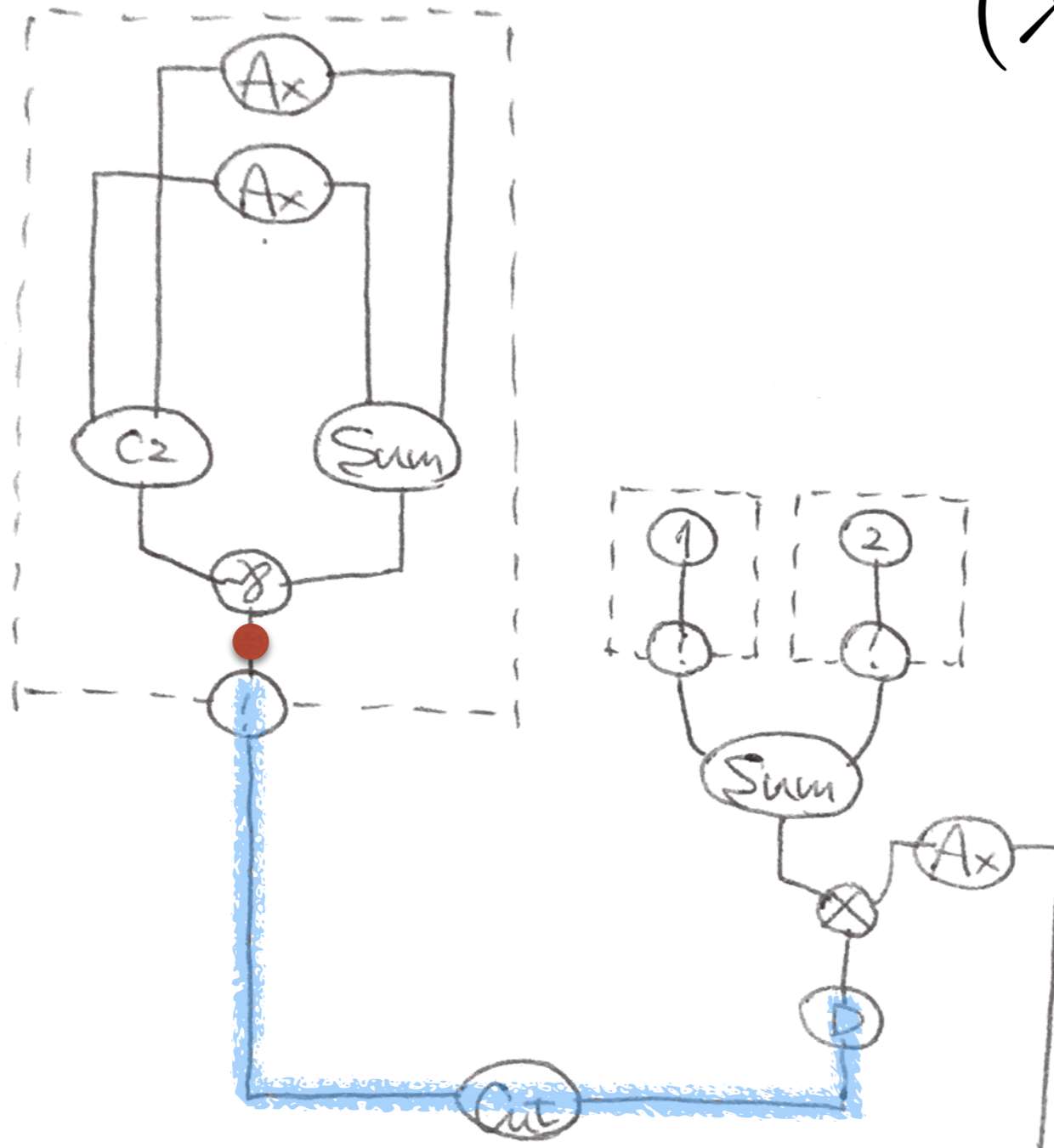
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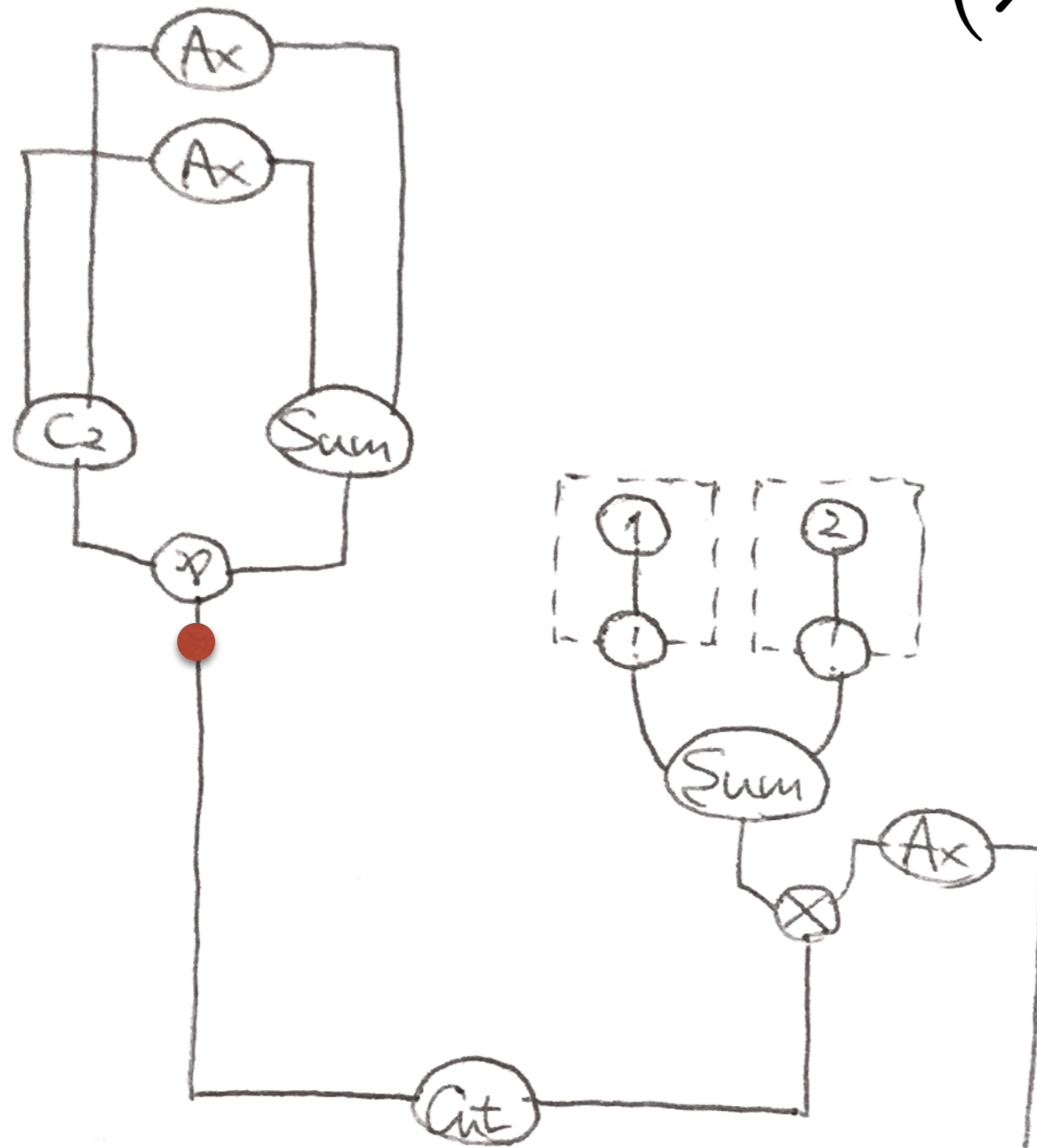
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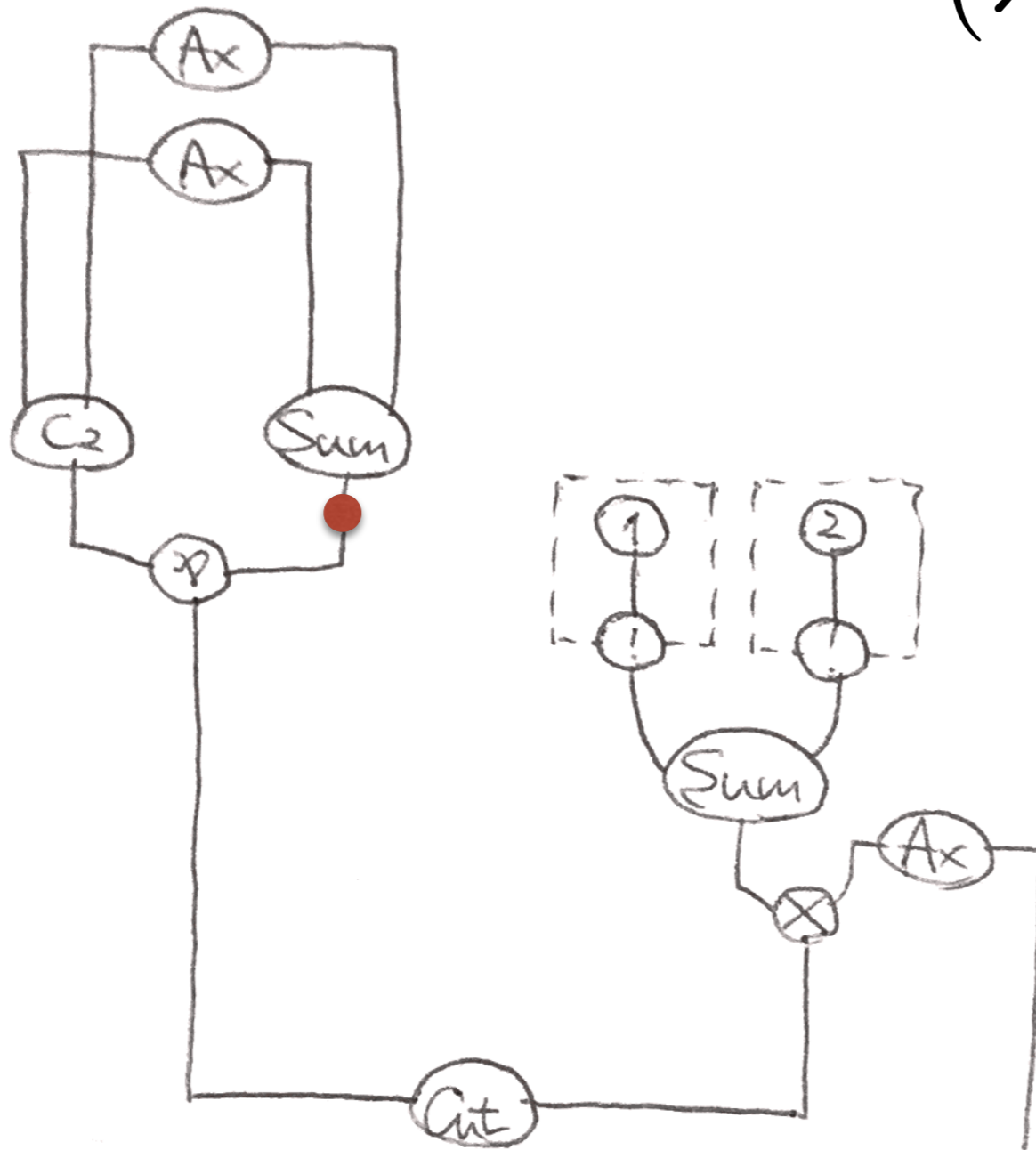
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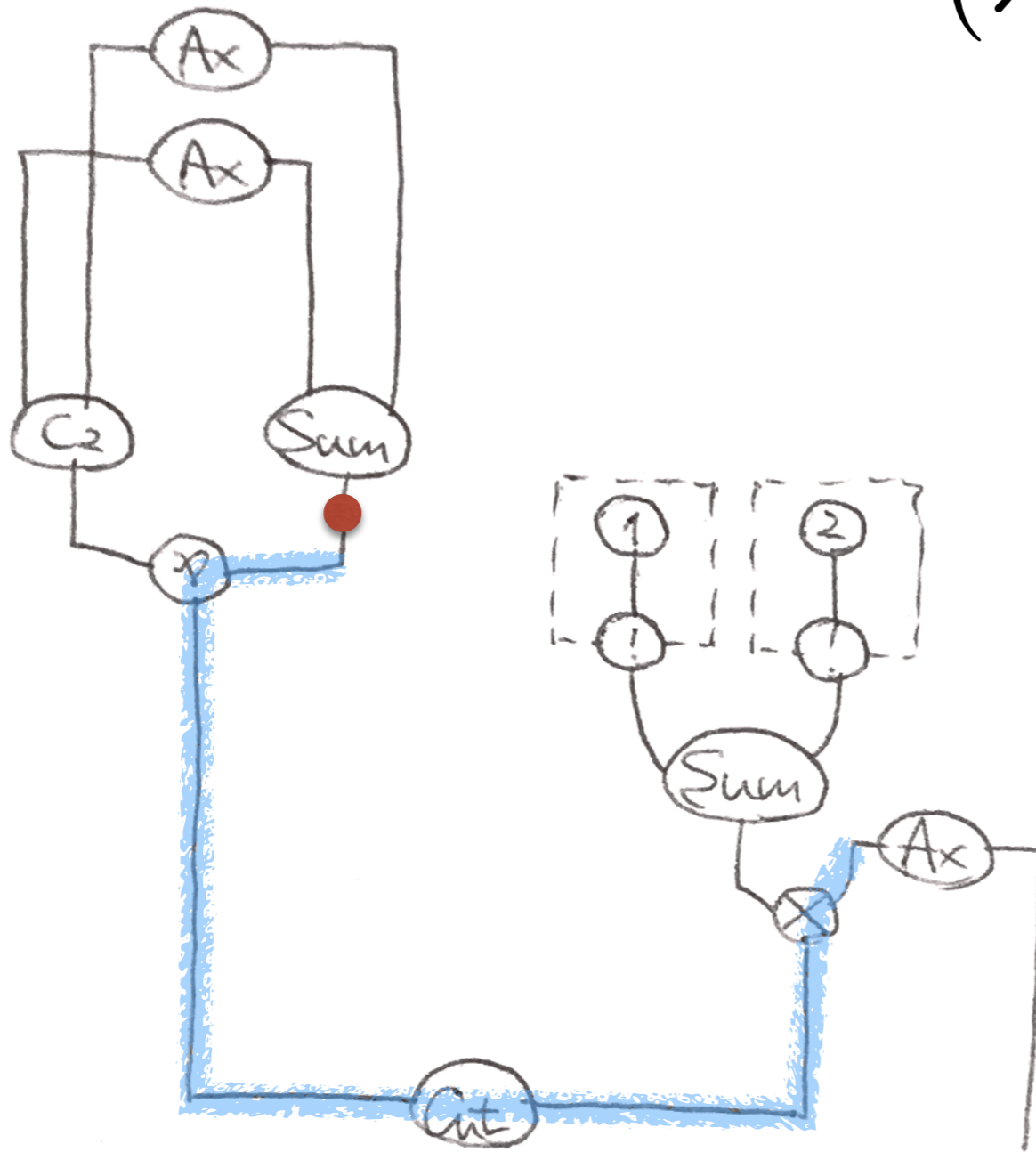
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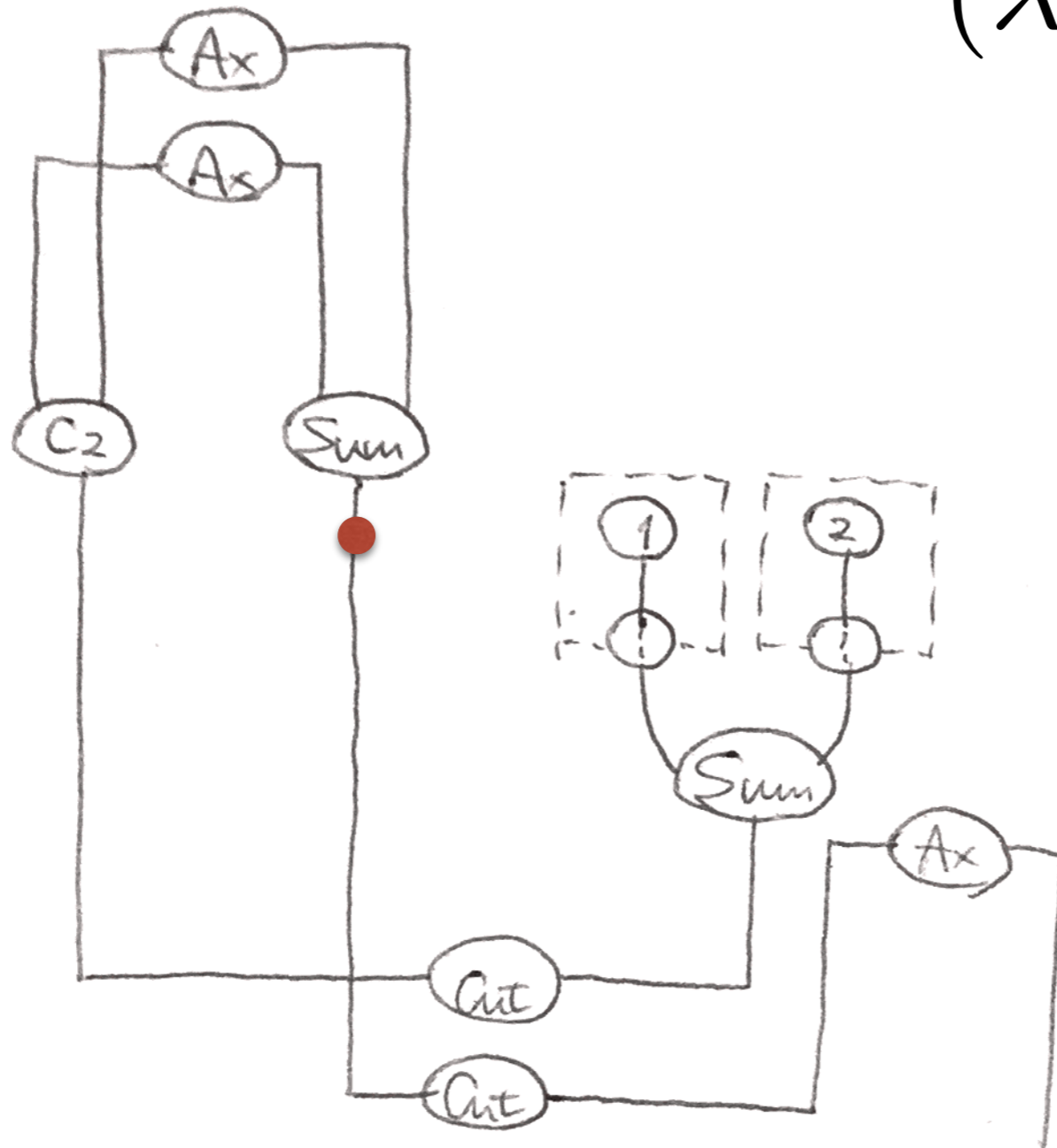
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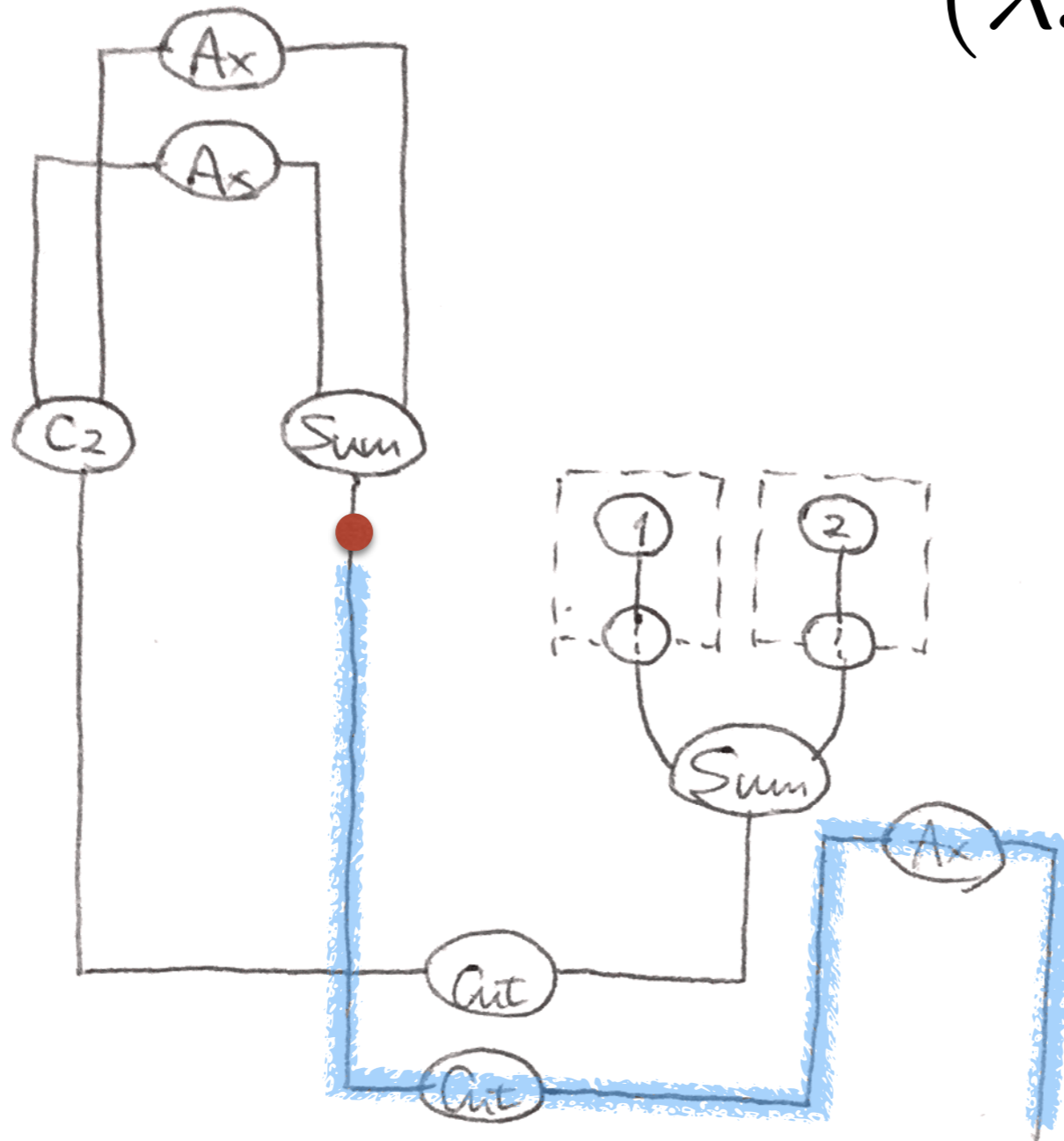
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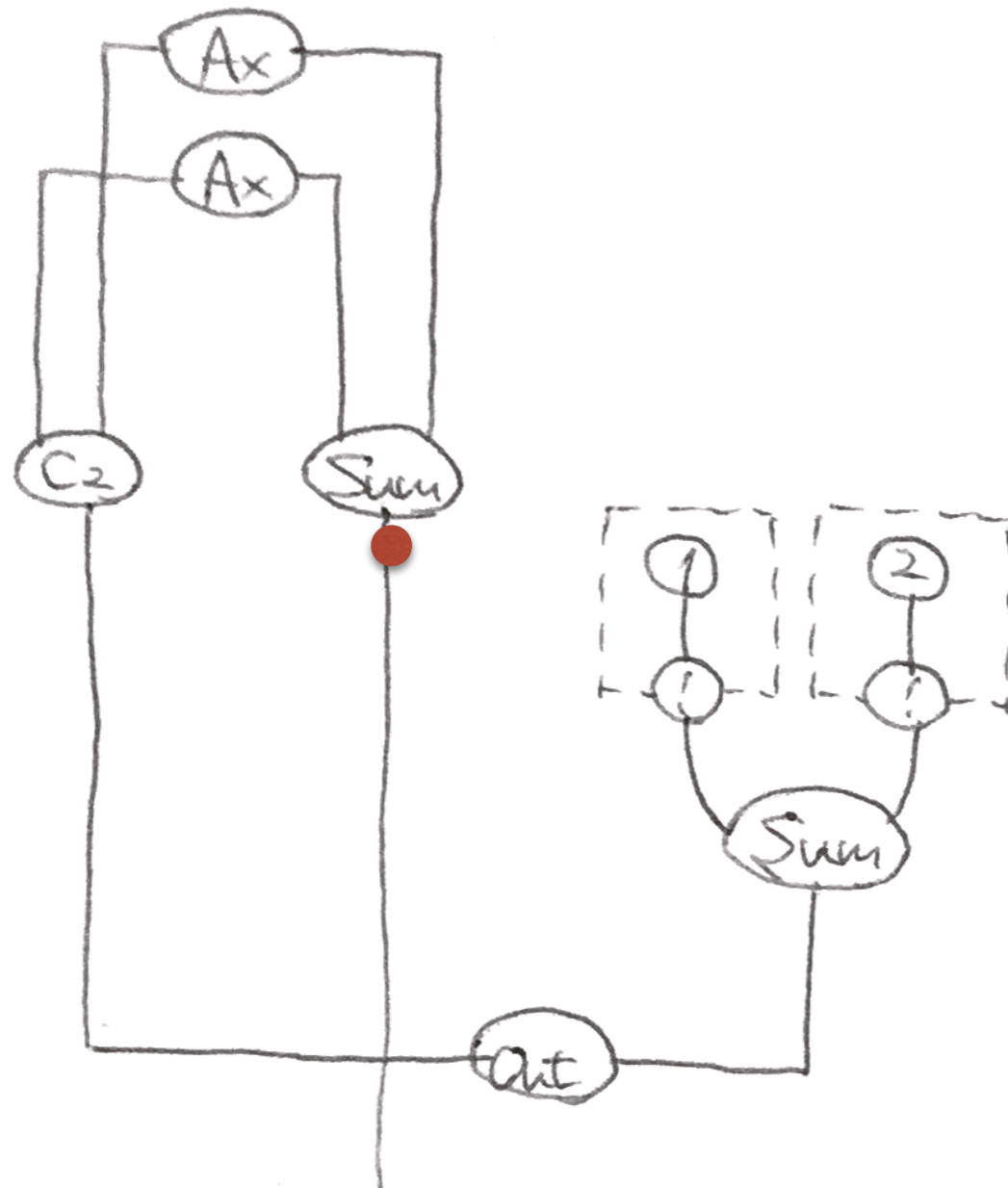
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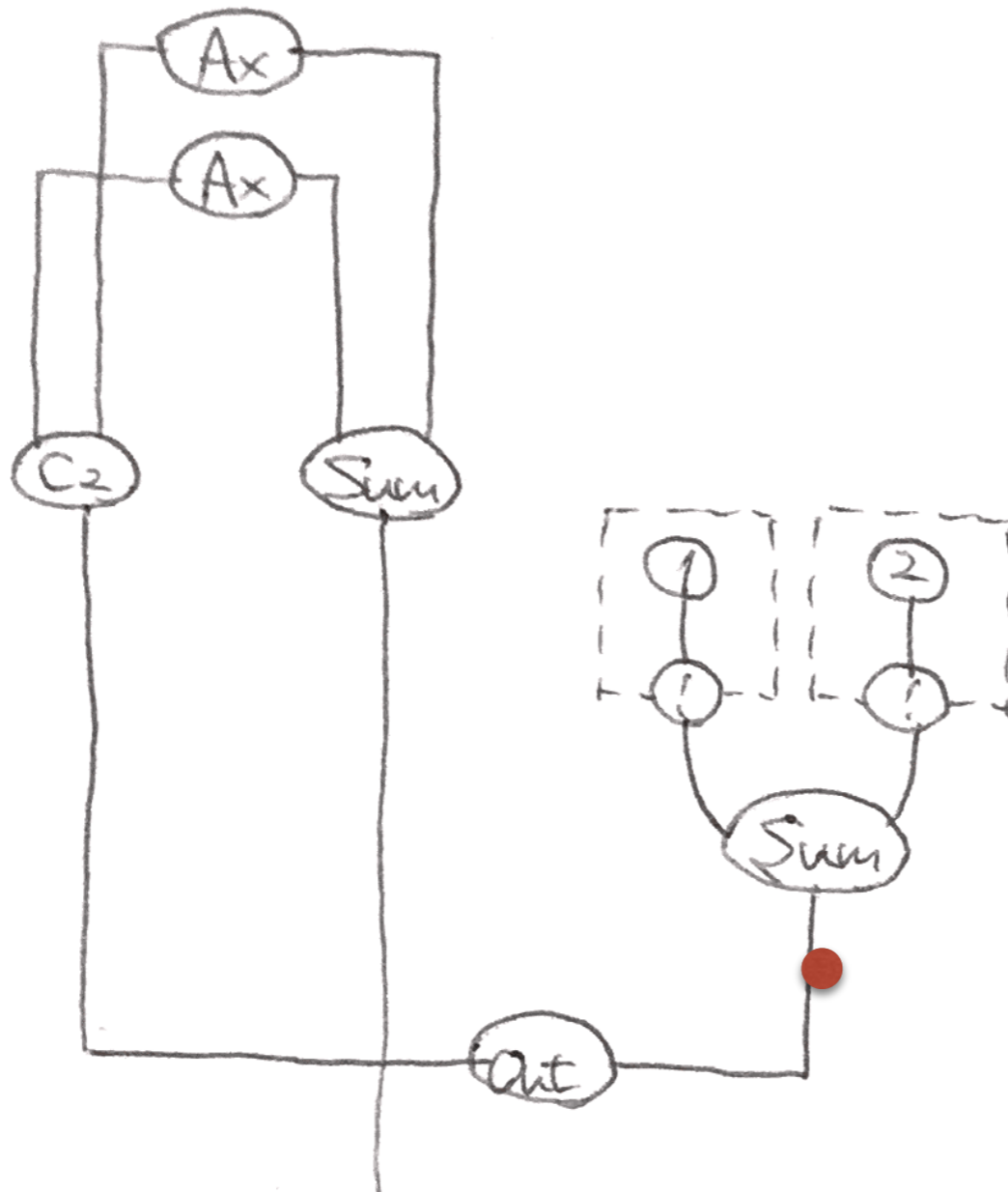
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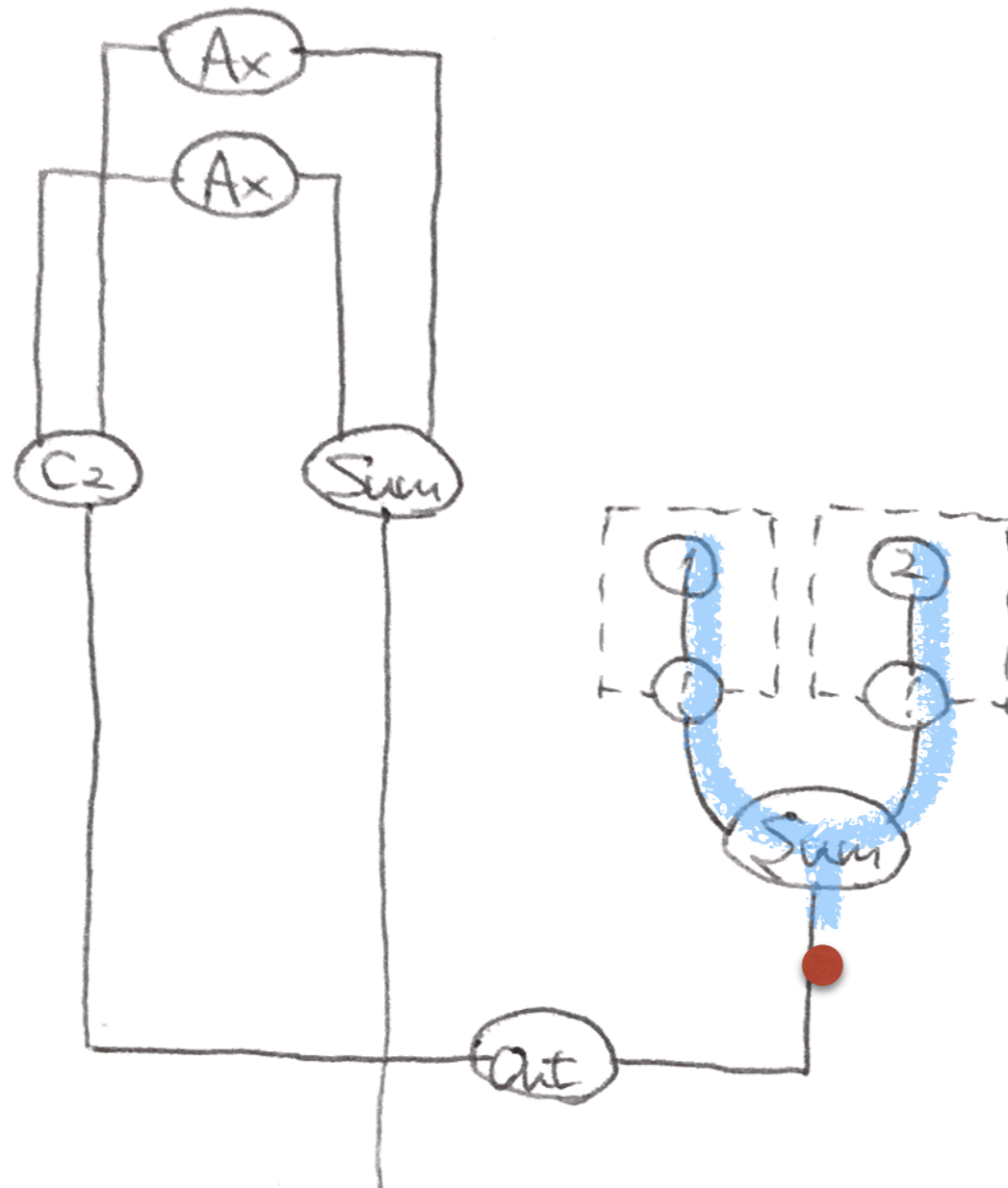
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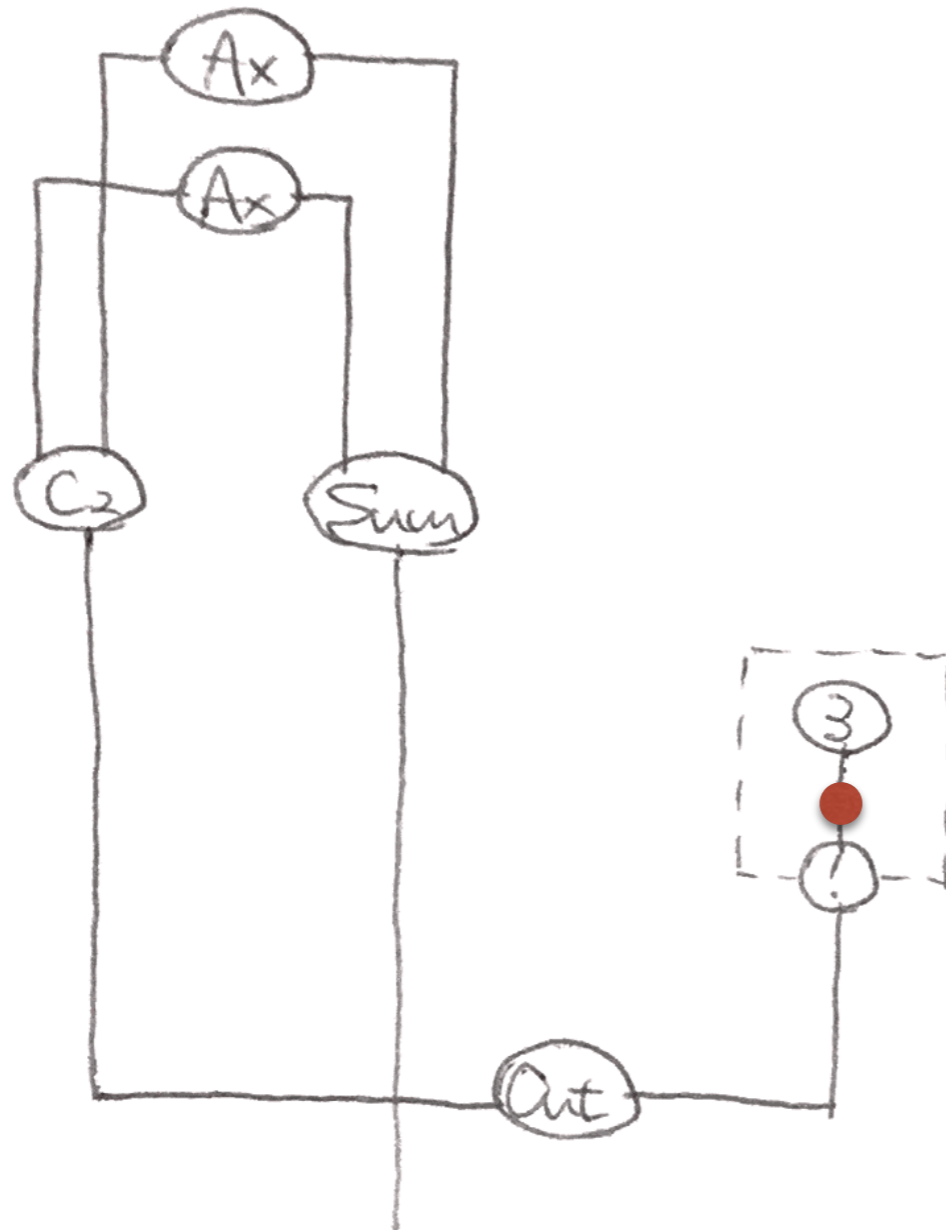
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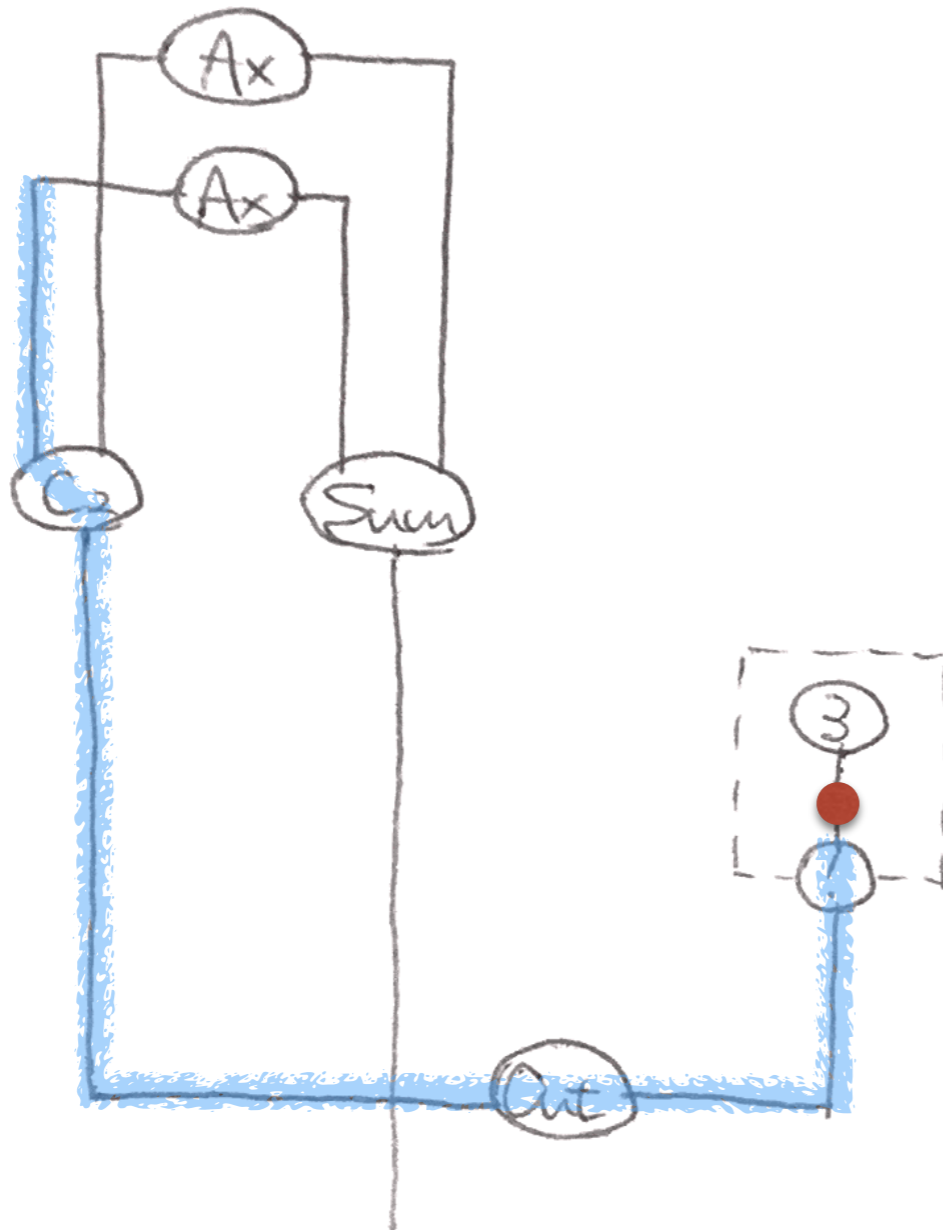
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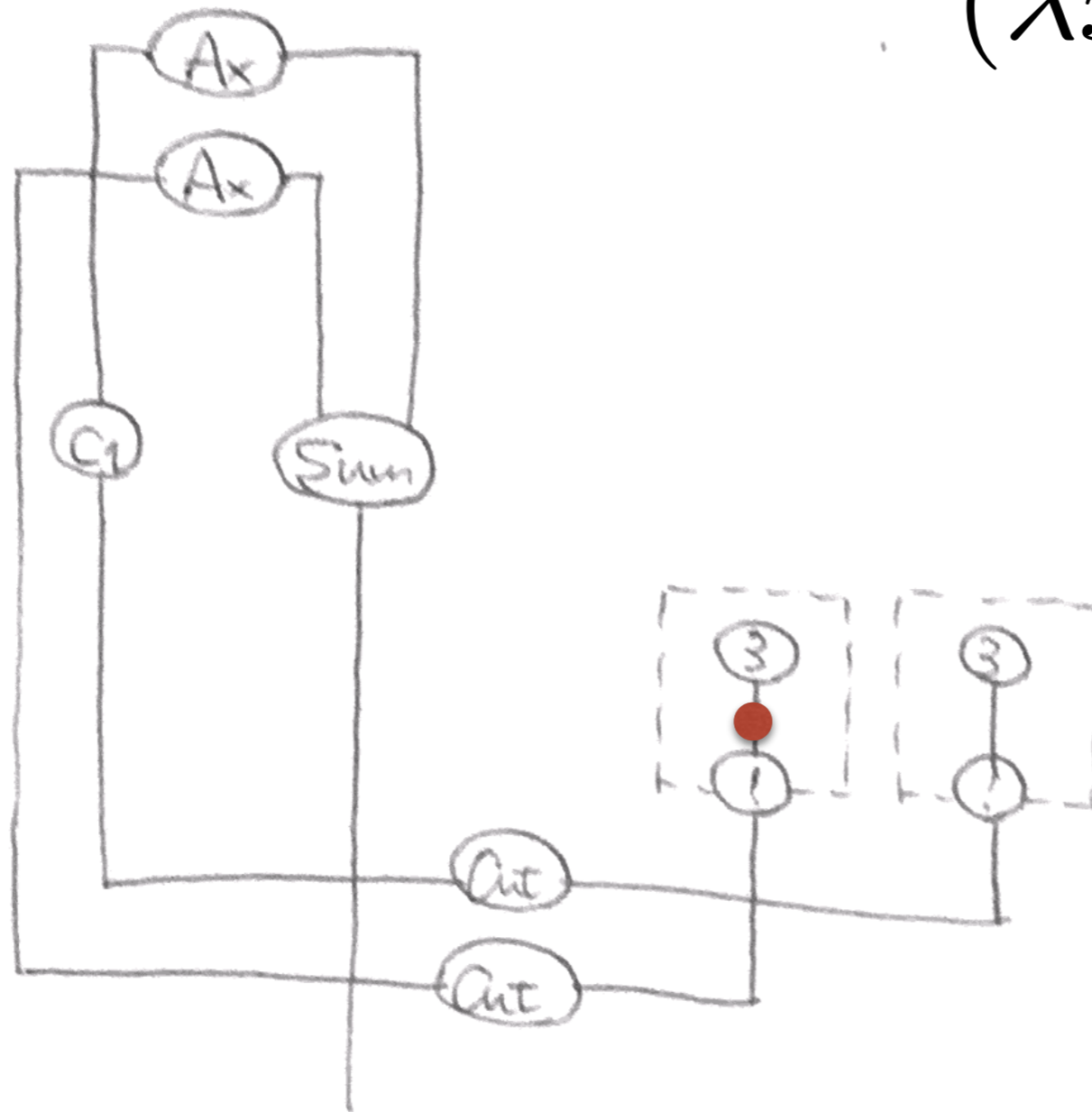
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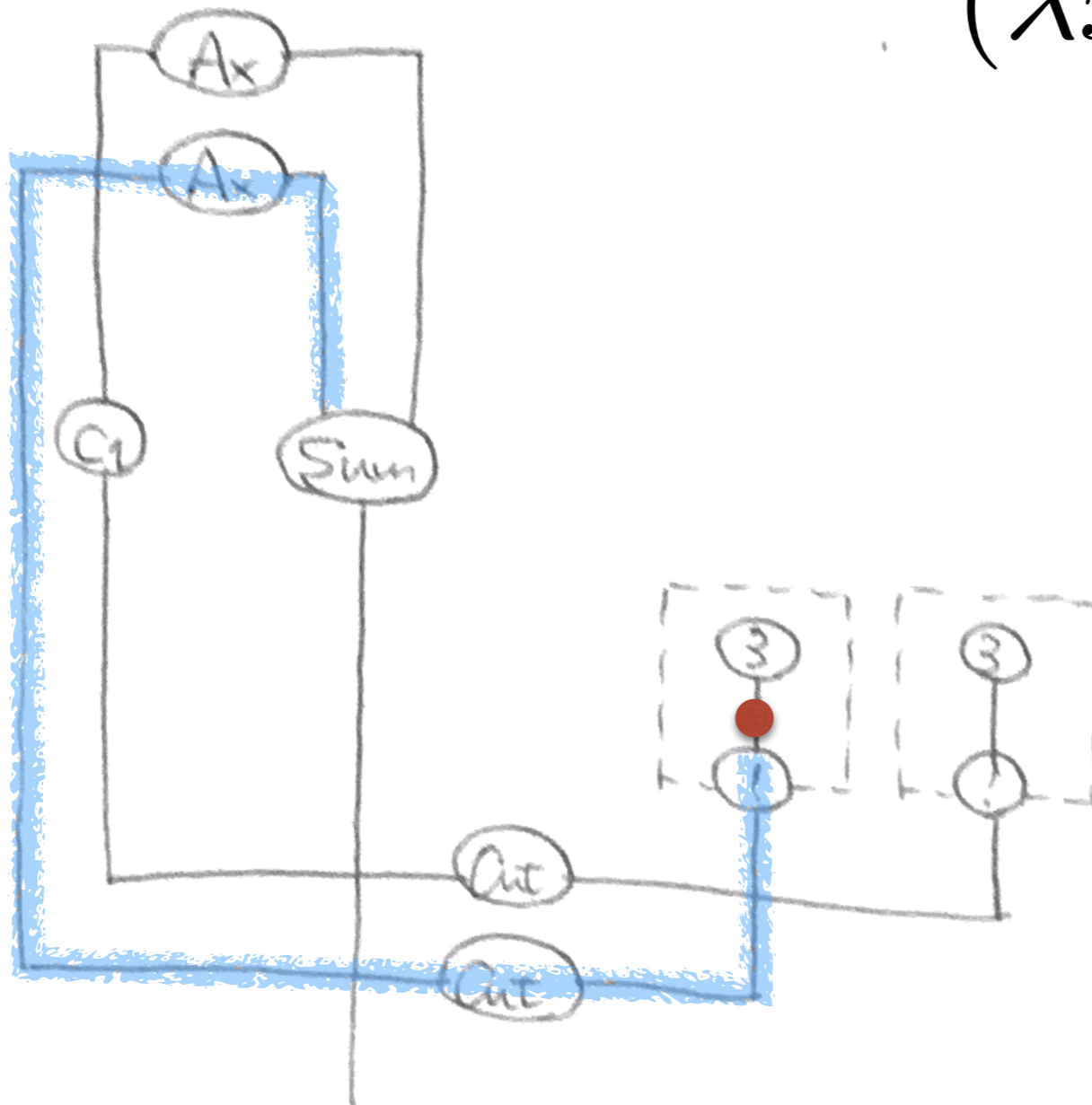
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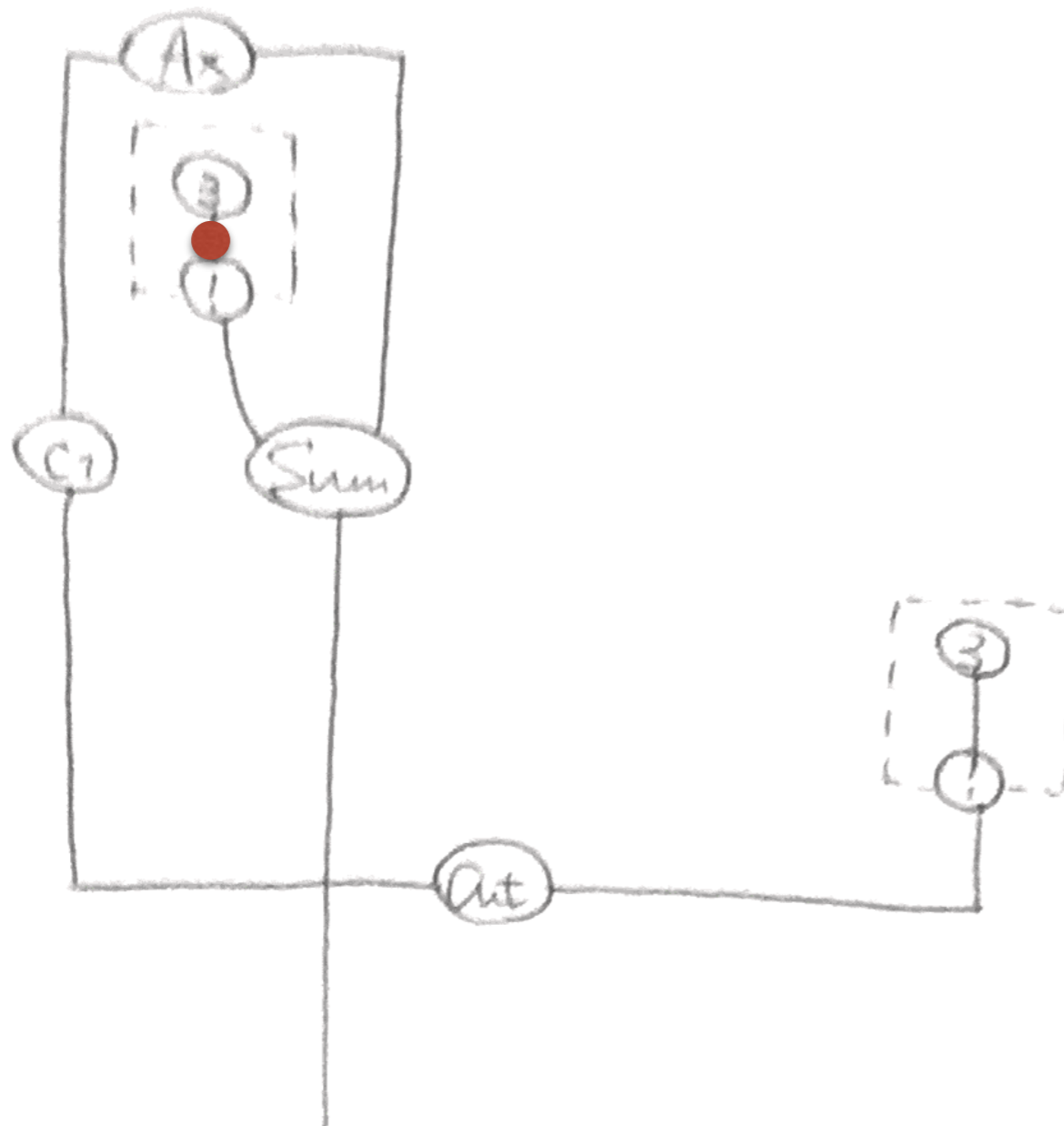
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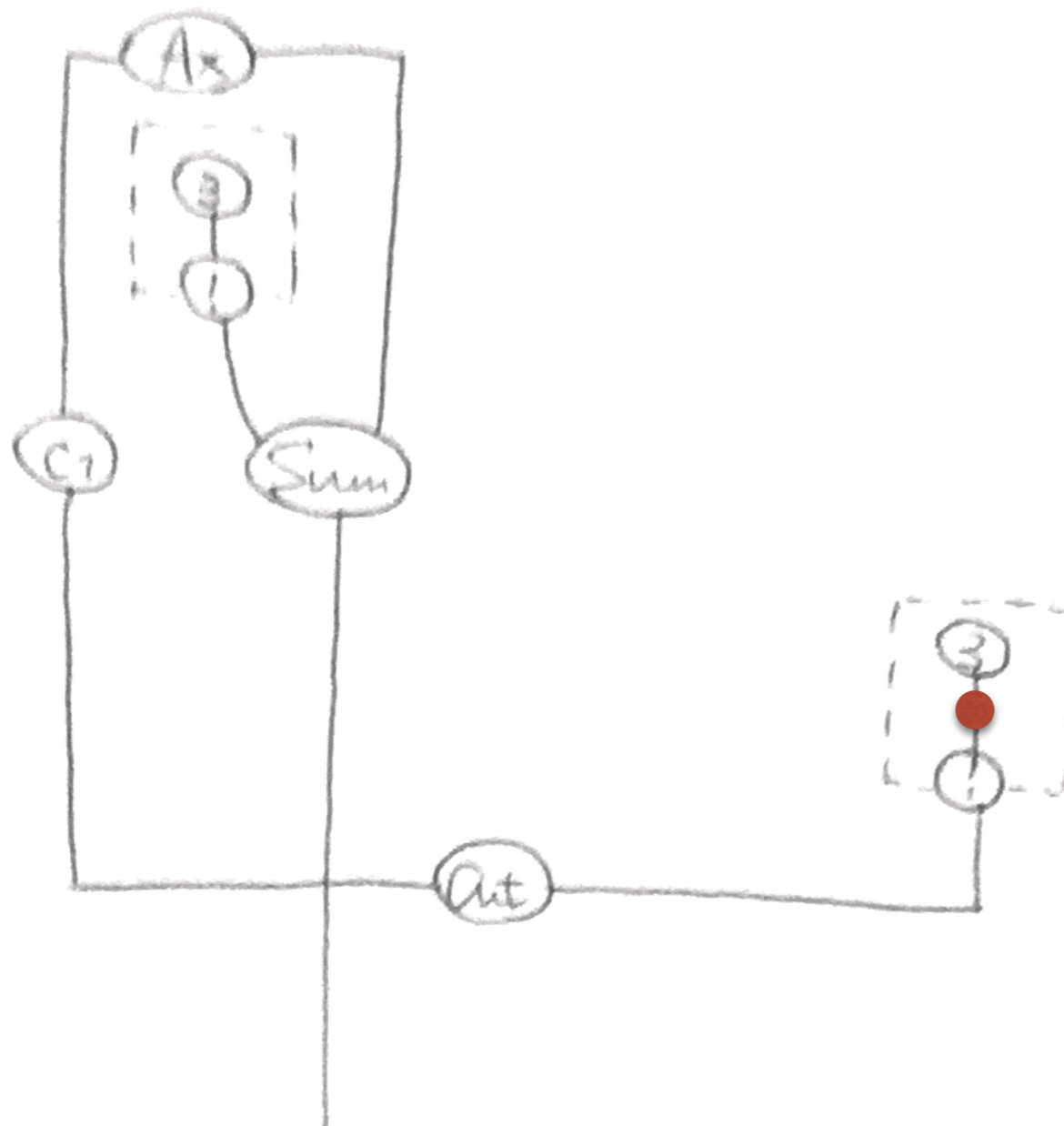
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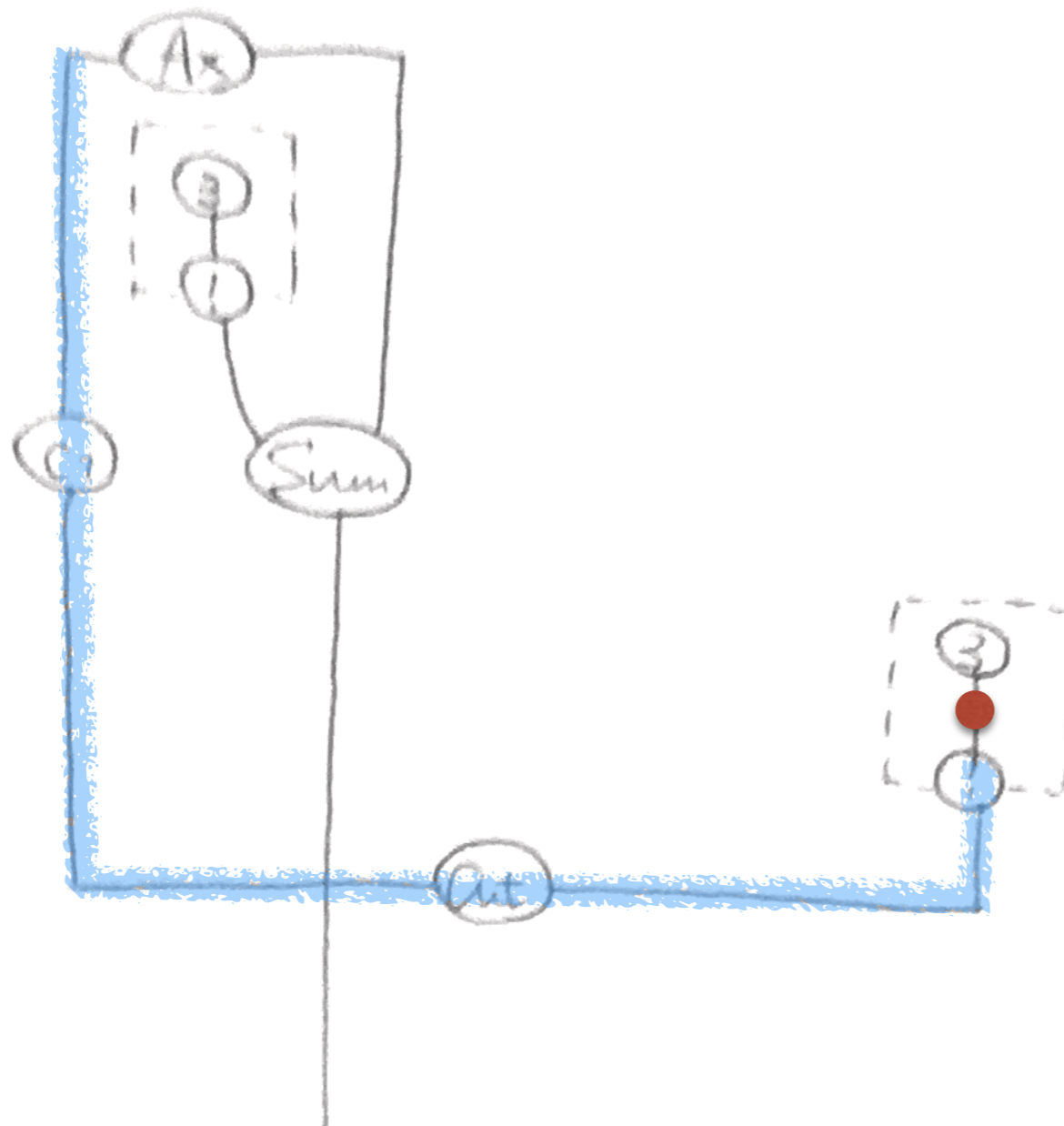
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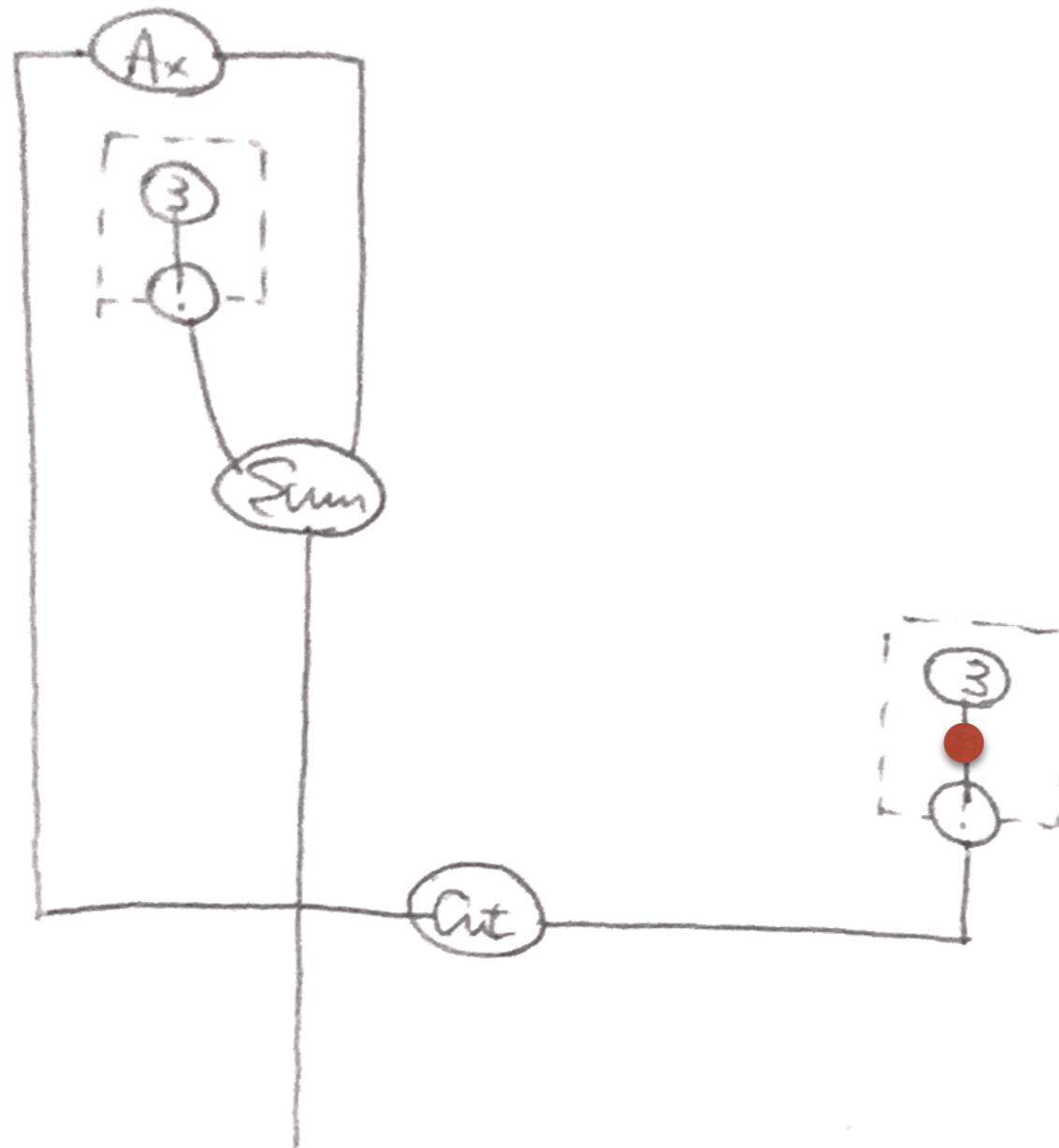
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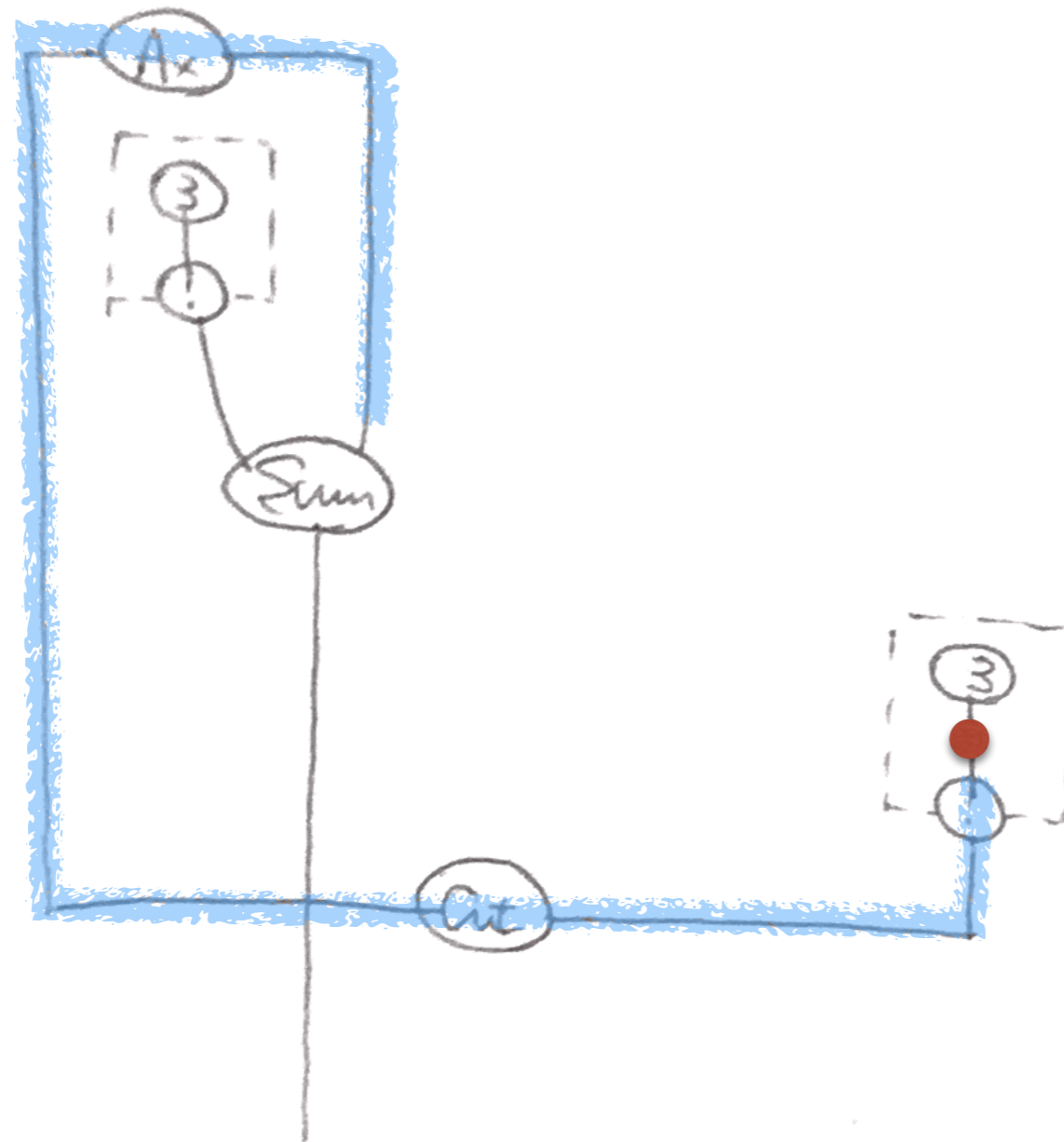
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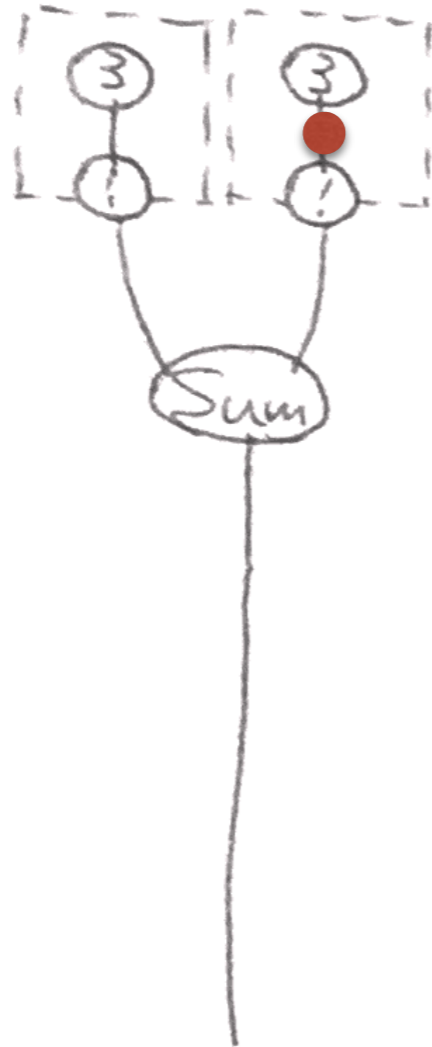
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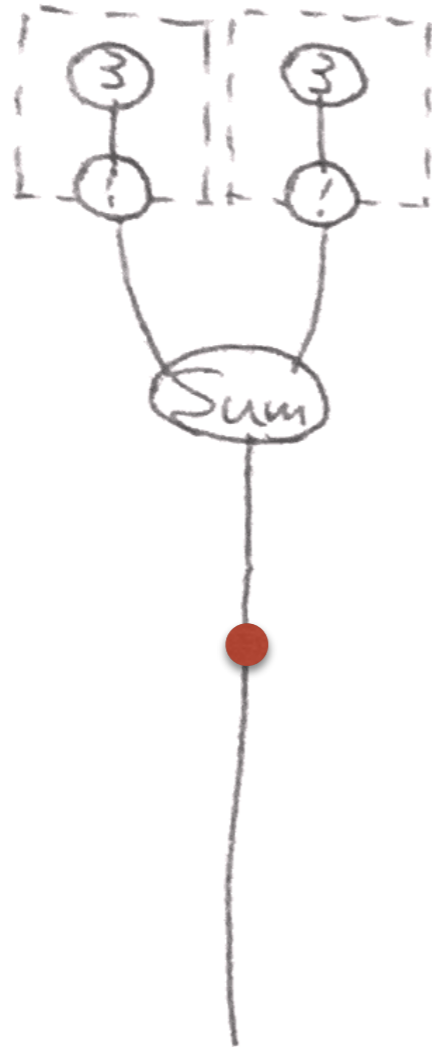
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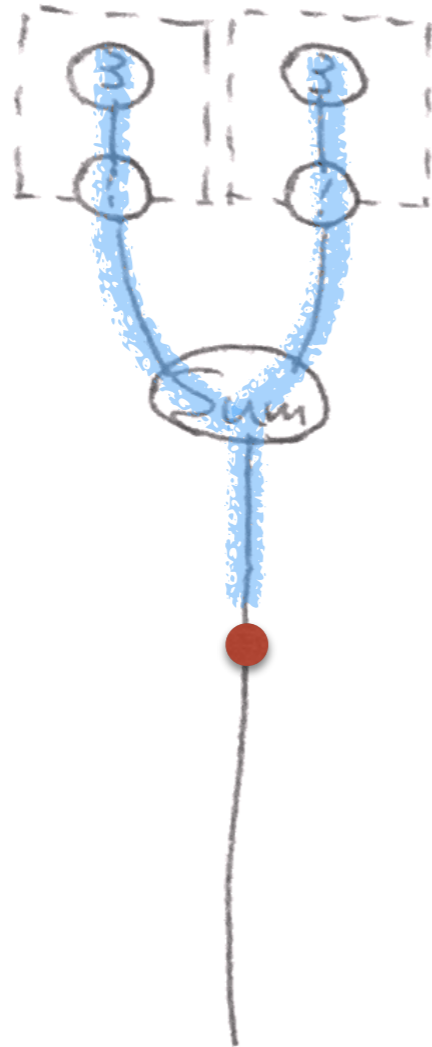
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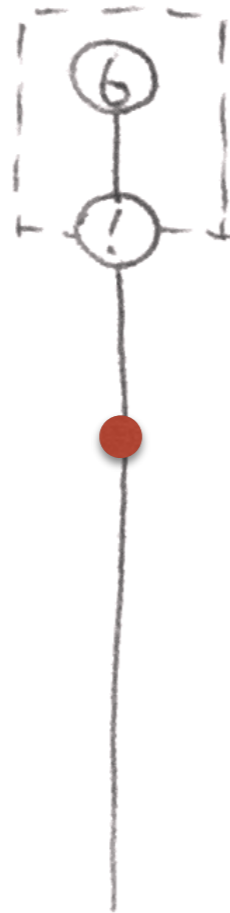
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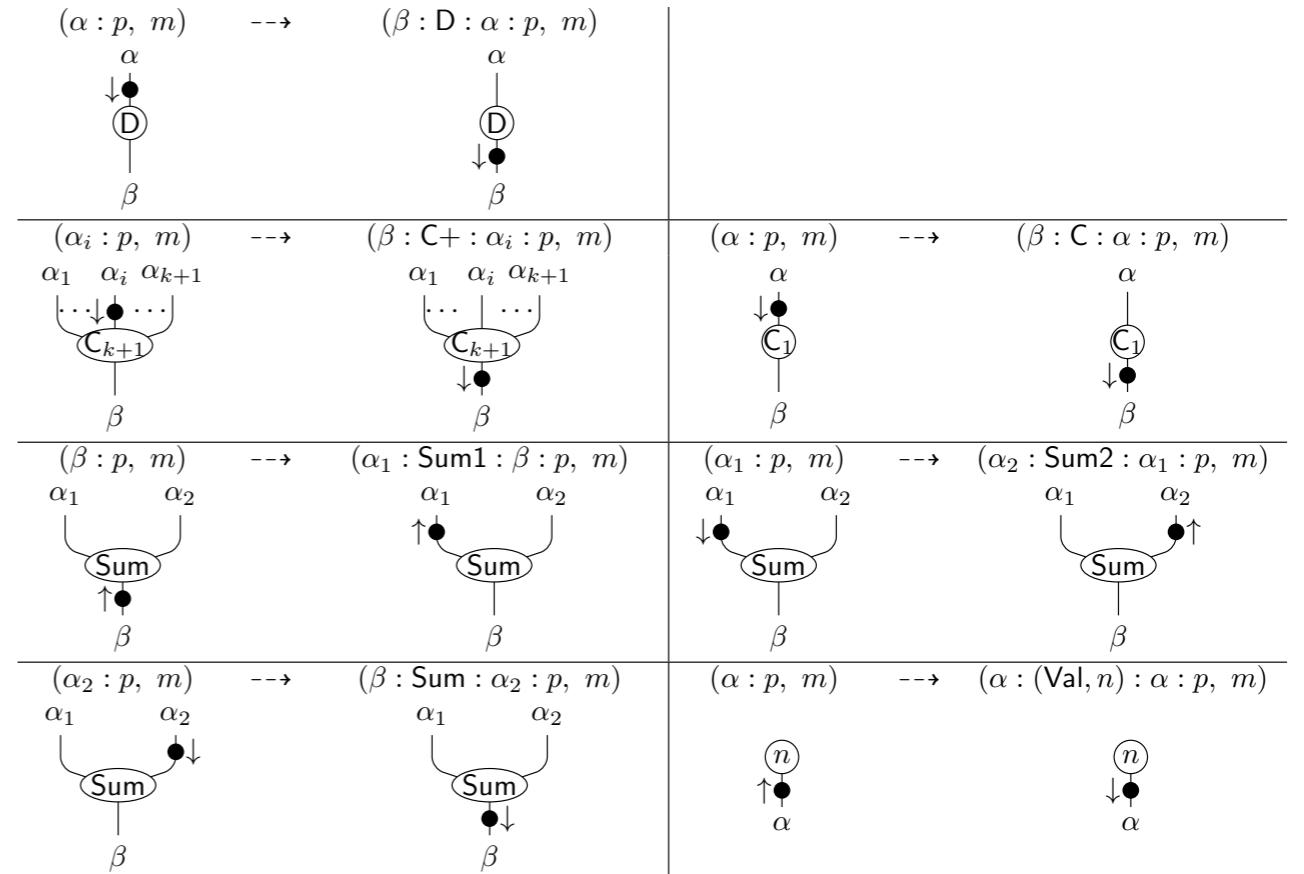
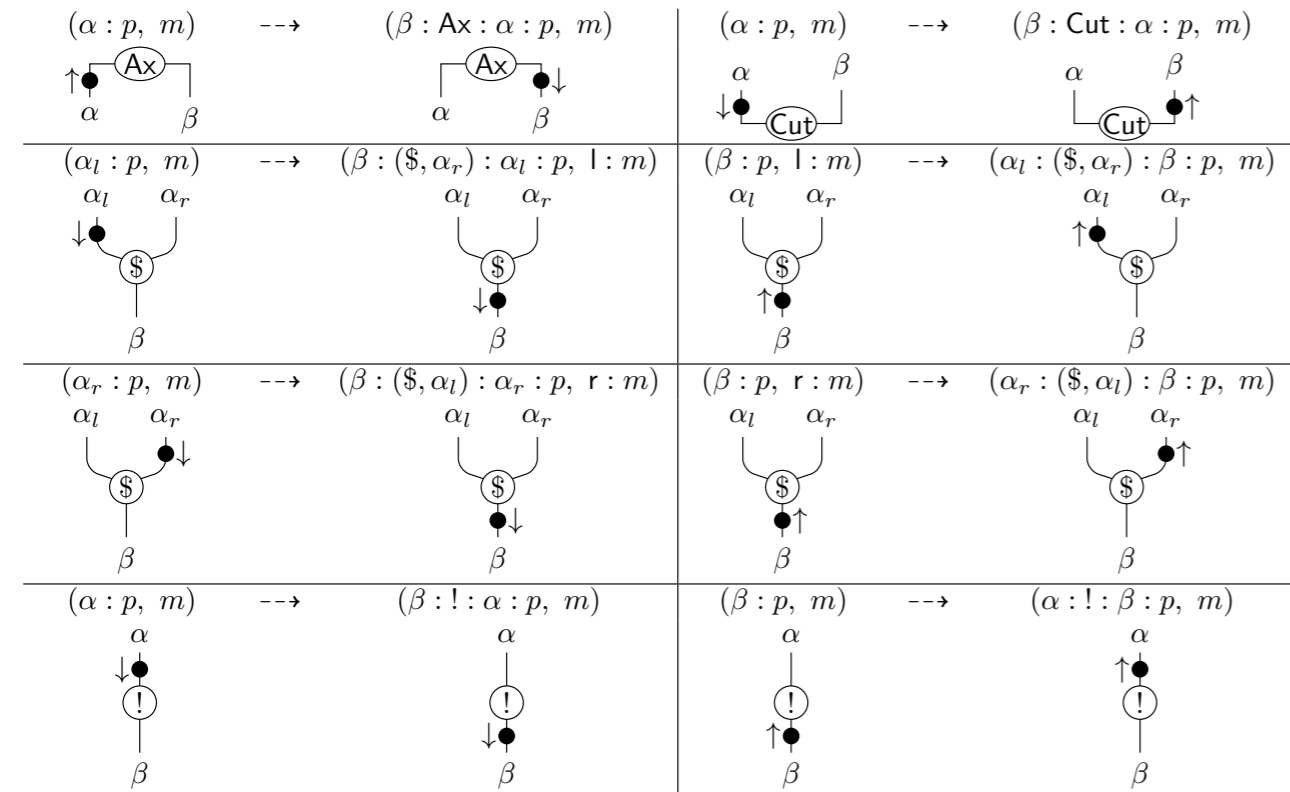
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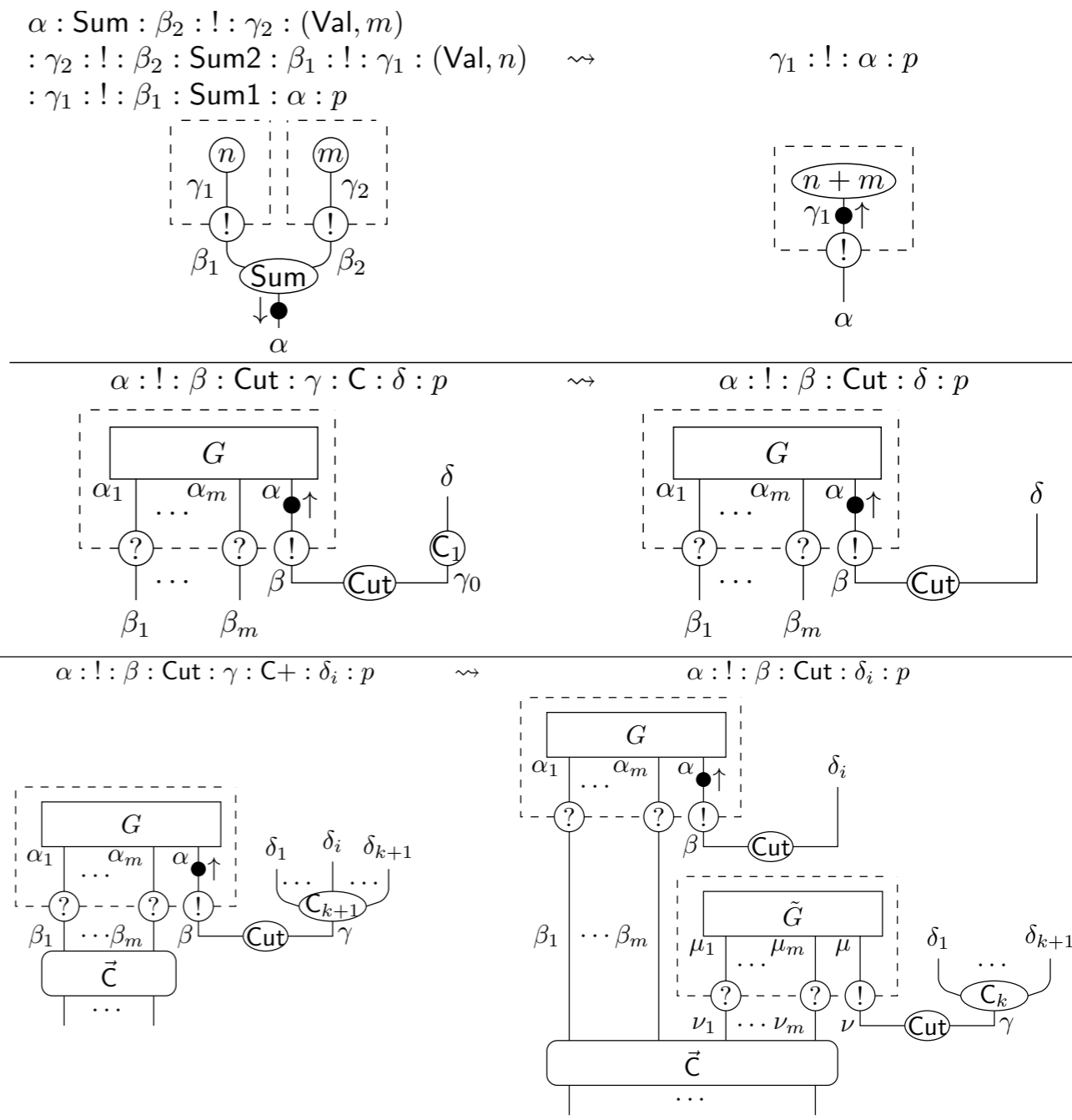
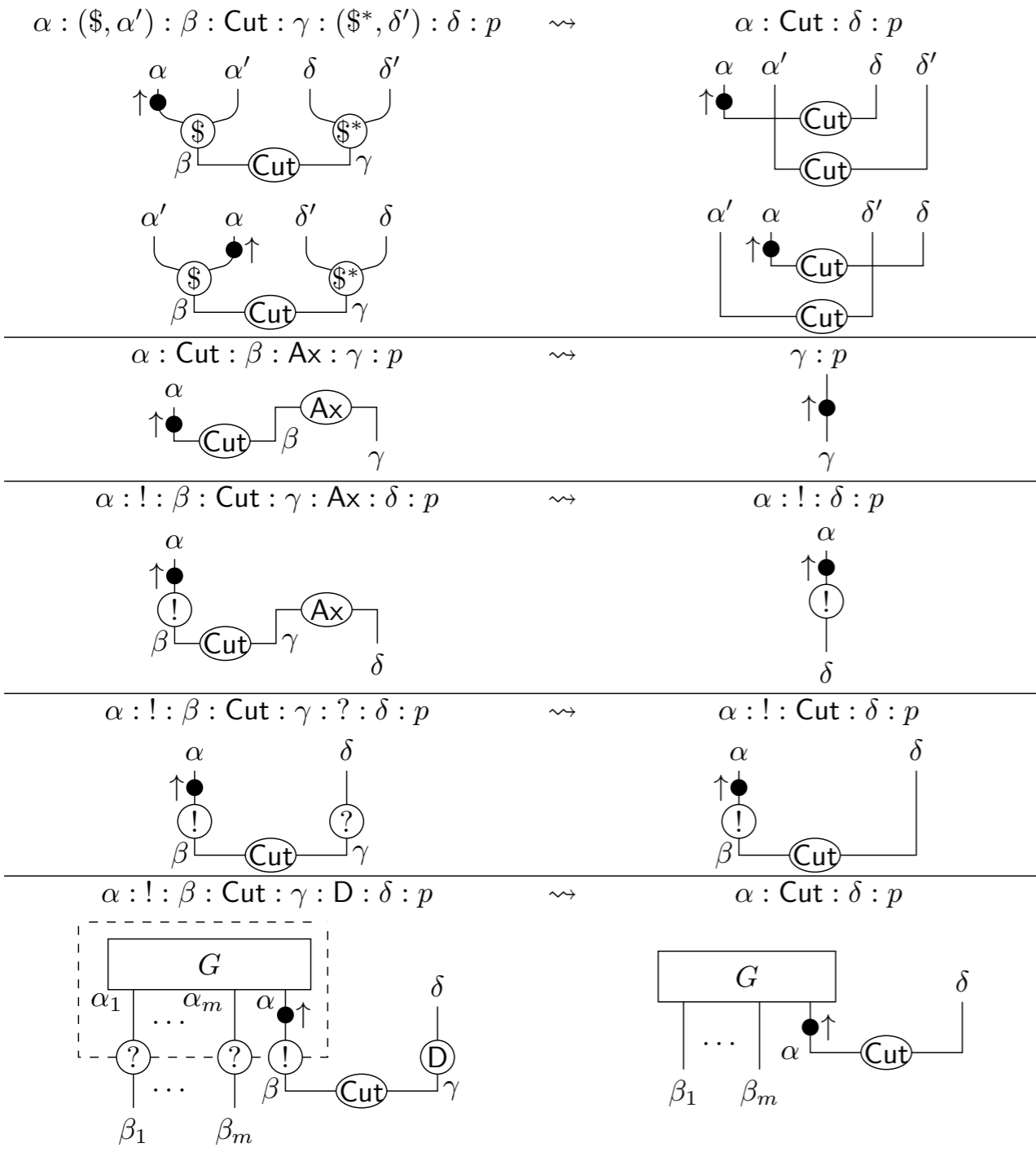
Dynamic Gol machine

“move” transition $((G, \ell_e, \ell_b), p, d, m) \dashrightarrow ((G, \ell_e, \ell_b), p', d', m')$



Dynamic Gol machine

“rewrite” transition $((G, \ell_e, \ell_b), p, d, m) \rightsquigarrow ((G', \ell'_e, \ell'_b), p', d', m)$



“Linear-cost” simulation

- Dynamic Gol machine $\rightarrow \xleftrightarrow{\text{def.}} \begin{cases} \rightsquigarrow & \text{if a rewrite is possible} \\ \dashrightarrow & \text{if no rewrite but a move is possible} \end{cases}$
- Call-by-need storeless abstract machine [Danvy & Zerny '13]

$$\begin{array}{ll}
 \langle V, E \rangle_t \rightarrow_{\text{need}} \langle E, V \rangle_c & \langle [], A[V] \rangle_c \rightarrow_{\text{need}} \langle A[V] \rangle_a \\
 \langle M N, E \rangle_t \rightarrow_{\text{need}} \langle M, E[[] N] \rangle_t & \langle E[[] N], A[\lambda x. M] \rangle_c \rightarrow_{\text{need}} \langle M[x'/x], E[A[\text{let } x' = N \text{ in } []]] \rangle_t \\
 \langle M + N, E \rangle_t \rightarrow_{\text{need}} \langle M, E[[] + N] \rangle_t & \langle E[[] + N], A[\underline{n}] \rangle_c \rightarrow_{\text{need}} \langle N, E[A[\underline{n} + []]] \rangle_t \\
 \langle x, E_1[\text{let } x = N \text{ in } E_2] \rangle_t \rightarrow_{\text{need}} \langle N, E_1[\text{let } x := [] \text{ in } E_2[x]] \rangle_t & \langle E[\underline{n} + []], A[\underline{m}] \rangle_c \rightarrow_{\text{need}} \langle E, A[\underline{n} + \underline{m}] \rangle_c \\
 & \langle E[\text{let } x = N \text{ in } []], A[V] \rangle_c \rightarrow_{\text{need}} \langle E, \text{let } x = N \text{ in } A[V] \rangle_c \\
 & \langle E[\text{let } x := [] \text{ in } E'[x]], A[V] \rangle_c \rightarrow_{\text{need}} \langle E[A[\text{let } x = V \text{ in } E']], V \rangle_c
 \end{array}$$

Theorem A.1. There exists a binary relation \ddagger that satisfies

$$\begin{aligned}
 c \xrightarrow{k}_{\text{need}} c' \wedge c \ddagger (G, p, d, m) \\
 \implies (G, p, d, m) \xrightarrow{\mathcal{O}(k)} \dots \rightarrow (G', p', d', m') \wedge c' \ddagger (G', p', d', m') .
 \end{aligned}$$

“Linear-cost” simulation

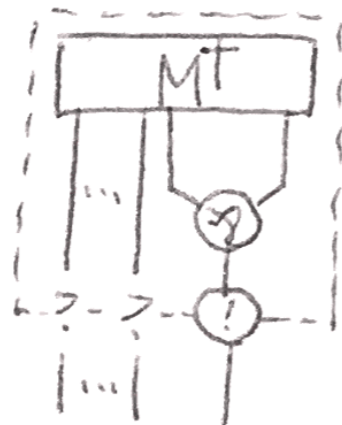
Theorem A.1. There exists a binary relation \ddagger that satisfies

$$c \xrightarrow{k}_{\text{need}} c' \wedge c \ddagger (G, p, d, m)$$

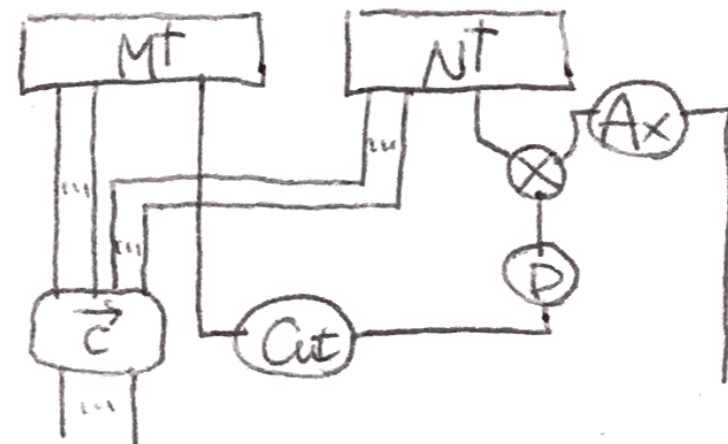
$$\implies (G, p, d, m) \xrightarrow{\mathcal{O}(k)} \dots \rightarrow (G', p', d', m') \wedge c' \ddagger (G', p', d', m') .$$



$(\lambda x. M)^\dagger :=$



$(M N)^\dagger :=$



Gol machine [Danos & Regnier '99] [Mackie '95]

call-by-name

call-by-need

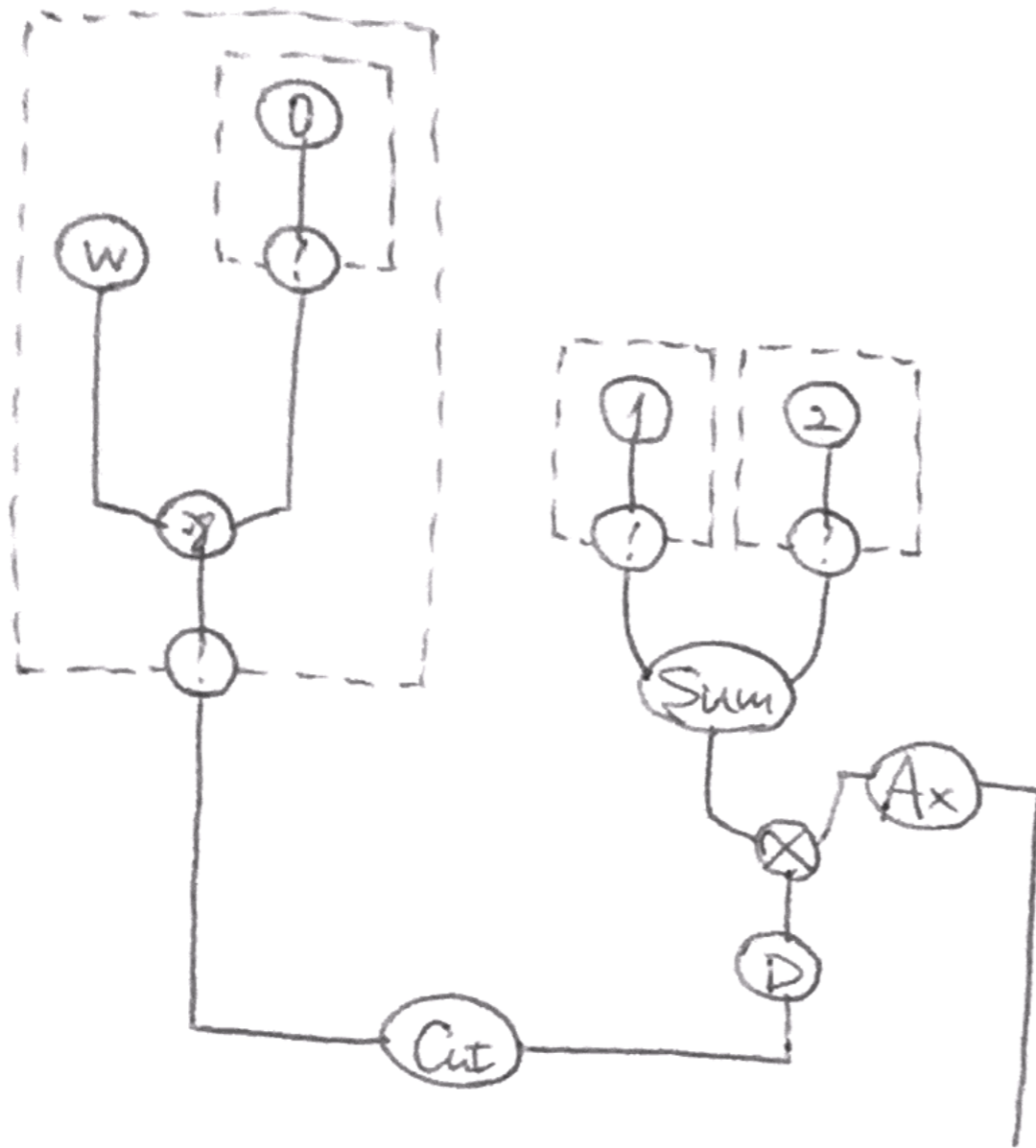
call-by-value

effects

	avoid re-evaluation	force evaluation of arguments	track each copy of terms
CPS transform.	?	✓	? Schöpp
memory	△		✓ Hoshino+
parallelism & sync.	△	✓	Dal Lago+
dynamic jump	✓	✓	Fernández+
dynamic rewrite	✓		☺
checkpoint		✓	

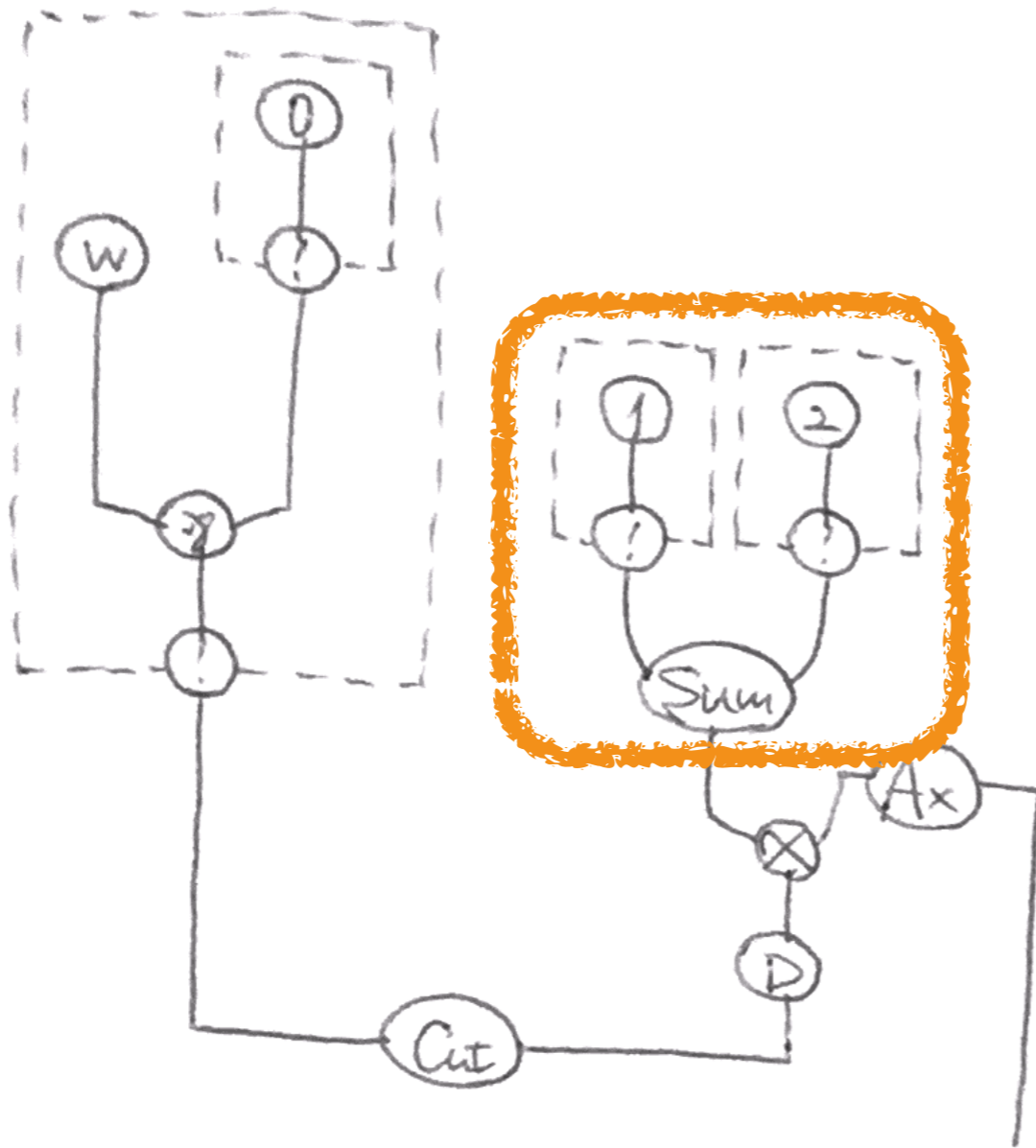
Force evaluation of arguments

$(\lambda x. 0) (1 + 2)$



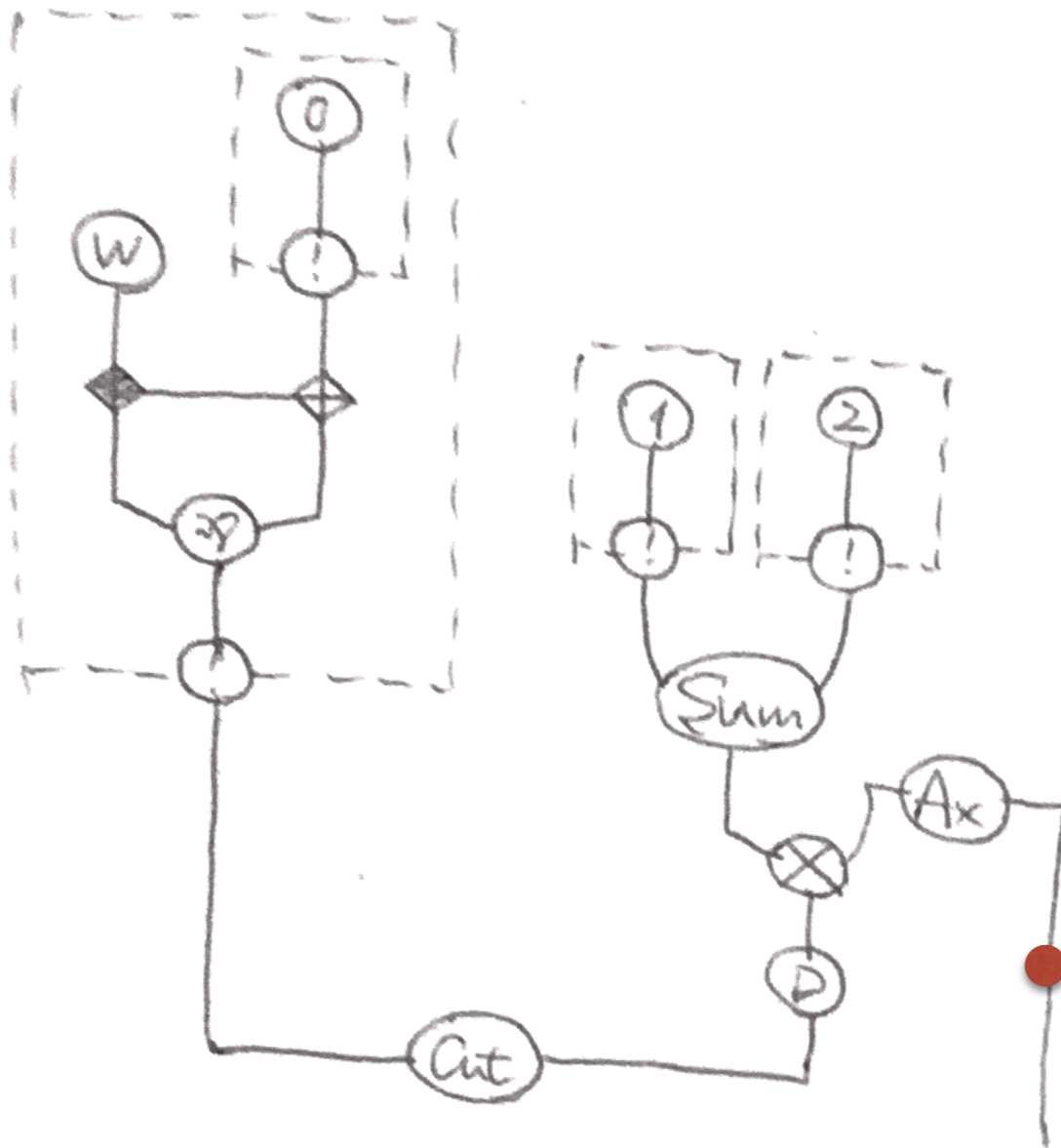
Force evaluation of arguments

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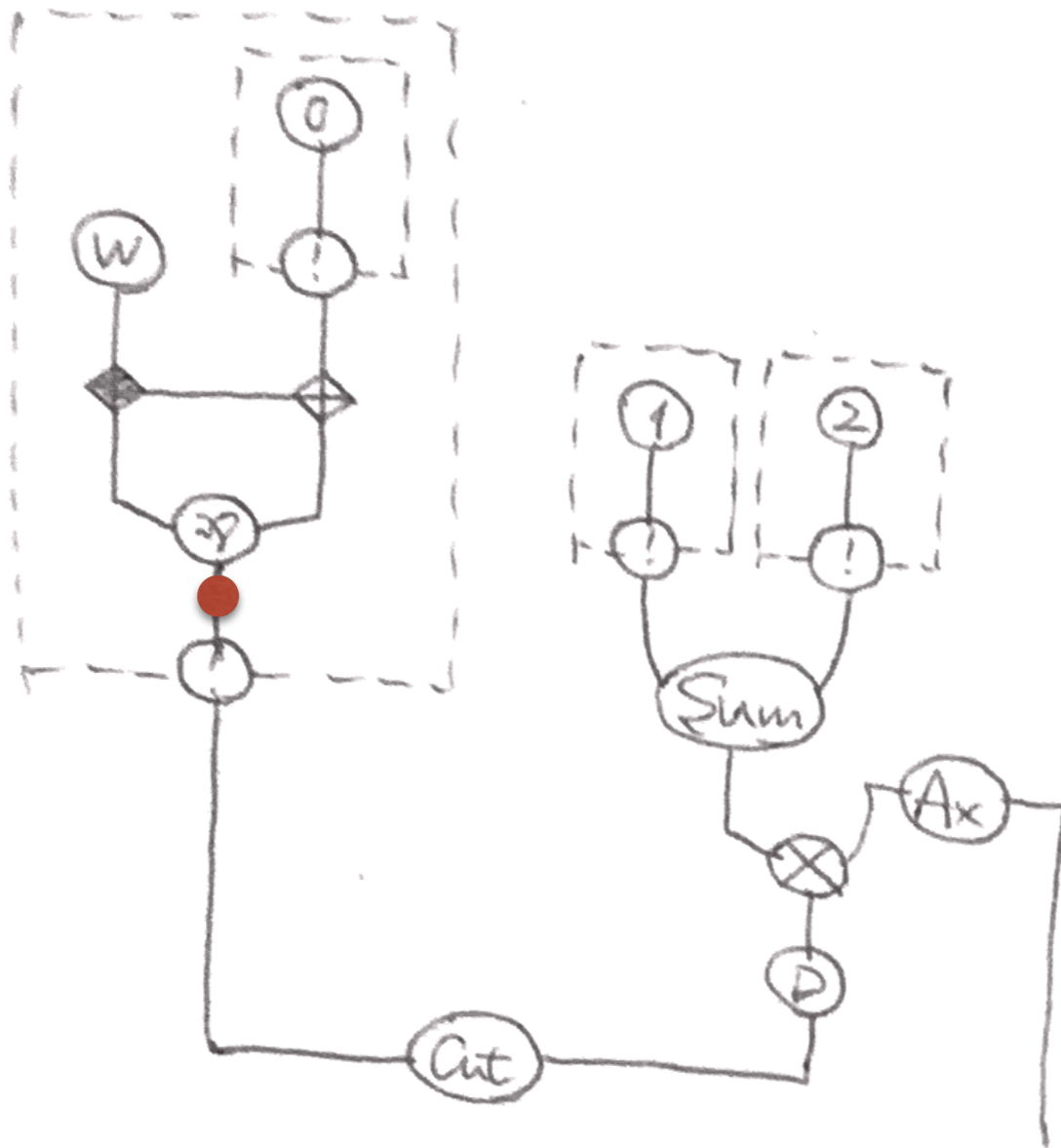
Force evaluation of arguments: checkpoint

$(\lambda x. 0) (1 + 2)$



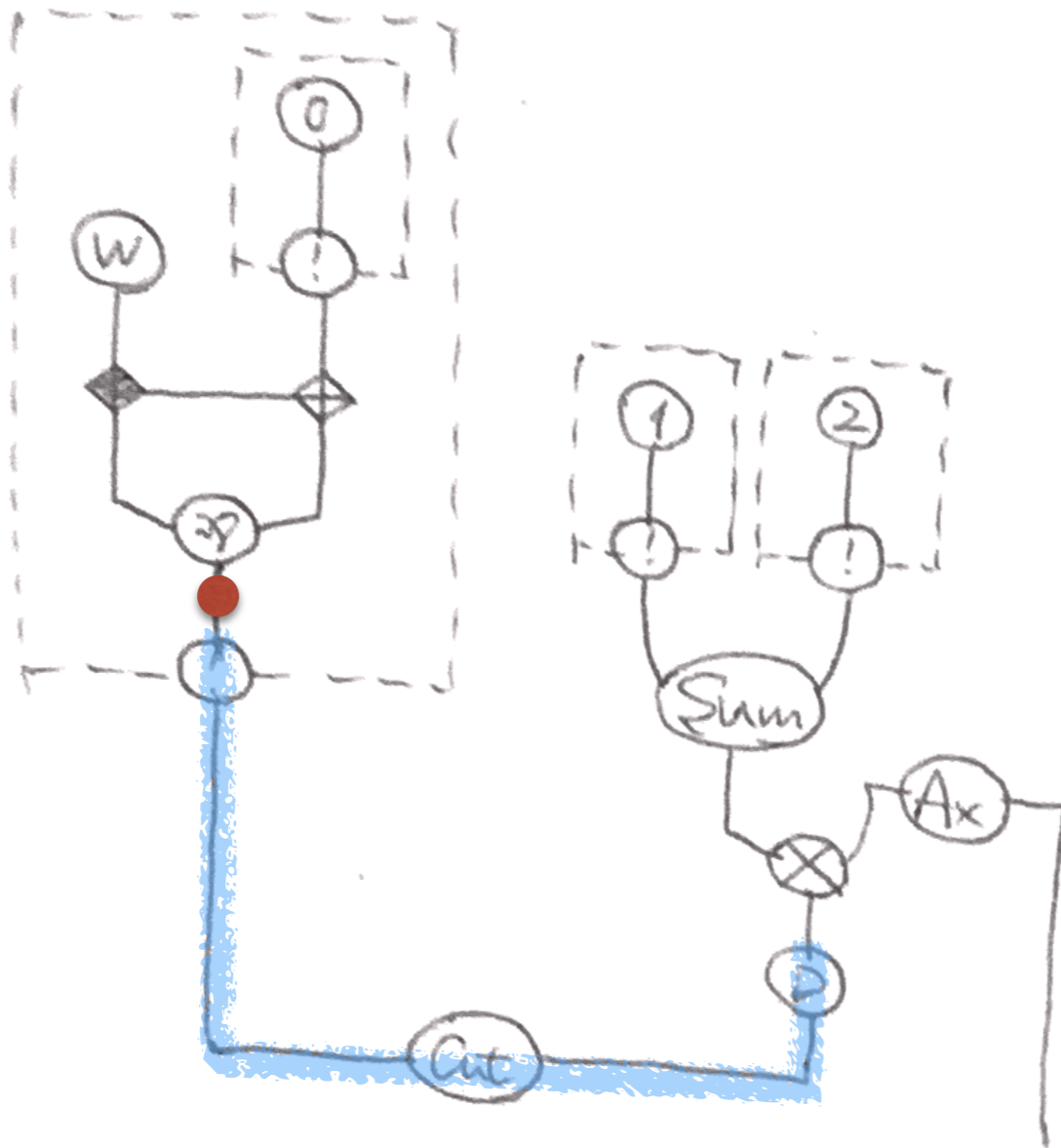
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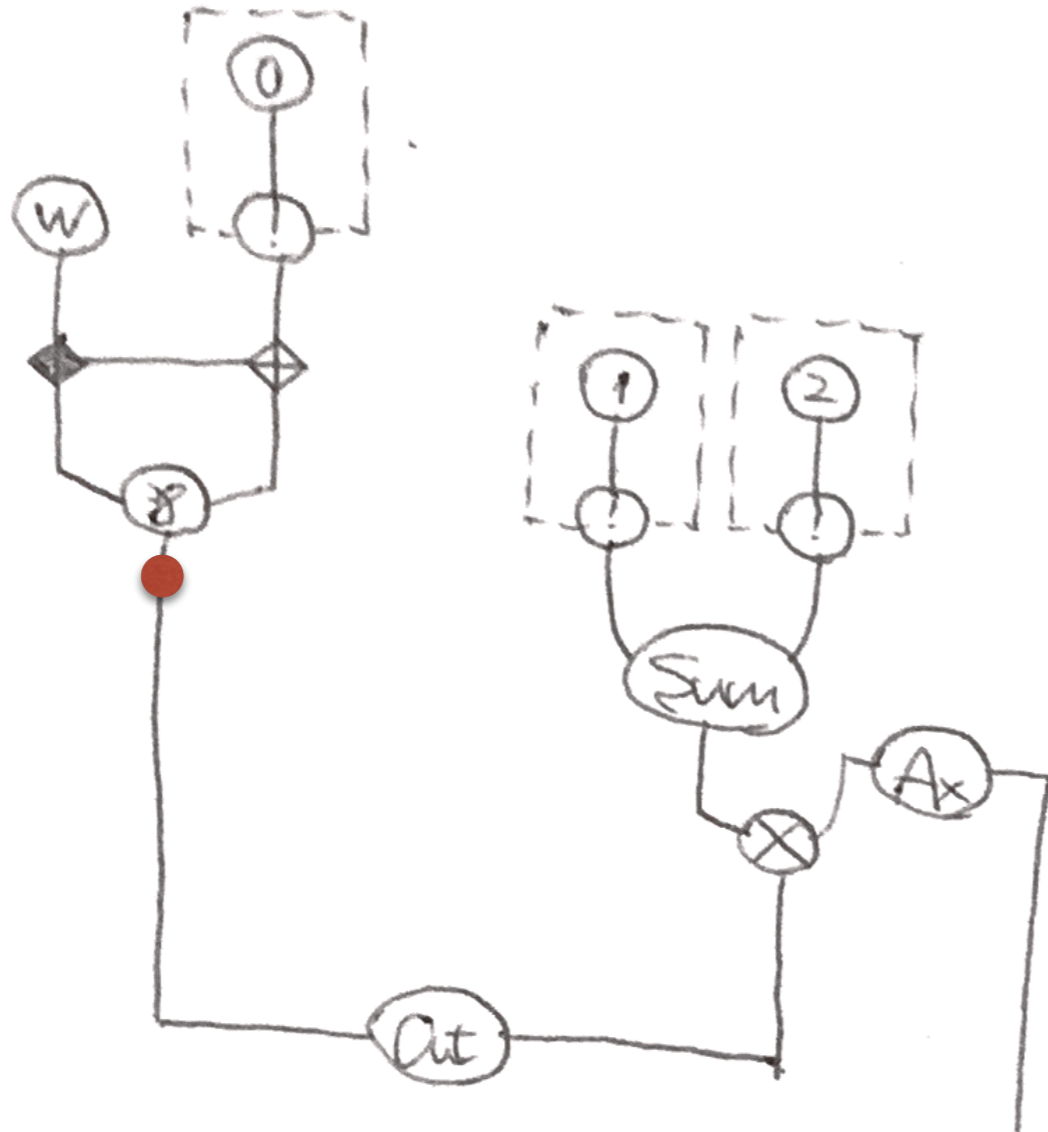
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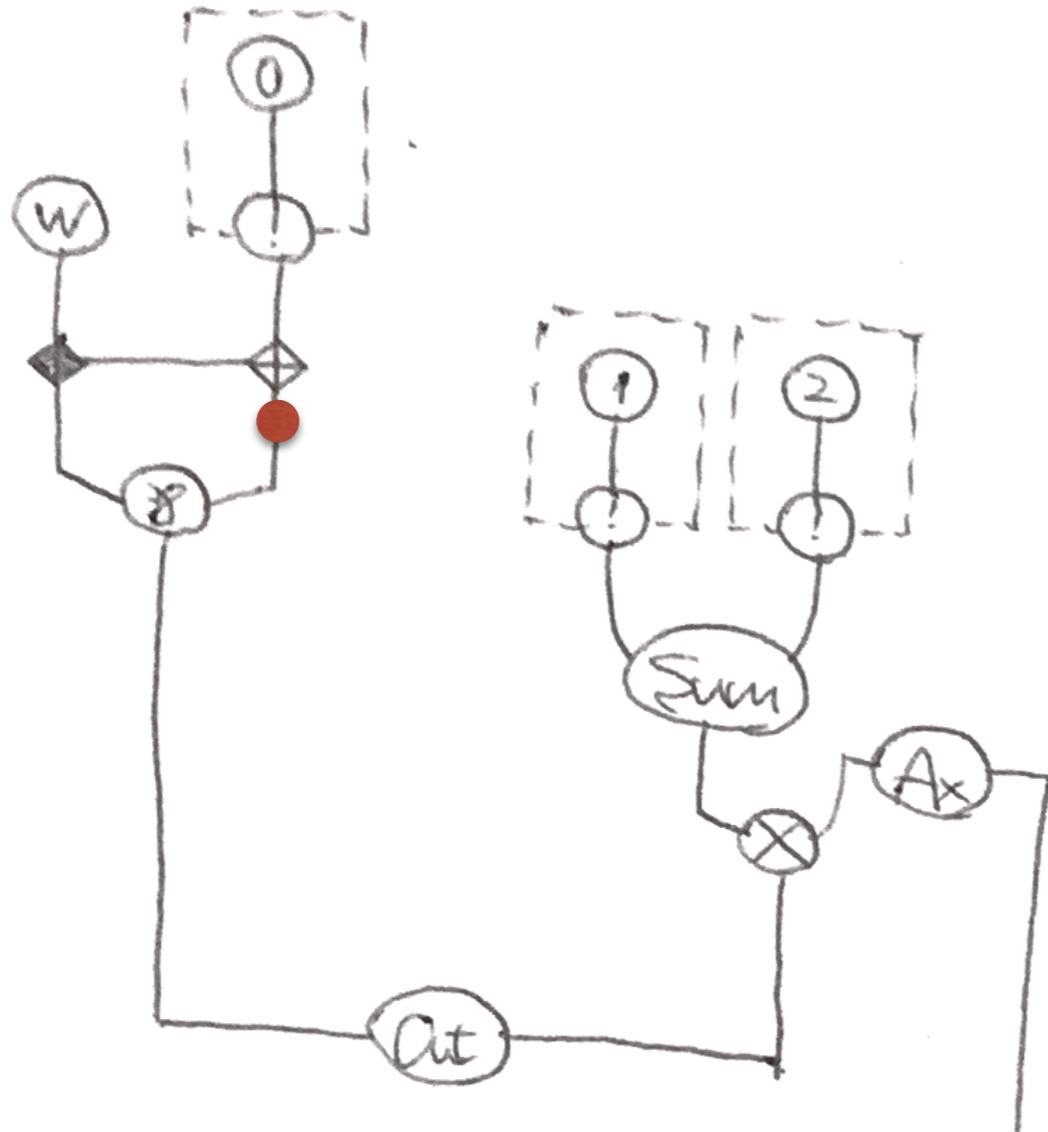
Force evaluation of arguments: checkpoint

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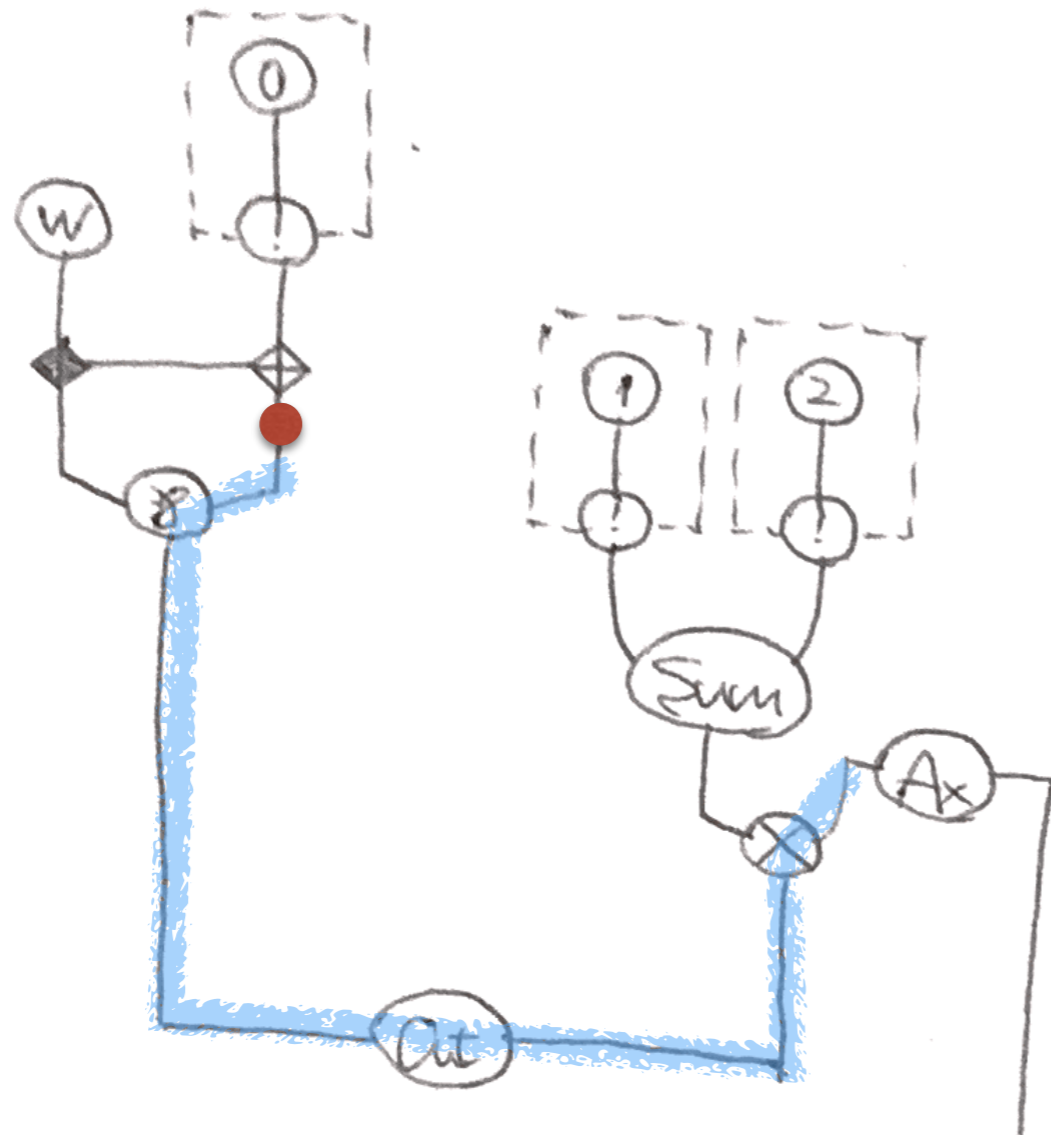
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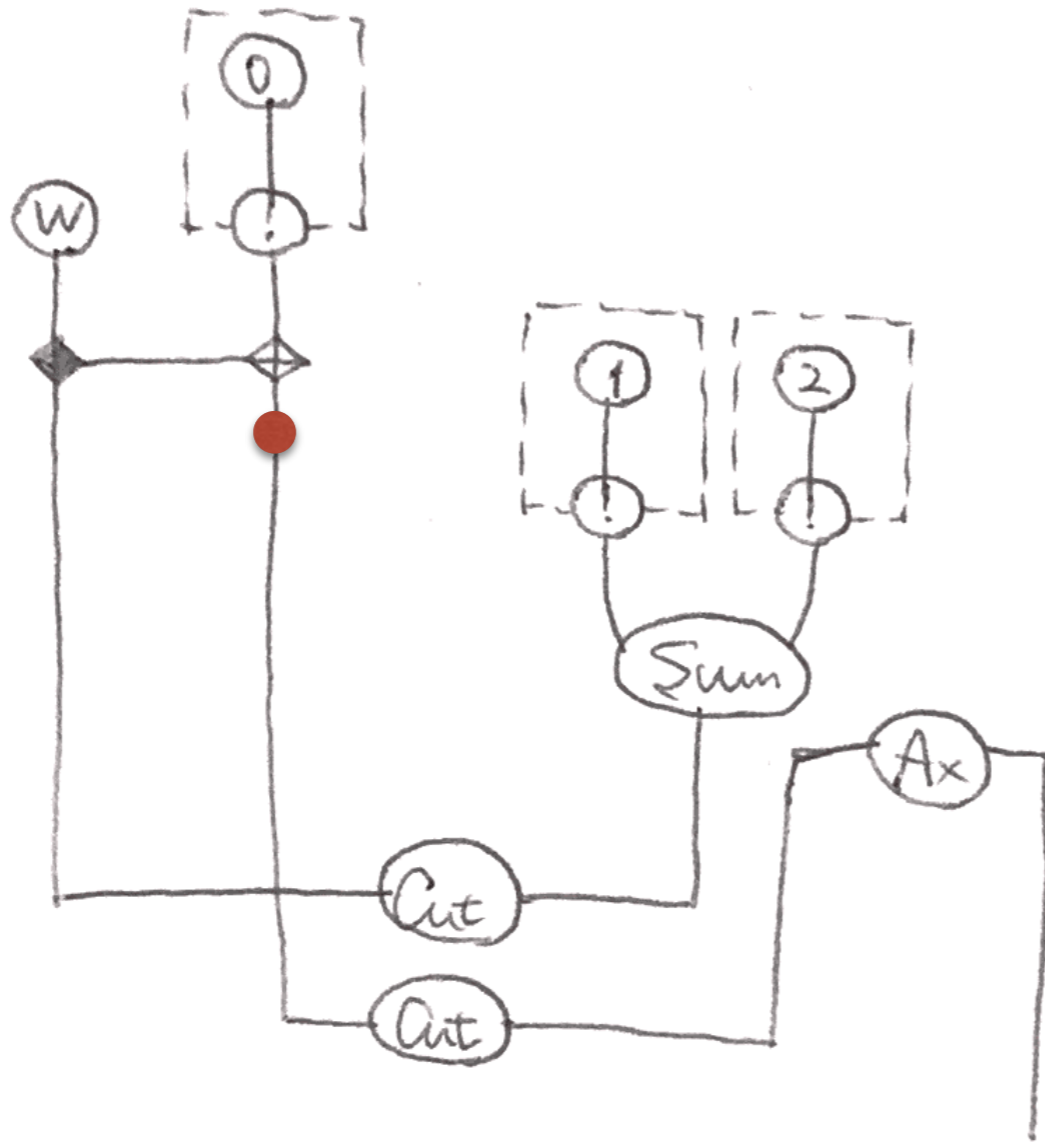
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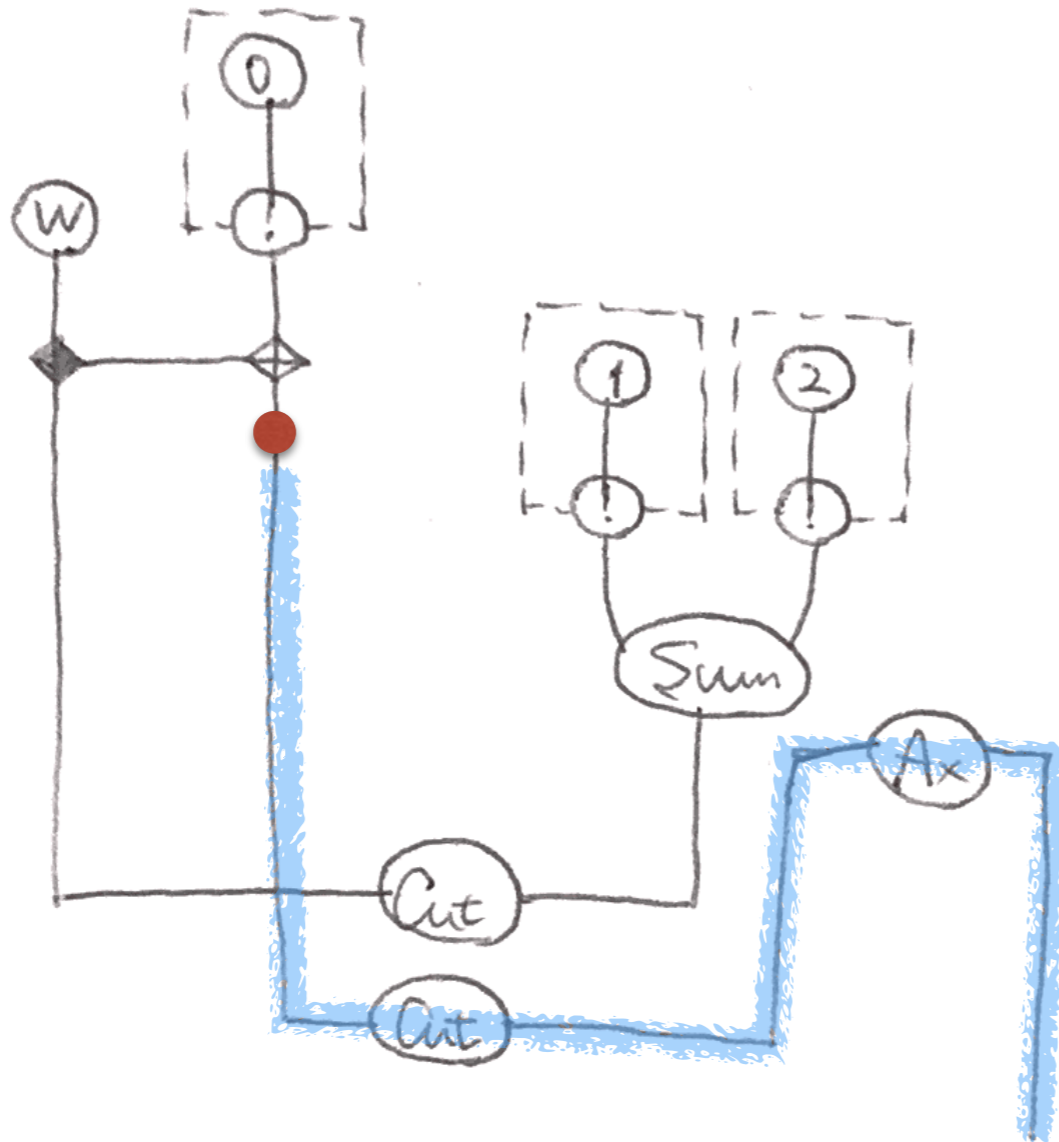
Force evaluation of arguments: checkpoint

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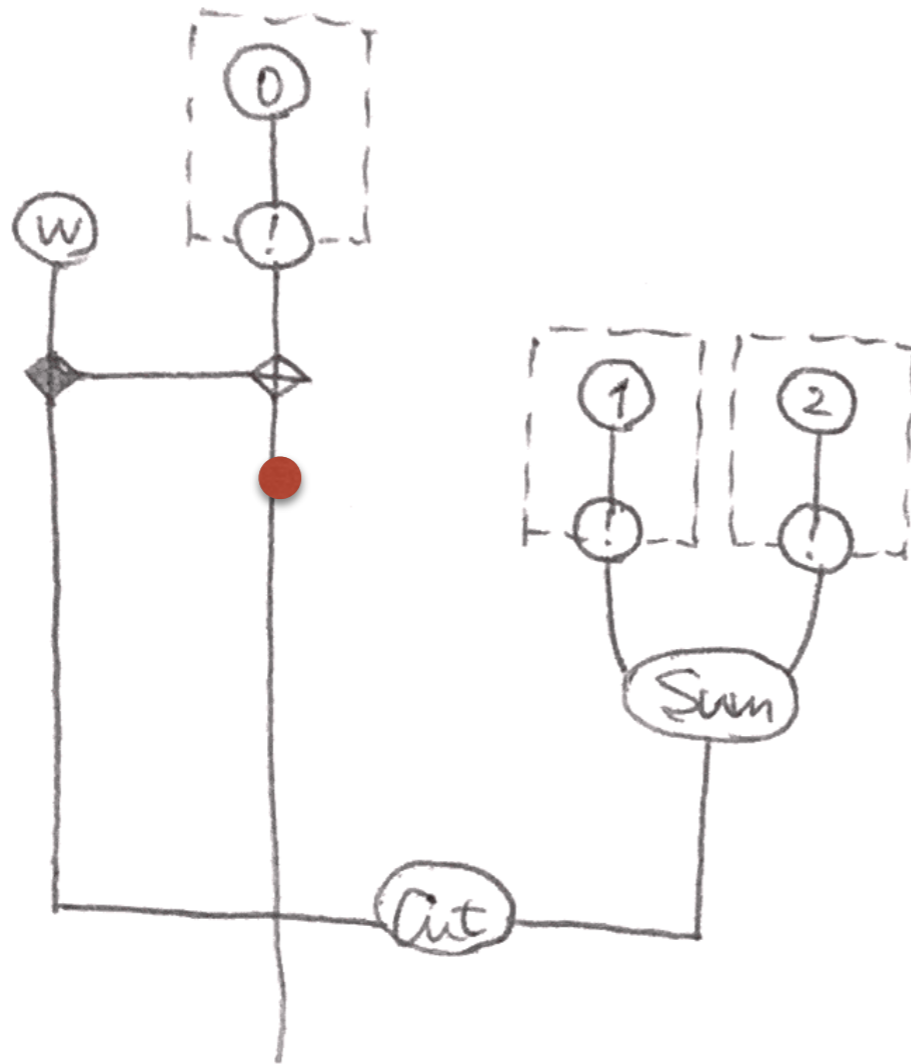
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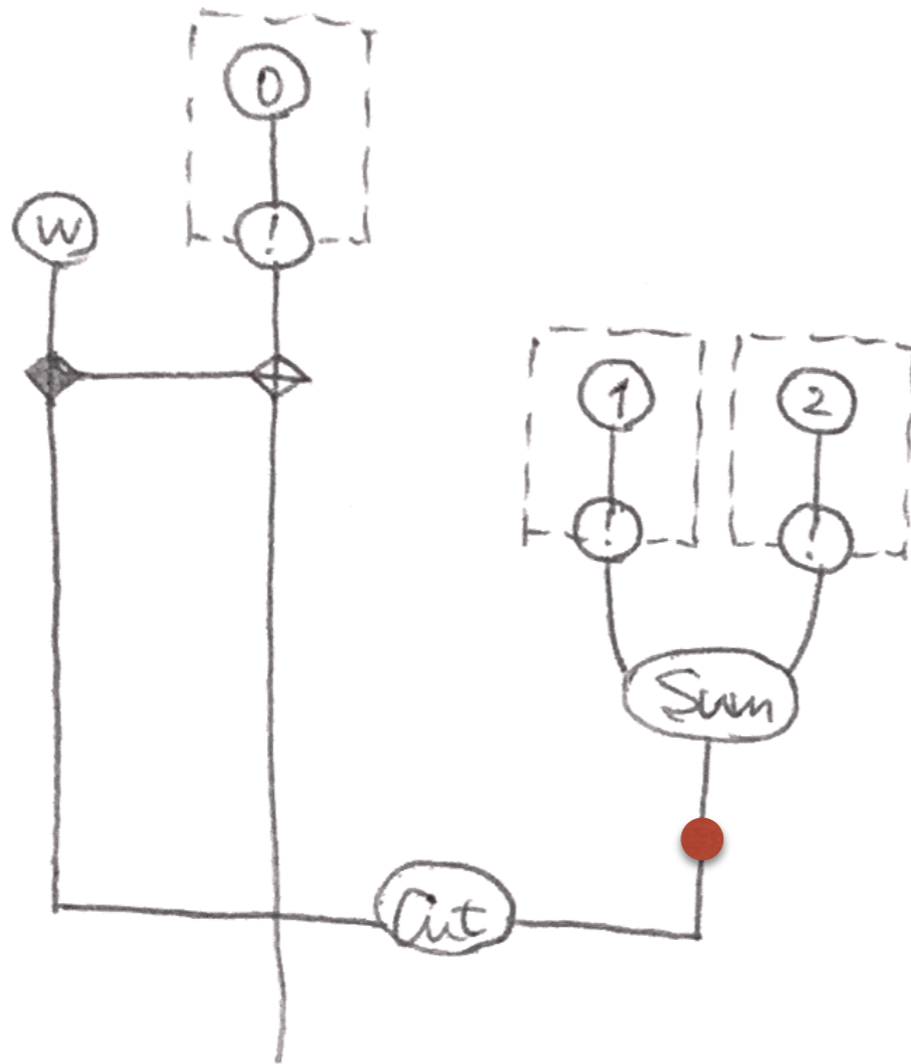
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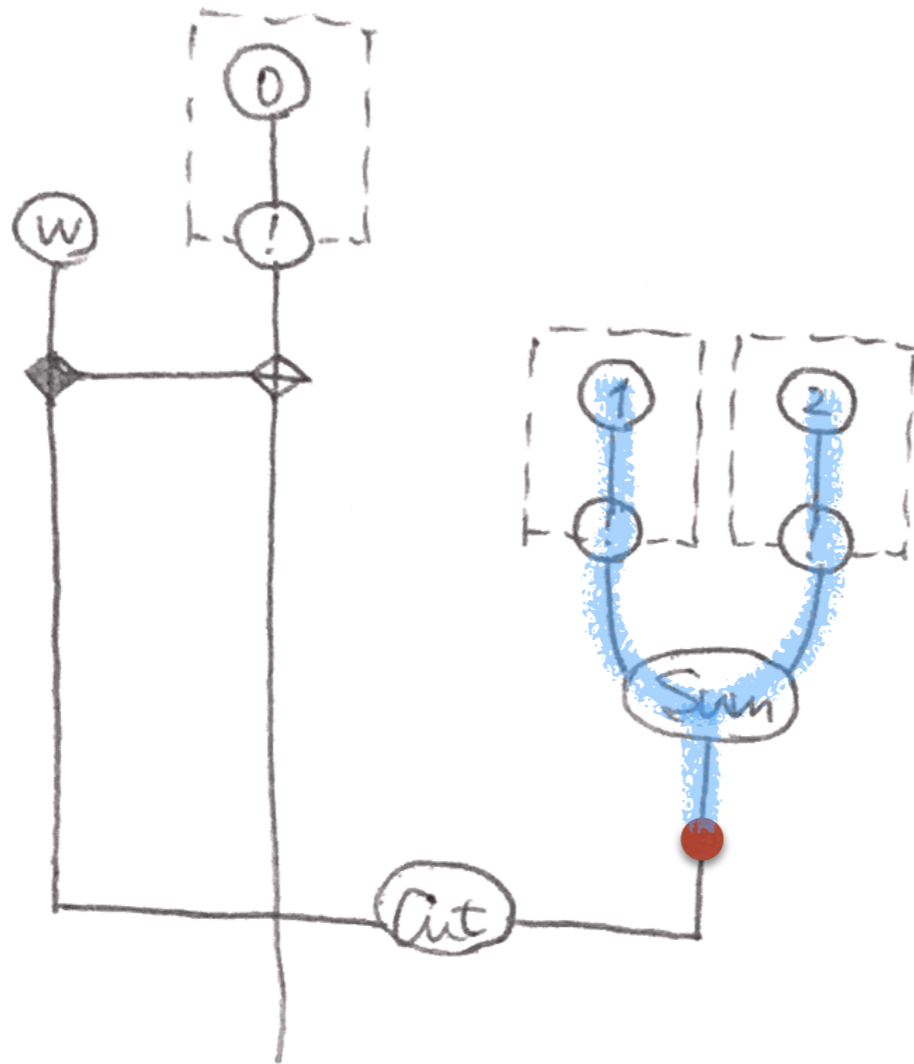
Force evaluation of arguments: checkpoint

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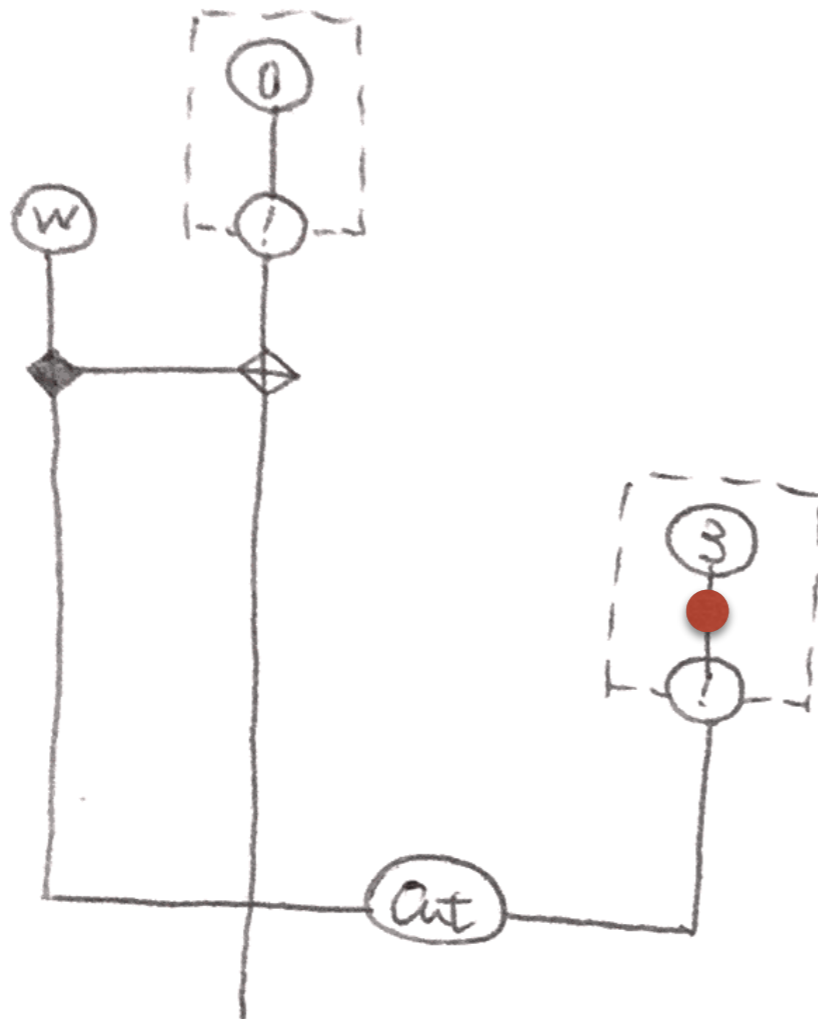
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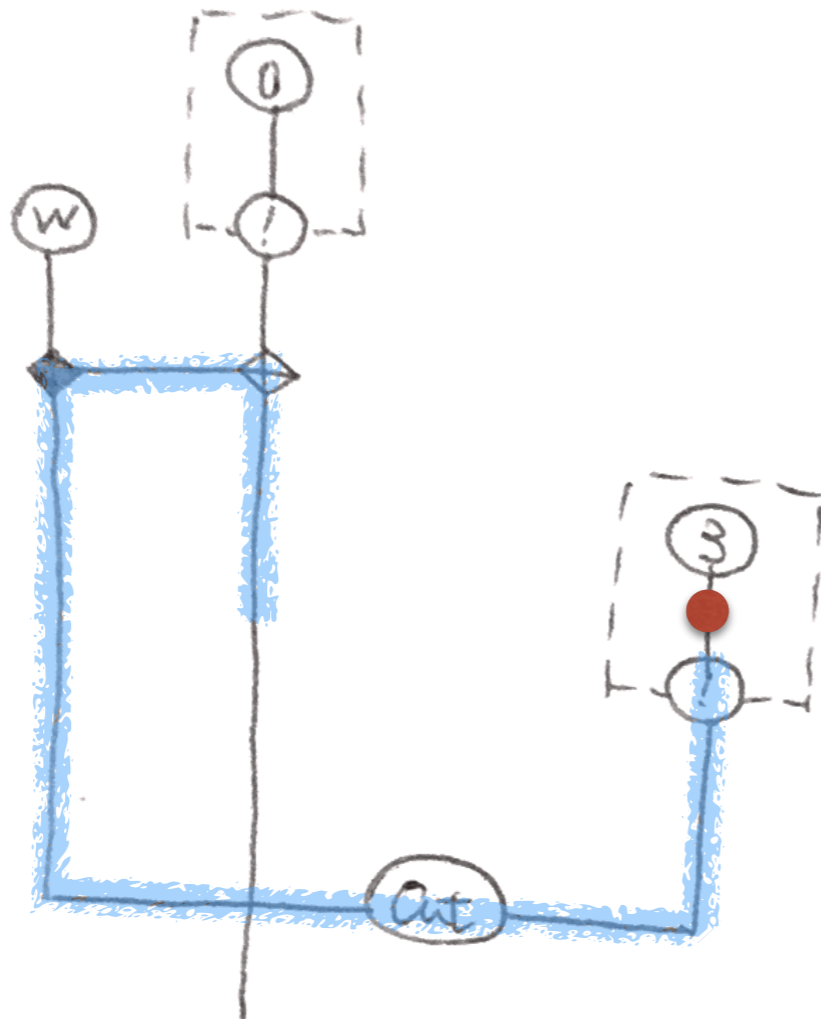
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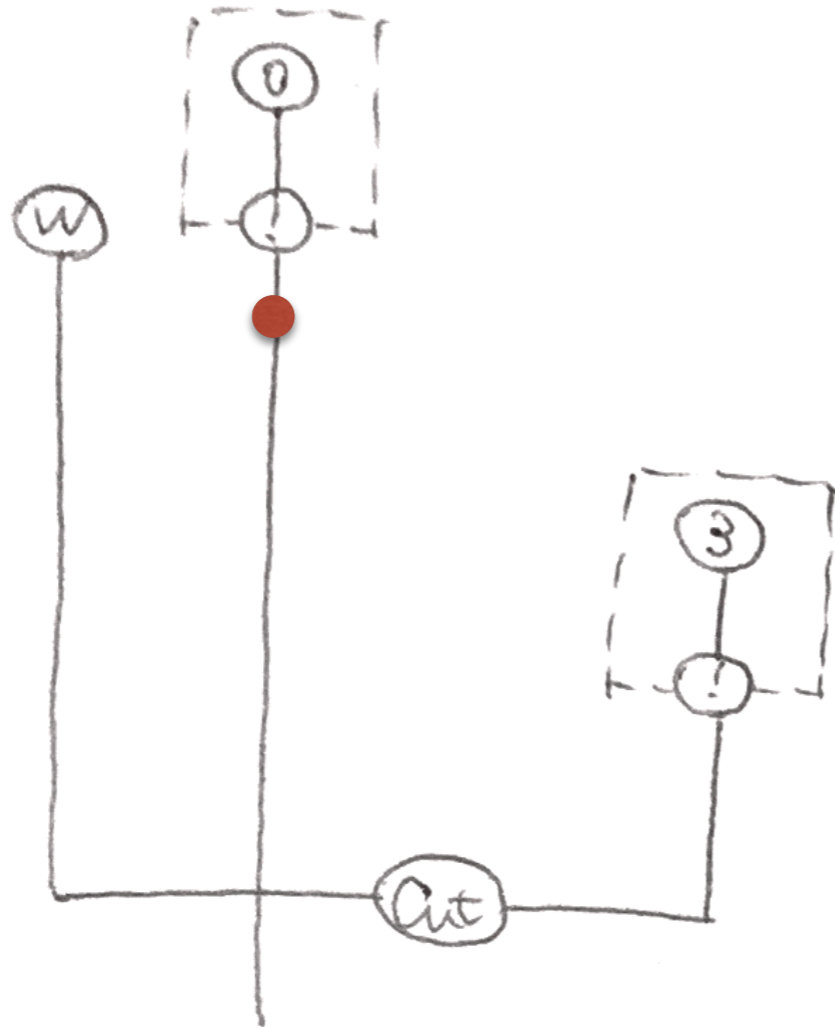
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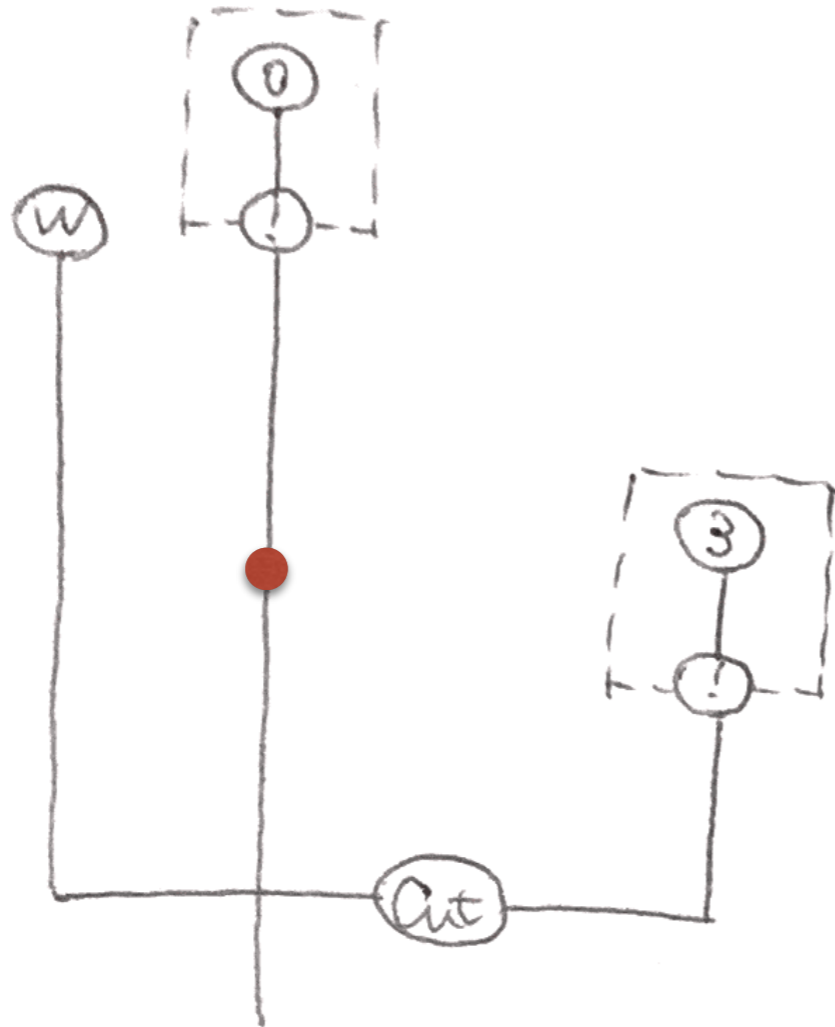
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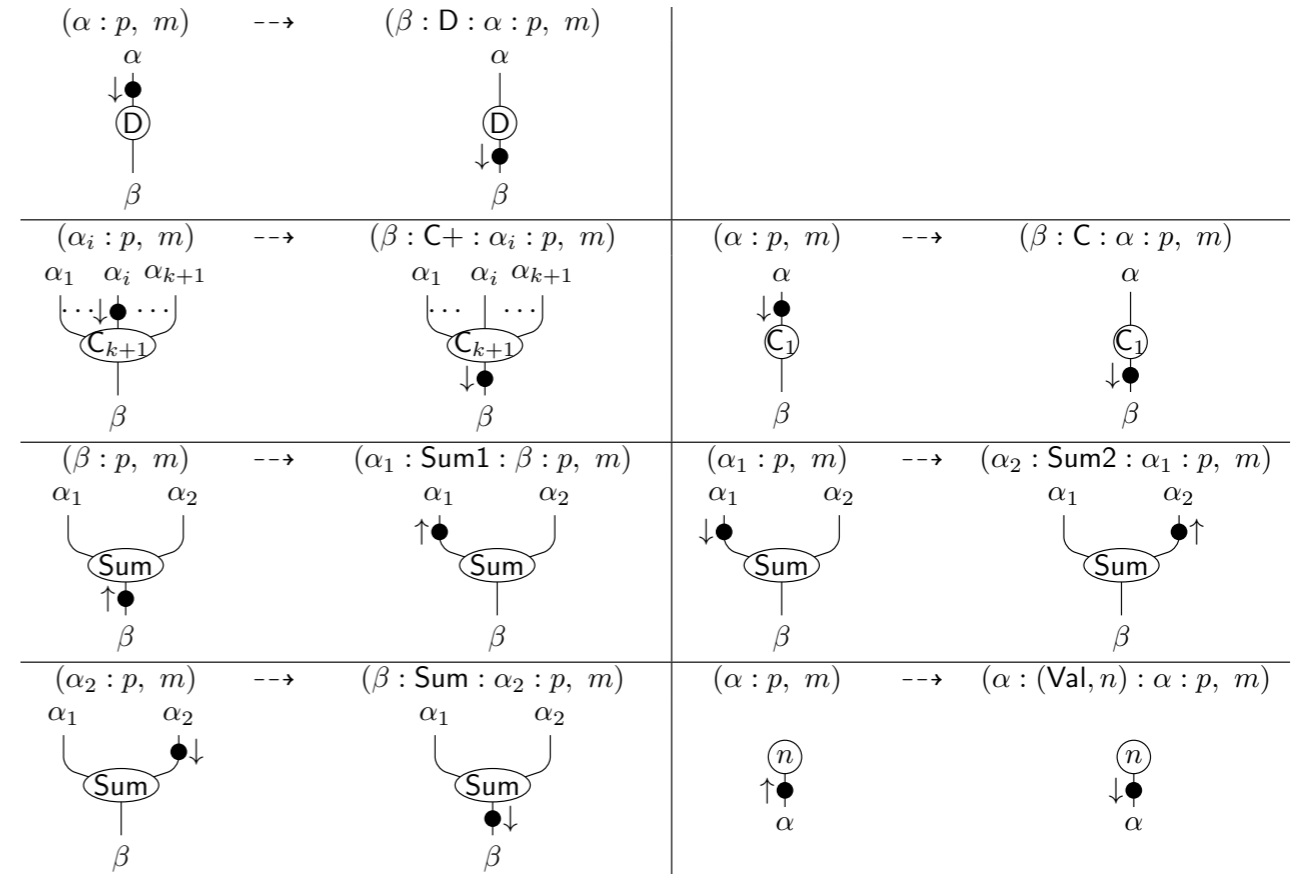
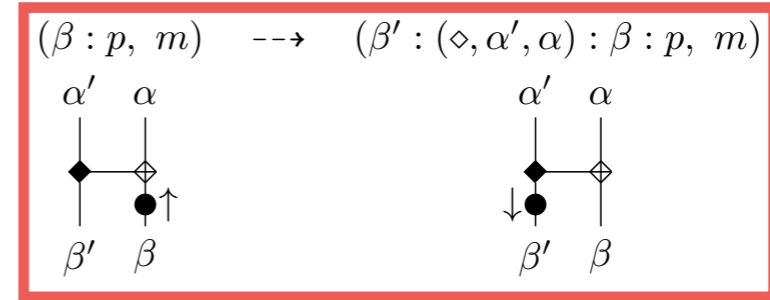
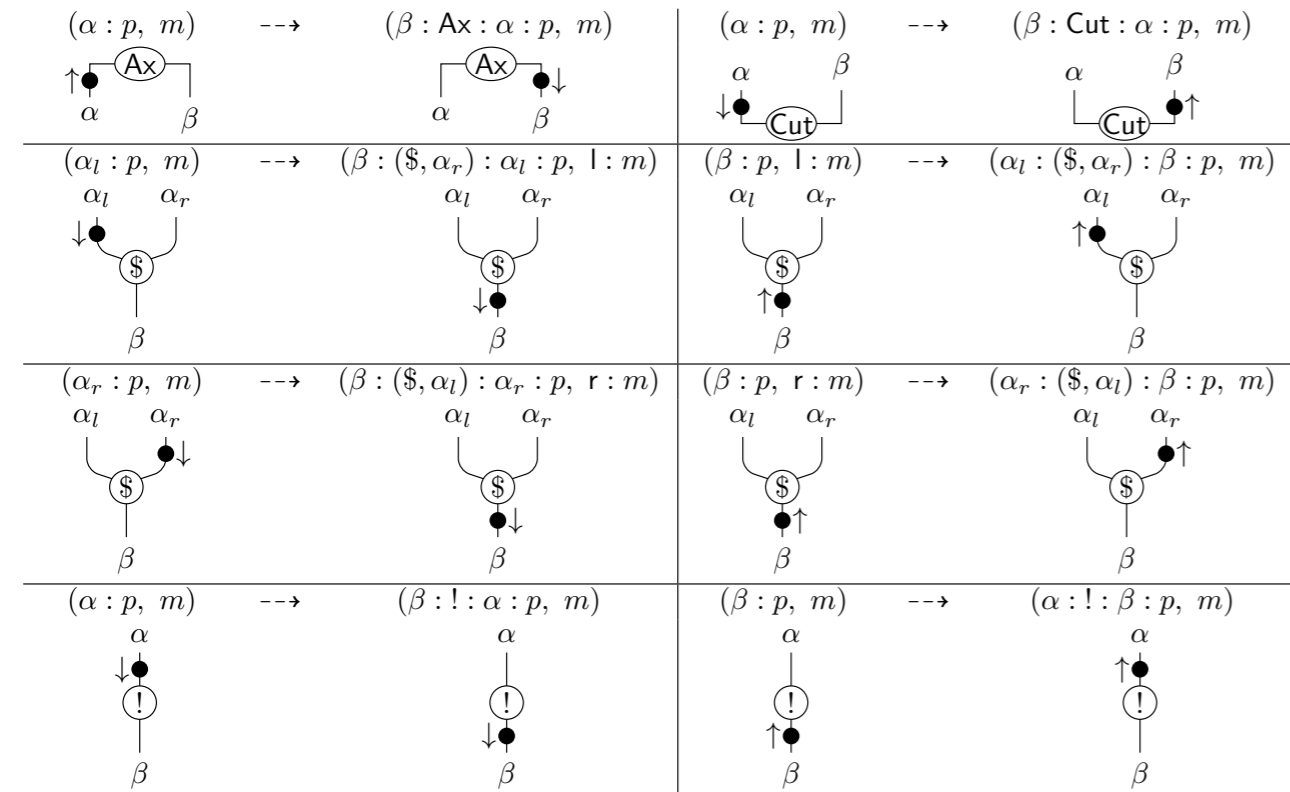
Force evaluation of arguments: checkpoint

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Dynamic Gol machine, extended

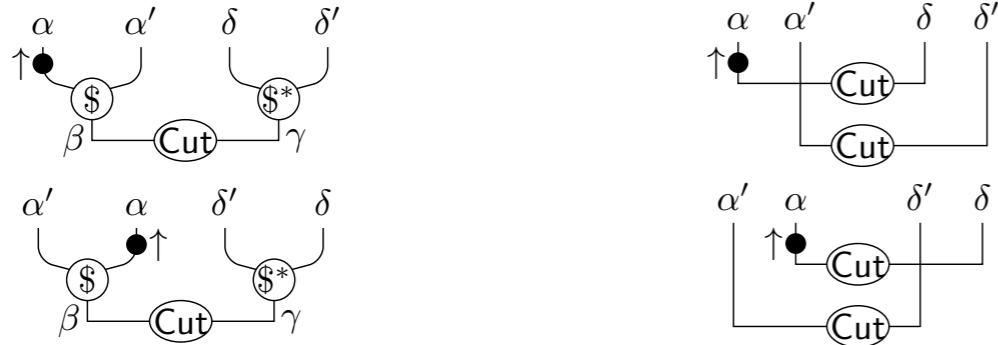
“move” transition $((G, \ell_e, \ell_b), p, d, m) \dashrightarrow ((G, \ell_e, \ell_b), p', d', m')$



Dynamic Gol machine, extended

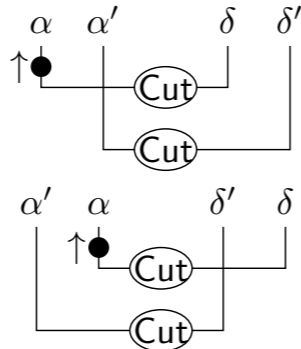
“rewrite” transition $((G, \ell_e, \ell_b), p, d, m) \rightsquigarrow ((G', \ell'_e, \ell'_b), p', d', m)$

$\alpha : (\$, \alpha') : \beta : \text{Cut} : \gamma : (\$, \delta') : \delta : p \rightsquigarrow$



$\alpha : \text{Cut} : \beta : \text{Ax} : \gamma : p$

$\alpha : \text{Cut} : \delta : p$



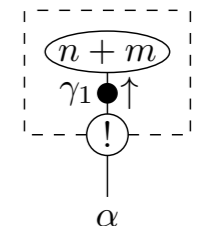
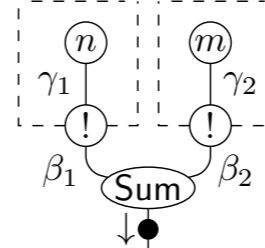
$\gamma : p$

$\alpha : \text{Sum} : \beta_2 : ! : \gamma_2 : (\text{Val}, m)$

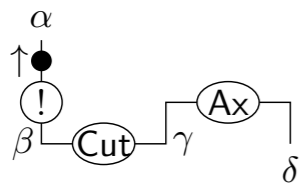
$: \gamma_2 : ! : \beta_2 : \text{Sum2} : \beta_1 : ! : \gamma_1 : (\text{Val}, n) \rightsquigarrow$

$\gamma_1 : ! : \alpha : p$

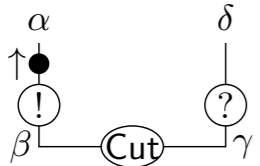
$: \gamma_1 : ! : \beta_1 : \text{Sum1} : \alpha : p$



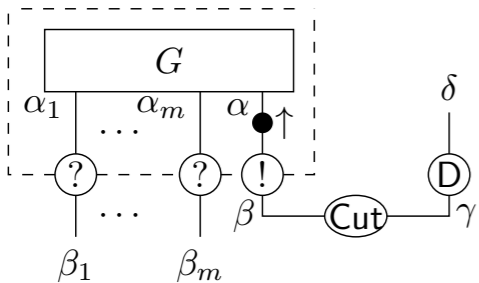
$\alpha : ! : \beta : \text{Cut} : \gamma : \text{Ax} : \delta : p$



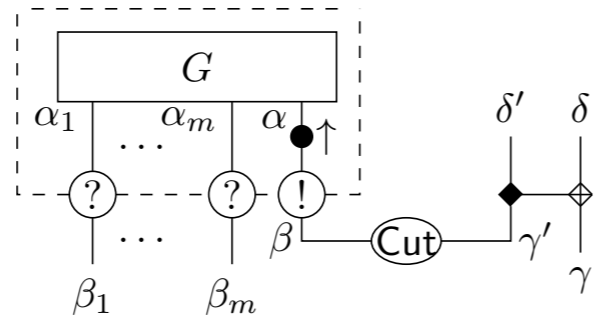
$\alpha : ! : \beta : \text{Cut} : \gamma : ? : \delta : p$



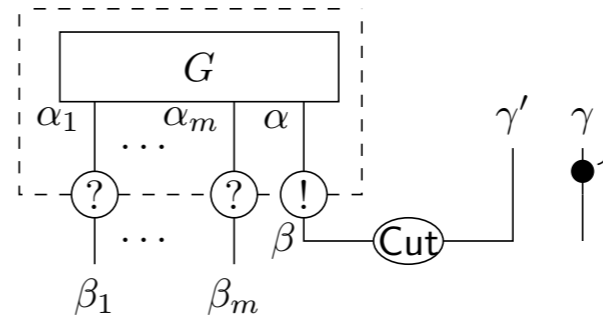
$\alpha : ! : \beta : \text{Cut} : \gamma : \text{D} : \delta : p$



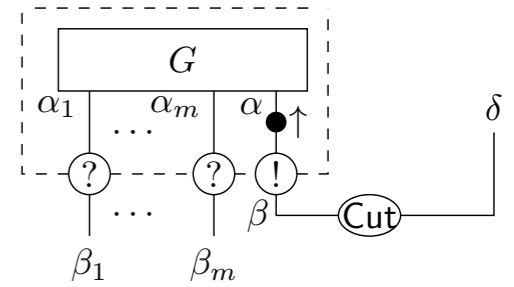
$\alpha : ! : \beta : \text{Cut} : \gamma' : (\diamond, \delta', \delta) : \gamma : p \rightsquigarrow$



$\gamma : p$

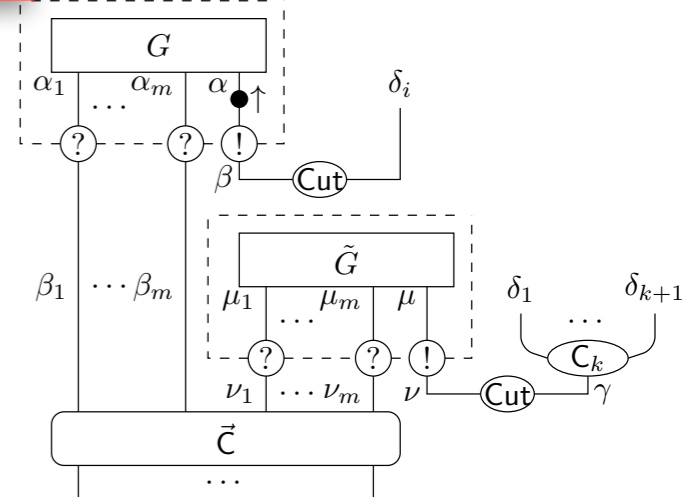
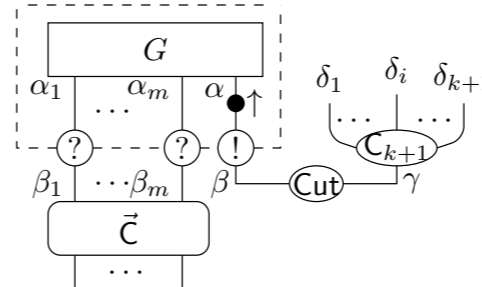
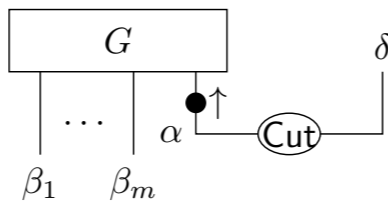


$\rightsquigarrow \alpha : ! : \beta : \text{Cut} : \delta : p$



$\alpha : ! : \beta : \text{Cut} : \delta_i : p$

$\alpha : \text{Cut} : \delta : p$



“Linear-cost” simulation

- Dynamic Gol machine $\rightarrow \xleftrightarrow{\text{def.}} \begin{cases} \rightsquigarrow & \text{if a rewrite is possible} \\ \dashrightarrow & \text{if no rewrite but a move is possible} \end{cases}$
- Call-by-value storeless abstract machine

$$\begin{array}{l}
 \langle V, E \rangle_t \rightarrow_{\text{val}} \langle E, V \rangle_c \\
 \langle M N, E \rangle_t \rightarrow_{\text{val}} \langle M, E[[] N] \rangle_t \\
 \langle M + N, E \rangle_t \rightarrow_{\text{val}} \langle M, E[[] + N] \rangle_t \\
 \langle x, E_1[\text{let } x = V \text{ in } E_2] \rangle_t \rightarrow_{\text{val}} \langle E_1[\text{let } x = V \text{ in } E_2], V \rangle_c \\
 \langle [], A[V] \rangle_c \rightarrow_{\text{val}} \langle A[V] \rangle_a \\
 \langle E[[] N], A[\lambda x. M] \rangle_c \rightarrow_{\text{val}} \langle N, E[A[\text{let } x' := [] \text{ in } M[x'/x]]] \rangle_t \\
 \langle E[[] + N], A[\underline{n}] \rangle_c \rightarrow_{\text{val}} \langle N, E[A[\underline{n} + []]] \rangle_t \\
 \langle E[\underline{n} + []], A[\underline{m}] \rangle_c \rightarrow_{\text{val}} \langle E, A[\underline{n} + \underline{m}] \rangle_c \\
 \langle E[\text{let } x = V' \text{ in } []], A[V] \rangle_c \rightarrow_{\text{val}} \langle E, \text{let } x = V' \text{ in } A[V] \rangle_c \\
 \langle E[\text{let } x := [] \text{ in } M], A[V] \rangle_c \rightarrow_{\text{val}} \langle M, E[A[\text{let } x = V \text{ in } []]] \rangle_t
 \end{array}$$

Theorem A.2. There exists a binary relation \ddagger that satisfies

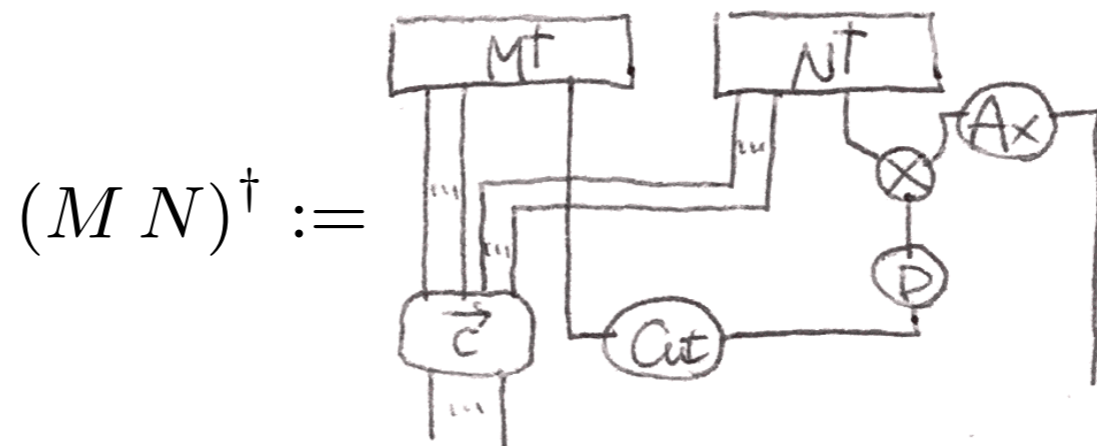
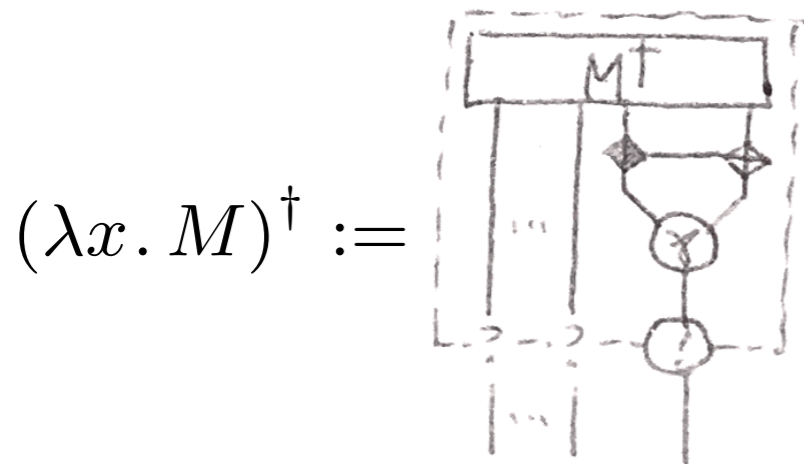
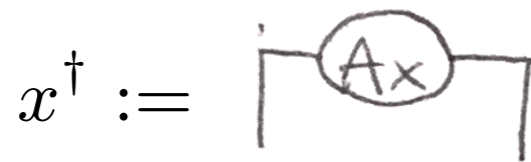
$$\begin{aligned}
 c \xrightarrow{k}_{\text{val}} c' \wedge c \ddagger (G, p, d, m) \\
 \implies (G, p, d, m) \xrightarrow{\mathcal{O}(k)} \dots \rightarrow (G', p', d', m') \wedge c' \ddagger (G', p', d', m') .
 \end{aligned}$$

“Linear-cost” simulation

Theorem A.2. There exists a binary relation \ddagger that satisfies

$$c \xrightarrow{k}_{\text{val}} c' \wedge c \ddagger (G, p, d, m)$$

$$\implies (G, p, d, m) \xrightarrow{\mathcal{O}(k)} \dots \rightarrow (G', p', d', m') \wedge c' \ddagger (G', p', d', m') .$$



Gol machine [Danos & Regnier '99] [Mackie '95]

call-by-name

call-by-need

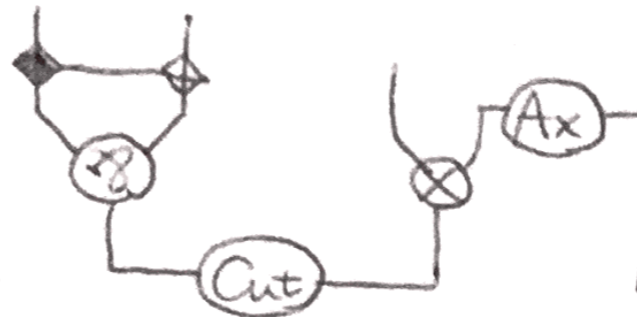
call-by-value

effects

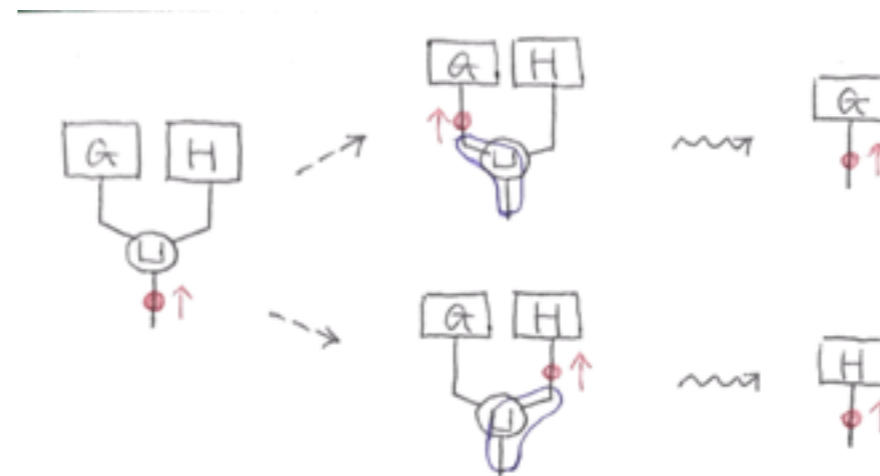
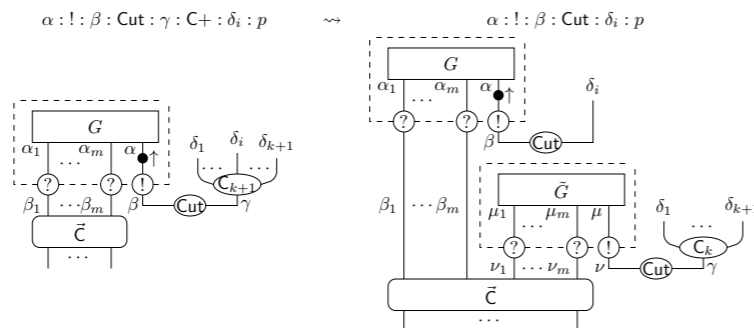
	avoid re-evaluation	force evaluation of arguments	track each copy of terms
CPS transform.	?	✓	? Schöpp
memory	△		✓ Hoshino+
parallelism & sync.	△	✓	Dal Lago+
dynamic jump	✓	✓	Fernández+
dynamic rewrite	✓		☺
checkpoint		✓	

Dynamic rewrite & checkpoint

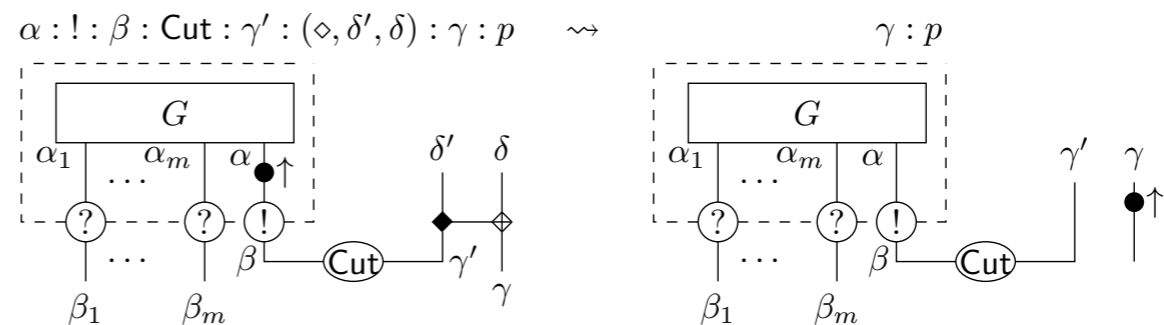
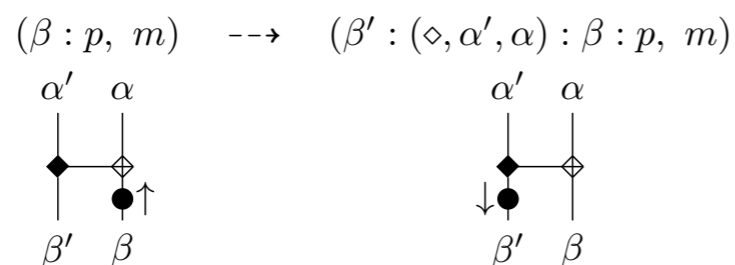
- jumping as rewriting



- honest copying



- potential parallelism



As an abstract machine

- efficiency

- no cost for look-up $\langle x, E_1[\mathbf{let} \ x = N \ \mathbf{in} \ E_2] \rangle_t \rightarrow_{\text{need}} \langle N, E_1[\mathbf{let} \ x := [] \ \mathbf{in} \ E_2[x]] \rangle_t$

- garbage collection integrated, in a restricted way

$$\langle E[\mathbf{let} \ x := [] \ \mathbf{in} \ E'[x]], A[V] \rangle_c \rightarrow_{\text{need}} \langle E[A[\mathbf{let} \ x = V \ \mathbf{in} \ E']], V \rangle_c$$

$$\langle E[\mathbf{let} \ x := [] \ \mathbf{in} \ E'[x]], A[V] \rangle_c \rightarrow_{\text{need}} \langle E[A[E']], V \rangle_c \text{ (if } x \text{ does not appear in } E')$$

- compositional reasoning
- automated “graph rewriter” of specific strategies
 - rather than “graph rewriting simulator”